Deep Learning
Sequence to Sequence models: Connectionist Temporal Classification
Sequence-to-sequence modelling

• Problem:
  – A sequence $X_1 \ldots X_N$ goes in
  – A different sequence $Y_1 \ldots Y_M$ comes out

• E.g.
  – Speech recognition: Speech goes in, a word sequence comes out
    • Alternately output may be phoneme or character sequence
  – Machine translation: Word sequence goes in, word sequence comes out
  – Dialog: User statement goes in, system response comes out
  – Question answering: Question comes in, answer goes out

• In general $N \neq M$
  – No synchrony between $X$ and $Y$. 
Sequence to sequence

- Sequence goes in, sequence comes out
- No notion of “time synchrony” between input and output
  - May even not even maintain order of symbols
    - E.g. “I ate an apple” → “Ich habe einen apfel gegessen”
  - Or even seem related to the input
    - E.g. “My screen is blank” → “Please check if your computer is plugged in.”
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Case 1: Order-aligned but not time synchronous

- The input and output sequences happen in the same order
  - Although they may not be *time synchronous*, they can be “aligned” against one another
  - E.g. Speech recognition
    - The input speech can be aligned to the phoneme sequence output
Problems

• How do we perform *inference* on such a model
  – How to output time-asynchronous sequences

• How do we *train* such models
Problems

• How do we perform *inference* on such a model
  ✔️ Partially addressed
    – How to output time-asynchronous sequences

• How do we *train* such models
The inference problem

- Objective: Given a sequence of inputs, asynchronously output a sequence of symbols
  - “Decoding”

- Find most likely symbol sequence given inputs
  \[
  S_0 \ldots S_{K-1} = \arg \max_{S'_0 \ldots S'_{K-1}} \text{prob}(S'_0 \ldots S'_{K-1}|X_0 \ldots X_{N-1})
  \]
Problems

• How do we perform *inference* on such a model
  – How to output time-asynchronous sequences

• How do we *train* such models
Recap: Training with alignment

• Training data: input sequence + output sequence
  – Output sequence length <= input sequence length

• Given the *alignment* of the output to the input
  – The phoneme /B/ ends at \( X_2 \), /AH/ at \( X_6 \), /T/ at \( X_9 \)
Recap: Characterizing an alignment

Given only the order-synchronous sequence and its time stamps

- $S_0(T_0), S_1(T_1), \ldots, S_{K-1}(T_{K-1})$
- E.g. $S_0 = /B/ (3)$, $S_1 = /B/ (7)$, $S_2 = /T/ (9)$,
Recap: Characterizing an alignment

- Given only the order-synchronous sequence and its time stamps
  - \( S_0(T_0), S_1(T_1), \ldots, S_{K-1}(T_{K-1}) \)
  - E.g. \( S_0 = /B/ (3), \quad S_1 = /B/ (7), \quad S_2 = /T/ (9), \)

- Repeat symbols to convert it to a time-synchronous sequence
  - \( s_0, s_1, \ldots, s_{N-1} = S_0, S_0, \ldots, (T_0 \text{ times}), S_1, S_1, \ldots, (T_1 \text{ times}), \ldots, S_{K-1} \)
  - E.g. \( s_0, s_1, \ldots, s_9 = /B//B//B//B//AH//AH//AH//AH//AH//AH//T//T/ \)
Recap: Characterizing an alignment

• Given only the order-synchronous sequence and its time stamps
  – \( S_0(T_0), S_1(T_1), \ldots, S_{K-1}(T_{K-1}) \)
  – E.g. \( S_0 = /B/ (3), \ S_1 = /B/ (7), \ S_2 = /T/ (9) \),

• Repeat symbols to convert it to a time-synchronous sequence
  – \( s_0 = S_0, s_1 = S_0, \ldots, s_{T_0} = S_0, s_{T_0+1} = S_1, \ldots, s_{T_1} = S_1, s_{T_1+1} = S_2, \ldots, s_{N-1} = S_{K-1} \)
  – E.g. \( s_0, s_1, \ldots, s_9 = /B//B//B//B///AH//AH//AH//AH//AH//AH///T//T/ \)

• For our purpose an alignment of \( S_0 \ldots S_{K-1} \) to an input of length \( N \) has the form
  – \( s_0, s_1, \ldots, s_{N-1} = S_0, S_0, \ldots, S_0, S_1, S_1, \ldots, S_1, S_2, \ldots, S_{K-1} \) (of length \( N \))

• Any sequence of this kind of length \( N \) that contracts (by eliminating repetitions) to \( S_0 \ldots S_{K-1} \) is a candidate alignment of \( S_0 \ldots S_{K-1} \)
Recap: Training with alignment

- Given the order-aligned output sequence with timing
• Given the order aligned output sequence with timing
  – Convert it to a time-synchronous alignment by repeating symbols
• Compute the divergence from the time-aligned sequence

\[ DIV = \sum_t KL(Y_t, symbol_t) = -\sum_t \log Y(t, symbol_t) \]
The gradient w.r.t the $t$-th output vector $Y_t$

$$
\nabla_{Y_t} \text{DIV} = \begin{bmatrix} 0 & 0 & \ldots & \frac{-1}{Y(t, \text{symbol}_t)} & 0 & \ldots & 0 \end{bmatrix}
$$

- Zeros except at the component corresponding to the target aligned to that time
• Only the sequence of output symbols is provided for the training data
  – But no timing information
Solution 1: Guess the alignment

Initialize alignments → Train model with given alignments → Decode to obtain alignments
Poll 1

• @1100, @1102

Viterbi training explicitly estimates the alignment of each training instance and computes the divergence for the estimated alignment (T/F)

• True
• False

Viterbi training requires reestimation of alignments in every iteration (T/F)

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Iterative update: Problem

• Approach heavily dependent on initial alignment

• Prone to poor local optima

• Alternate solution: Do not commit to an alignment during any pass..
Recap: Training *without* alignment

- We know how to train if the alignment is provided
- Problem: Alignment is *not* provided

Solution:

1. Guess the alignment
2. Consider *all possible* alignments
Recap: The “aligned” table

<table>
<thead>
<tr>
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Arrange the constructed table so that from top to bottom it has the exact sequence of symbols required.
The reason for suboptimality

- We commit to the single “best” estimated alignment
  - The most likely alignment

\[
\textsc{DIV} = - \sum_t \log Y \left( t, symbol_t^{\text{bestpath}} \right)
\]

  - This can be way off, particularly in early iterations, or if the model is poorly initialized
The reason for suboptimality

- **We commit** to the single “best” estimated alignment
  - The *most likely* alignment
    
    \[
    DIV = - \sum_t \log Y \left( t, symbol_t^{bestpath} \right)
    \]
  - This can be way off, particularly in early iterations, or if the model is poorly initialized

- **Alternate view**: there is a probability distribution over alignments of the target Symbol sequence (to the input)
  - *Selecting a single alignment is the same as drawing a single sample from it*
  - Selecting the most likely alignment is the same as deterministically always drawing the most probable value from the distribution
Instead of only selecting the most likely alignment, use the statistical expectation over all possible alignments—use the entire distribution of alignments—this will mitigate the issue of suboptimal selection of alignment.

\[
DIV = E \left[ - \sum_t \log Y(t, s_t) \right]
\]
The “training-without-alignment” procedure computes the average divergence over *all possible* alignments of the label sequence to the input (T/F)

- True
- False

The “training-without-alignment” requires explicit estimation of the alignment of the label sequence to the input

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The expectation over all alignments

Using the linearity of expectation

\[ \text{DIV} = \mathbb{E} \left[ - \sum_{t} \log Y(t, s_t) \right] \]

- This reduces to finding the expected divergence at each input

\[ \text{DIV} = - \sum_{t} \mathbb{E} \left[ \log Y(t, s_t) \right] \]

\[ \text{DIV} = - \sum_{t} \sum_{S \in S_1 \ldots S_K} P(s_t = S|S,X) \log Y(t, s_t = S) \]
The expectation over all alignments

The probability of aligning the specific symbol \( s \) at time \( t \), given that unaligned sequence \( S = S_0 \ldots S_{K-1} \) and given the input sequence \( X = X_0 \ldots X_{N-1} \),

We need to be able to compute this

\[
DIV = - \sum_t E[\log Y(t, s_t)]
\]

- This reduces to finding the expected divergence at each input

\[
DIV = - \sum_t \sum_{S \in S_1 \ldots S_K} P(s_t = S|S, X) \log Y(t, s_t = S)
\]
A posteriori probabilities of symbols

\[ P(s_t = S_r | S, X) \propto P(s_t = S_r, S | X) \]

- \( P(s_t = S_r, S | X) \) is the total probability of all valid paths in the graph for target sequence \( S \) that go through the symbol \( S_r \) (the \( r \)th symbol in the sequence \( S_0 \ldots S_{K-1} \)) at time \( t \)

- We will compute this using the “forward-backward” algorithm
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A posteriori probabilities of symbols

- $P(s_t = S_r, S|X)$ can be decomposed as
  
  $P(s_t = S_r, S|X) = P(S_0, ..., S_r, ..., S_{K-1}, s_t = S_r|X)$
  
  $= P(S_0 ... S_r, s_t = S_r, s_{t+1} \in succ(S_r), succ(S_r), ..., S_{K-1}|X)$

- Using Bayes Rule
  
  $= P(S_0 ... S_r, s_t = S_r |X)P(s_{t+1} \in succ(S_r), succ(S_r), ..., S_{K-1} |S_0 ... S_r, s_t = S_rX)$

- The probability of the subgraph in the blue outline, times the conditional probability of the red-encircled subgraph, given the blue subgraph
Conditional independence

- **Dependency graph:** Input sequence $\mathbf{X} = X_0 \, X_1 \, ... \, X_{N-1}$ governs hidden variables $\mathbf{H} = H_0 \, H_1 \, ... \, H_{N-1}$

- Hidden variables govern output predictions $y_0, \, y_1, \, ... \, y_{N-1}$ individually

- $y_0, \, y_1, \, ... \, y_{N-1}$ are conditionally independent given $\mathbf{H}$

- Since $\mathbf{H}$ is deterministically derived from $\mathbf{X}$, $y_0, \, y_1, \, ... \, y_{N-1}$ are also conditionally independent given $\mathbf{X}$

  - This wouldn’t be true if the relation between $\mathbf{X}$ and $\mathbf{H}$ were not deterministic or if $\mathbf{X}$ is unknown, or if the $y$s at any time went back into the net as inputs.
A posteriori symbol probability

\[ P(s_t = S_r, S|X) = P(S_0 \ldots S_r, s_t = S_r |X)P(s_{t+1} \in \text{succ}(S_r), \text{succ}(S_r), \ldots, S_{K-1} |X) \]

- We will call the first term the \textit{forward probability} \( \alpha(t, r) \)
- We will call the second term the \textit{backward} probability \( \beta(t, r) \)
We will call the first term the **forward probability** $\alpha(t, r)$

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$$P(s_t = S_r, S | X) = P(S_0 \ldots S_r, s_t = S_r | X)P(s_{t+1} \in succ(S_r), succ(S_r), \ldots, S_{K-1} | X)$$
Computing $\alpha(t, r)$: Forward algorithm

$$\alpha(t, r) = P(S_0 \ldots S_r, s_t = S_r | X)$$

- The $\alpha(t, r)$ is the total probability of the subgraph shown
  - The total probability of all paths leading to the alignment of $S_r$ to time $t$
Computing $\alpha(t, r)$: Forward algorithm

$\alpha(3, IY) = P(S_0 \ldots S_r, s_t = S_r | X)$

$\alpha(3, IY) = P(\text{subgraph ending at } (2, B))y_3^{IY} + P(\text{subgraph ending at } (2, IY))y_3^{IY}$

$\alpha(t, r) = \sum_{q: s_q \in \text{pred}(S_r)} P(\text{subgraph ending at } (t-1, q))y_t^{S(r)}$

- Where $\text{pred}(S_r)$ is any symbol that is permitted to come before an $S_r$ and may include $S_r$
- $q$ is its row index, and can take values $r$ and $r - 1$ in this example
Computing $\alpha(t, r)$: Forward algorithm

$\alpha(t, r) = P(S_0 \ldots S_r, s_t = S_r | X)$

$\alpha(3, IY) = \alpha(2, B) y_3^{IY} + \alpha(2, IY) y_3^{IY}$

$\alpha(t, r) = \sum_{q: S_q \in \text{pred}(S_r)} \alpha(t-1, q) Y_t^{S(r)}$

- Where $\text{pred}(S_r)$ is any symbol that is permitted to come before an $S_r$ and may include $S_r$
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Forward algorithm

\[ \alpha(t, r) = \sum_{q: S_q \in \text{pred}(S_r)} \alpha(t - 1, q) y_t^{S_r} \]

- The \( \alpha(t, r) \) is the total probability of the subgraph shown
Forward algorithm

\[
\alpha(t, r) = \left( \alpha(t - 1, r) + \alpha(t - 1, r - 1) \right) y_t^{S(r)}
\]
Forward algorithm

\begin{itemize}
  \item Initialization:
    \[ \alpha(0,0) = y_0^{s(0)}, \quad \alpha(0, r) = 0, \quad r > 0 \]
  \item for \( t = 1 \ldots T - 1 \)
    \[ \alpha(t, 0) = \alpha(t - 1, 0)y_t^{s(0)} \]
    for \( l = 1 \ldots K - 1 \)
    \[ \alpha(t, l) = (\alpha(t - 1, l) + \alpha(t - 1, l - 1))y_t^{s(l)} \]
\end{itemize}
Forward algorithm

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for \( t = 1 \ldots T - 1 \)

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- **for** \( t = 1 \ldots T - 1 \)

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Forward algorithm

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  \[ \alpha(0,0) = y_0^{S(0)}, \quad \alpha(0,r) = 0, \ r > 0 \]
- for \( t = 1 \ldots T - 1 \)
  \[ \alpha(t, 0) = \alpha(t - 1, 0)y_t^{S(0)} \]
  for \( l = 1 \ldots K - 1 \)
  - \( \alpha(t, l) = (\alpha(t - 1, l) + \alpha(t - 1, l - 1))y_t^{S(l)} \)
In practice..

- The recursion
  \[
  \alpha(t, l) = (\alpha(t - 1, l) + \alpha(t - 1, l - 1)) y_t^{S(l)}
  \]
  will generally underflow

- Instead we can do it in the log domain
  \[
  \log \alpha(t, l) = \log(e^{\log \alpha(t-1,l)} + e^{\log \alpha(t-1,l-1)}) + \log y_t^{S(l)}
  \]
  - This can be computed entirely without underflow
The algorithm can also be stated as follows which separates the graph probability from the observation probability. This is needed to compute derivatives.

**Initialization:**

\[ \hat{\alpha}(0,0) = 1, \quad \hat{\alpha}(0,r) = 0, \quad r > 0 \]

\[ \alpha(0,r) = \hat{\alpha}(0,r) y_0^{S(r)}, \quad 0 \leq r \leq K - 1 \]

**for** \( t = 1 \ldots T - 1 \)

\[ \hat{\alpha}(t,0) = \alpha(t-1,0) \]

**for** \( l = 1 \ldots K - 1 \)

\[ \hat{\alpha}(t,l) = \alpha(t-1,l) + \alpha(t-1,l-1) \]

\[ \alpha(t,r) = \hat{\alpha}(t,r) y_t^{S(r)}, \quad 0 \leq r \leq K - 1 \]
The final forward probability $\alpha(t, r)$

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$t$ 0 1 2 3 4 5 6 7 8

$\alpha(T - 1, K - 1) = P(S_0\ldots S_{K-1} | X)$

- The probability of the entire symbol sequence is the alpha at the bottom right node
SIMPLE FORWARD ALGORITHM

#N is the number of symbols in the target output
#S(i) is the ith symbol in target output
#y(t,i) is the output of the network for the ith symbol at time t
#T = length of input

First create output table
For i = 1:N
    s(1:T,i) = y(1:T, S(i))

The forward recursion
First, at t = 1
alpha(1,1) = s(1,1)
alpha(1,2:N) = 0
for t = 2:T
    alpha(t,1) = alpha(t-1,1)*s(t,1)
    for i = 2:N
        alpha(t,i) = alpha(t-1,i-1) + alpha(t-1,i)
        alpha(t,i) *= s(t,i)

Can actually be done without explicitly composing the output table

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation
SIMPLE FORWARD ALGORITHM

#N is the number of symbols in the target output
#S(i) is the ith symbol in target output
#y(t,i) is the network output for the ith symbol at time t
#T = length of input

#The forward recursion
# First, at t = 1
alpha(1,1) = y(1,S(1))
alpha(1,2:N) = 0
for t = 2:T
    alpha(t,1) = alpha(t-1,1)*y(t,S(1))
    for i = 2:N
        alpha(t,i) = alpha(t-1,i-1) + alpha(t-1,i)
        alpha(t,i) *= y(t,S(i))

Without explicitly composing the output table

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation
A posteriori symbol probability

We have seen how to compute this

\[ P(s_t = S_r, S|X) = P(S_0 \ldots S_r, s_t = S_r |X)P(s_{t+1} \in \text{succ}(S_r), \text{succ}(S_r), \ldots, S_{K-1} |X) \]

- We will call the first term the **forward probability** \( \alpha(t, r) \)
- We will call the second term the **backward** probability \( \beta(t, r) \)

We have seen how to compute this
We will call the first term the \textit{forward probability} $\alpha(t, r)$

We will call the second term the \textit{backward probability} $\beta(t, r)$

\[ P(s_t = S_r, S|X) = \alpha(t, r) P(s_{t+1} \in succ(S_r), succ(S_r), ..., S_{K-1} |X) \]
We will call the first term the forward probability $\alpha(t, r)$

We will call the second term the backward probability $\beta(t, r)$

$$P(s_t = S_r, S|X) = \alpha(t, r)P(s_{t+1} \in succ(S_r), succ(S_r), ..., S_{K-1} | X)$$
• $\beta(t, r)$ is the probability of the exposed subgraph, not including the orange shaded box
• \( \beta(t, r) \) is the probability of the exposed subgraph, not including the orange shaded box

• For convenience, let us include the box in the graph, and factor it out later

\[
\hat{\beta}(t, r) = \text{probability of graph including node at } (t, r)
\]

\[
\beta(t, r) = \frac{1}{y_t^{Sr}} \hat{\beta}(t, r)
\]

• We will develop an algorithm to compute \( \hat{\beta}(t, r) \) and compute \( \beta(t, r) \) from it by dividing out \( y_t^{Sr} \) later
Using the same logic as in the forward algorithm:

\[ \hat{\beta}(3, IY) = y_3^{IY} P(\text{subgraph starting at } (4, IY)) + y_3^{IY} P(\text{subgraph starting at } (4, F)) \]
Using the same logic as in the forward algorithm:

\[ \hat{\beta}(3, IY) = y_3^{IY} P(\text{subgraph starting at } (4, IY)) + y_3^{IY} P(\text{subgraph starting at } (4, F)) \]

We recognize these terms:

\[ \hat{\beta}(3, IY) = y_3^{IY} \left( \hat{\beta}(3, IY) + \hat{\beta}(4, F) \right) \]
The backward algorithm is the total probability of the subgraph shown including the node at (t,r).

\[ \hat{\beta}(t, r) = y_t^{S_r} \sum_{q \in \text{succ}(r)} \hat{\beta}(t + 1, q) \]

- The \( \hat{\beta}(t, r) \) is the total probability of the subgraph shown including the node at (t,r).

- The \( \hat{\beta}(t, r) \) terms at any time \( t \) are defined recursively in terms of the \( \hat{\beta}(t + 1, q) \) terms at the next time.
Backward algorithm

- Entire backward algorithm:
  - Note: some nodes (bottom row) have more successors than others

- Initialization:
  \[ \hat{\beta}(T-1, K-1) = y^{S(K-1)}_{T-1}, \quad \hat{\beta}(T-1, r) = 0, \quad r < K-1 \]

- for \( t = T-2 \) down to 0
  for \( r = K-1 \) ... 0
  \[ \hat{\beta}(t, r) = y^{S(r)}_{t} \sum_{q \in \text{succ}(r)} \hat{\beta}(t + 1, q) \]
Backward algorithm

- **Initialization:**
  \[ \hat{\beta}(T - 1, K - 1) = y^{S(K-1)}_{T-1}, \quad \hat{\beta}(T - 1, r) = 0, \quad r < K - 1 \]

- for \( t = T - 2 \) down to 0
  for \( r = K - 1 \) down to 0
  \[ \hat{\beta}(t, r) = y_t^{S(r)} \sum_{q \in \text{succ}(r)} \hat{\beta}(t + 1, q) \]
### Backward algorithm

<table>
<thead>
<tr>
<th>$t$</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>/B/</td>
<td>$y_0^B$</td>
<td>$y_1^B$</td>
<td>$y_2^B$</td>
<td>$y_3^B$</td>
<td>$y_4^B$</td>
<td>$y_5^B$</td>
<td>$y_6^B$</td>
<td>$y_7^B$</td>
<td>$y_8^B$</td>
</tr>
<tr>
<td>/IY/</td>
<td>$y_0^{IY}$</td>
<td>$y_1^{IY}$</td>
<td>$y_2^{IY}$</td>
<td>$y_3^{IY}$</td>
<td>$y_4^{IY}$</td>
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<td>$y_7^{IY}$</td>
<td>$y_8^{IY}$</td>
</tr>
<tr>
<td>/F/</td>
<td>$y_0^F$</td>
<td>$y_1^F$</td>
<td>$y_2^F$</td>
<td>$y_3^F$</td>
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<td>/IY/</td>
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<td>$y_6^{IY}$</td>
<td>$y_7^{IY}$</td>
<td>$y_8^{IY}$</td>
</tr>
</tbody>
</table>

- **Initialization:**

\[
\hat{\beta}(T - 1, K - 1) = y_{t+1}^{S(K-1)}, \hat{\beta}(T - 1, r) = 0, \ r < K - 1
\]

- **for** $t = T - 2$ **down to** 0

  for $r = K - 1 \ldots 0$

\[
\hat{\beta}(t, r) = y_t^{s(r)} \sum_{q \in \text{succ}(r)} \hat{\beta}(t + 1, q)
\]
Backward algorithm

- Initialization:
  \[ \hat{\beta}(T - 1, K - 1) = y_{t+1}^{S(K-1)}, \hat{\beta}(T - 1, r) = 0, \ r < K - 1 \]

- for \( t = T - 2 \) down to 0
  - for \( r = K - 1 \ldots 0 \)
  \[ \hat{\beta}(t, r) = y_{t}^{S(r)} \sum_{q \in \text{succ}(r)} \hat{\beta}(t + 1, q) \]
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\]

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\hat{\beta}(t, r) = y_t^{S(r)} \sum_{q \in \text{succ}(r)} \hat{\beta}(t + 1, q)
\]
Backward algorithm

• Initialization:
  \[ \hat{\beta}(T - 1, K - 1) = y_{t+1}^{S(K-1)}, \hat{\beta}(T - 1, r) = 0, \ r < K - 1 \]

• for \( t = T - 2 \) down to 0
  for \( r = K - 1 \ldots 0 \)
  \[ \hat{\beta}(t, r) = y_t^{S(r)} \sum_{q \in \text{succ}(r)} \hat{\beta}(t + 1, q) \]
• This recursion gives us $\hat{\beta}(t, r)$ which includes the node at $(t, r)$

• The actual backward probability is obtained as

$$\beta(t, r) = \frac{1}{y_t} \frac{s_r}{\hat{\beta}(t, r)}$$
Backward algorithm

• Initialization:

\[ \hat{\beta}(T - 1, K - 1) = y_{T-1}^{S(K-1)}, \quad \hat{\beta}(T - 1, r) = 0, \quad r < K - 1 \]

• for \( t = T - 2 \) down to 0
  for \( r = K - 1 \) ... 0

\[ \hat{\beta}(t, r) = y_t^{S(r)} \sum_{q \in \text{succ}(r)} \hat{\beta}(t + 1, q) \]

\[ \beta(t, r) = \frac{1}{y_t^{S(r)}} \hat{\beta}(t, r) \]
A posteriori symbol probability

\[ P(s_t = S_r, S|X) = \alpha(t, r)P(\text{blue graph}) \]

- We will call the first term the **forward probability** \( \alpha(t, r) \)
- We will call the second term the **backward** probability \( \beta(t, r) \)
We will call the first term the **forward probability** \( \alpha(t, r) \)

We will call the second term the **backward probability** \( \beta(t, r) \)

\[
P(s_t = S_r, S|X) = \alpha(t, r) \beta(t, r)
\]
**SIMPLE BACKWARD ALGORITHM**

#N is the number of symbols in the target output
#S(i) is the ith symbol in target output
#y(t,i) is the output of the network for the ith symbol at time t
#T = length of input

#First create output table
For i = 1:N
  s(1:T,i) = y(1:T, S(i))

#The backward recursion to compute betahat
# First, at t = T
beta(t,N) = s(T,N)
betahat(T,1:N-1) = 0
for t = T-1 downto 1
  betahat(t,N) = s(t,N)*betahat(t+1,N)
  for i = N-1 downto 1
    betahat(t,i) = s(t,i)*(betahat(t+1,i) + betahat(t+1,i+1))

#Compute beta from betahat
for t = T downto 1
  for i = N downto 1
    beta(t,i) = betahat(t,i)/s(t,i)

Can actually be done without explicitly composing the output table

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation
BACKWARD ALGORITHM

#N is the number of symbols in the target output
#S(i) is the ith symbol in target output
#y(t,i) is the output of the network for the ith symbol at time t
#T = length of input

#The backward recursion for betahat
# First, at t = T
betahat(T,N) = y(T,S(N))
betahat(T,1:N-1) = 0
for t = T-1 downto 1
    betahat(t,N) = y(t,S(N))*betahat(t+1,N)
    for i = N-1 downto 1
        betahat(t,i) = y(t,S(i))*(betahat(t+1,i) + betahat(t+1,i+1))

#Compute beta from betahat
for t = T downto 1
    for i = N downto 1
        beta(t,i) = betahat(t,i)/y(t,S(i))

Without explicitly composing the output table

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation
The posterior probability

\[ P(s_t = S_r, S|X) = \alpha(t, r)\beta(t, r) \]

- The posterior is given by

\[
P(s_t = S_r|S, X) = \frac{P(s_t = S_r, S|X)}{\sum_{S_r'} P(s_t = S_r', S|X)} = \frac{\alpha(t, r)\beta(t, r)}{\sum_{r'} \alpha(t, r')\beta(t, r')} 
\]
The posterior probability

Let the posterior $P(s_t = S_r | S, X)$ be represented by $\gamma(t, r)$

$$\gamma(t, r) = \frac{\alpha(t, r) \beta(t, r)}{\sum_{r'} \alpha(t, r') \beta(t, r')}$$
Computing Posteriors

#N is the number of symbols in the target output
#S(i) is the ith symbol in target output
#y(t,i) is the output of the network for the ith symbol at time t
#T = length of input

Assuming the forward are completed first:

alpha = forward(y, S)  # forward probabilities computed
beta  = backward(y, S)  # backward probabilities computed

Now compute the posteriors:

for t = 1:T
    sumgamma(t) = 0
    for i = 1:N
        gamma(t,i) = alpha(t,i) * beta(t,i)
        sumgamma(t) += gamma(t,i)
    end
    for i=1:N
        gamma(t,i) = gamma(t,i) / sumgamma(t)
end

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation
The expected divergence

\[
DIV = - \sum_{t} \sum_{s \in S_0 \ldots S_{K-1}} P(s_t = s | s, X) \log Y(t, s_t = s)
\]

\[
DIV = - \sum_{t} \sum_{r} \gamma(t, r) \log y^S_t(r)
\]
Select all that are true

- The forward-backward algorithm is used to compute the a posteriori probability of aligning each symbol in the compressed sequence to each input
- These probabilities are required to compute the expected divergence across all alignments of the compressed symbol sequence to the input
Select all that are true

- The forward-backward algorithm is used to compute the a posteriori probability of aligning each symbol in the compressed sequence to each input
- These probabilities are required to compute the expected divergence across all alignments of the compressed symbol sequence to the input
The expected divergence

\[
DIV = - \sum_t \sum_{s \in S_0 \ldots S_{K-1}} P(s_t = s | \mathbf{s}, \mathbf{x}) \log Y(t, s_t = s)
\]

\[
DIV = - \sum_t \sum_r \gamma(t, r) \log y_t^{S(r)}
\]

- The derivative of the divergence w.r.t the output \( Y_t \) of the net at any time:

\[
\nabla_{Y_t} DIV = \begin{bmatrix}
\frac{dDIV}{dy_t^{S_0}} & \frac{dDIV}{dy_t^{S_1}} & \cdots & \frac{dDIV}{dy_t^{S_{L-1}}}
\end{bmatrix}
\]

- Components will be non-zero only for symbols that occur in the training instance
The expected divergence

\[
DIV = - \sum_t \sum_{s \in S_0 \ldots S_{K-1}} P(s_t = s | S, X) \log Y(t, s_t = s)
\]

\[
DIV = - \sum_t \sum_r \gamma(t, r) \log y_t^{S(r)}
\]

- The derivative of the divergence w.r.t the output \(Y_t\) of the net at any time:

\[
\nabla_{Y_t} DIV = \begin{bmatrix}
\frac{dDIV}{dy_t^{S_0}} \\
\frac{dDIV}{dy_t^{S_1}} \\
\vdots
\end{bmatrix}
\]

- Components will be non-zero only for symbols that occur in the training instance.

Must compute these terms from here
The expected divergence

\[
\frac{d \text{DIV}}{dy_t^l} = - \sum_{r : S(r) = l} \frac{d}{dy_t^l} \gamma(t, r) \log y_t^l
\]

\[
\text{DIV} = - \sum_t \sum_r \gamma(t, r) \log y_t^{S(r)}
\]

- The derivative of the divergence w.r.t the output \(Y_t\) of the net at any time:

\[
\nabla_{Y_t} \text{DIV} = \begin{bmatrix}
\frac{d \text{DIV}}{dy_t^{s_0}} \\
\frac{d \text{DIV}}{dy_t^{s_1}} \\
\vdots
\end{bmatrix}
\]

Must compute these terms from here

- Components will be non-zero only for symbols that occur in the training instance
The expected divergence

\[ \frac{dD}{dy_t} = \sum_{r : S(r) = l} \frac{d}{dy_t} \gamma(t, r) \log y_t \]

- The derivative of the divergence w.r.t the output \( Y_t \) of the net at any time:

\[
\nabla_{Y_t} DIV = \begin{bmatrix}
\frac{dDIV}{dy_t^{s_0}} & \frac{dDIV}{dy_t^{s_1}} & \cdots & \frac{dDIV}{dy_t^{s_{L-1}}}
\end{bmatrix}
\]

- Components will be non-zero only for symbols that occur in the training instance.
The expected divergence

\[
\frac{d\text{DIV}}{dy^l_t} = - \sum_{r : S(r) = t} \frac{d}{dy^l_t} \gamma(t, r) \log y^l_t
\]

- The derivative of the divergence w.r.t the output \(Y_t\) of the net at any time:

\[
\nabla_{Y_t} \text{DIV} = \begin{bmatrix}
\frac{d\text{DIV}}{dy^0_t} & \frac{d\text{DIV}}{dy^1_t} & \cdots & \frac{d\text{DIV}}{dy^{S_{L-1}}_t}
\end{bmatrix}
\]

- Components will be non-zero only for symbols that occur in the training instance
The expected divergence

The derivatives at both these locations must be summed to get \( \frac{d \text{DIV}}{dy^I_y} \)

\[
\frac{d \text{DIV}}{dy^l_t} = - \sum_{r : S(r) = l} \frac{d}{dy^l_t} \gamma(t, r) \log y^l_t
\]

- Components will be non-zero only for symbols that occur in the training instance
The expected divergence

<table>
<thead>
<tr>
<th>/B/</th>
<th>/IY/</th>
<th>/F/</th>
<th>/IY/</th>
</tr>
</thead>
<tbody>
<tr>
<td>( y_0^B )</td>
<td>( y_0^{IY} )</td>
<td>( y_0^F )</td>
<td>( y_0^{IY} )</td>
</tr>
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</tr>
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<td>( y_7^F )</td>
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</tr>
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<td>( y_8^{IY} )</td>
<td>( y_8^F )</td>
<td>( y_8^{IY} )</td>
</tr>
</tbody>
</table>

The derivatives at both these locations must be summed to get \( \frac{dDIV}{dy_t^{IY}} \)

\[
\frac{dDIV}{dy_t^l} = - \sum_{r:S(r)=l} \frac{d}{dy_t^l} \gamma(t, r) \log y_t^l
\]

- The derivative of the divergence w.r.t the output of the net at any time:

\[
\frac{d}{dy_t^l} \gamma(t, r) \log y_t^l \approx \frac{\gamma(t, r)}{y_t^l}
\]

The approximation is exact if we think of this as a maximum-likelihood estimate.
The derivative of the divergence w.r.t any particular output of the network must sum over all instances of that symbol in the target sequence. For example, the derivative w.r.t \( y_1^{\text{IY}} \) will sum over both rows representing /IY/ in the above figure.

The derivatives at both these locations must be summed to get \( \frac{dDIV}{dy_t^{\text{IY}}} \).

\[
DIV = - \sum_t \sum_r \gamma(t, r) \log y_t^{S(r)}
\]

- The derivative of the divergence w.r.t any particular output of the network must sum over all instances of that symbol in the target sequence.

\[
\frac{dDIV}{dy_t^l} = - \frac{1}{y_t^l} \sum_{r : S(r) = l} \gamma(t, r)
\]

- E.g. the derivative w.r.t \( y_t^{\text{IY}} \) will sum over both rows representing /IY/ in the above figure.
COMPUTING DERIVATIVES

#N is the number of symbols in the target output
#S(i) is the ith symbol in target output
#y(t,i) is the output of the network for the ith symbol at time t
#T = length of input

#Assuming the forward are completed first
alpha = forward(y, S)  # forward probabilities computed
beta  = backward(y, S)  # backward probabilities computed

# Compute posteriors from alpha and beta
gamma = computeposteriors(alpha, beta)

#Compute derivatives
for t = 1:T
    dy(t,1:L) = 0  # Initialize all derivatives at time t to 0
    for i = 1:N
        dy(t,S(i)) -= gamma(t,i) / y(t,S(i))

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation
Overall training procedure for Seq2Seq case 1

• Problem: Given input and output sequences without alignment, train models
Overall training procedure for Seq2Seq case 1

• **Step 1**: Setup the network
  – Typically many-layered LSTM

• **Step 2**: Initialize all parameters of the network
Overall Training: Forward pass

• Foreach training instance
  • **Step 3**: Forward pass. Pass the training instance through the network and obtain all symbol probabilities at each time
Overall training: Backward pass

- **Foreach training instance**
  - **Step 3**: Forward pass. Pass the training instance through the network and obtain all symbol probabilities at each time.
  - **Step 4**: Construct the graph representing the specific symbol sequence in the instance. This may require having multiple rows of nodes with the same symbol scores.
Foreach training instance:

– **Step 5:** Perform the forward backward algorithm to compute $\alpha(t, r)$ and $\beta(t, r)$ at each time, for each row of nodes in the graph. Compute $\gamma(t, r)$.

– **Step 6:** Compute derivative of divergence $\nabla_{Y_t} DIV$ for each $Y_t$. 

**Overall training: Backward pass**
Overall training: Backward pass

- Foreach instance
  - **Step 6**: Compute derivative of divergence $\nabla_{Y_t} DIV$ for each $Y_t$

$$
\nabla_{Y_t} DIV = \begin{bmatrix}
\frac{dDIV}{dy_t^0} & \frac{dDIV}{dy_t^1} & \cdots & \frac{dDIV}{dy_t^{L-1}}
\end{bmatrix}
$$

$$
\frac{dDIV}{dy_t^l} = - \sum_{r:S(r)=l} \frac{\gamma(t,r)}{y_t^l}
$$

- **Step 7**: Backpropagate $\frac{dDIV}{dy_t^l}$ and aggregate derivatives over minibatch and update parameters
Story so far: CTC models

• Sequence-to-sequence networks which irregularly output symbols can be “decoded” by Viterbi decoding
  – Which assumes that a symbol is output at each time and *merges* adjacent symbols

• They require alignment of the output to the symbol sequence for training
  – This alignment is generally not given

• Training can be performed by iteratively estimating the alignment by Viterbi-decoding and time-synchronous training

• Alternately, it can be performed by optimizing the expected error over all possible alignments
  – Posterior probabilities for the expectation can be computed using the forward backward algorithm
A key decoding problem

• Consider a problem where the output symbols are characters

• We have a decode: R R R E E E E E D

• Is this the compressed symbol sequence RED or REED?
We’ve seen this before

Cannot distinguish between an extended symbol and repetitions of the symbol

• /G/ /F/ /F/ /IY/ /D/ or /G/ /F/ /IY/ /D/ ?
A key *decoding* problem

- We have a decode: R R R E E E E E D
- Is this the symbol sequence RED or REED?

- Solution: Introduce an explicit extra symbol which serves to separate discrete versions of a symbol
  - A “blank” (represented by “-”)
  - RRR---EE---DDD = RED
  - RR-E--EED = REED
  - RR-R---EE---D-DD = RREDD
  - R-R-R---E-EDD-DDDD-D = RRREEDDD
    - The next symbol at the end of a sequence of blanks is always a new character
    - When a symbol repeats, there must be at least one blank between the repetitions

- The symbol set recognized by the network must now include the extra blank symbol
  - Which too must be trained
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Which of the following are valid expansions of the character string “BILLY”?

- B B I I L L Y
- B – B I L – L Y
- B – I – L L Y
- B – I – L – L Y Y
Which of the following are valid expansions of the character string “BILLY”?

- B B I I L L Y
- B – B I L – L Y
- B – I – L L Y
- B – I – L – L Y Y
The modified forward output

• Note the extra “blank” at the output
The modified forward output

- Note the extra “blank” at the output

/B/ /IY/ /F/ /IY/
The modified forward output

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/B/ /IY/ /F/ /IY/
The modified forward output

• Note the extra “blank” at the output

/B/ /IY/ /F/ /F/ /IY/
Composing the graph for training

• The original method without blanks

• Changing the example to /B/ /IY/ /IY/ /F/ from /B/ /IY/ /F/ /IY/ for illustration
How blanks change the graph

\[ /B/ \rightarrow /IY/ \rightarrow /F/ \rightarrow /IY/ \]

- Regular order: Each symbol must be followed by the next one
- New pattern: Each symbol may optionally be followed by a blank (explicitly shown)
  - Unless the next symbol is the same
    - E.g. /IY/ /IY/
    - In this case an intermediate black is mandatory
    - Blanks may also occur in the first and last positions
Composing the graph for training

- $\gamma_0^b$
- $\gamma_0^B$
- $\gamma_1^b$
- $\gamma_1^B$
- $\gamma_2^b$
- $\gamma_2^B$
- $\gamma_3^b$
- $\gamma_3^B$
- $\gamma_4^b$
- $\gamma_4^B$
- $\gamma_5^b$
- $\gamma_5^B$
- $\gamma_6^b$
- $\gamma_6^B$
- $\gamma_7^b$
- $\gamma_7^B$
- $\gamma_8^b$
- $\gamma_8^B$

With blanks
- Follows the graph we just saw
  - Note: a row of blanks between any two symbols
  - Also blanks at the very beginning and the very end
Composing the graph for training

- Add edges such that all paths from initial node(s) to final node(s) unambiguously represent the target symbol sequence

- If there is an edge on the left graph, there is a corresponding arrow between columns
The first and last column are allowed to also end at initial and final blanks.
Composing the graph for training

- The first and last column are allowed to also end at initial and final blanks
- Skips are permitted across a blank, but only if the symbols on either side are different
  - Because a blank is *mandatory between repetitions of a symbol* but *not required between distinct symbols*
Composing the graph

#N is the number of symbols in the target output
#S(i) is the ith symbol in target output

#Compose an extended symbol sequence Sext from S, that has the blanks
#in the appropriate place
#Also keep track of whether an extended symbol Sext(j) is allowed to connect
#directly to Sext(j-2) (instead of only to Sext(j-1)) or not

function [Sext] = extendedsequencewithblanks(S)
    j = 1
    for i = 1:N
        Sext(j) = 'b'  # blank
        j = j+1
        Sext(j) = S(i)
        j = j+1
    end
    Sext(j) = 'b'

    return Sext

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation
MODIFIED VITERBI ALIGNMENT WITH BLANKS

\[ \text{Sext} = \text{extendedsequencewithblanks}(S) \]

\[ N = \text{length}(\text{Sext}) \quad \# \text{length of extended sequence} \]

# Viterbi starts here

\[ \text{BP}(1,1) = -1 \]
\[ \text{Bscr}(1,1) = y(1, \text{Sext}(1)) \quad \# \text{Blank} \]
\[ \text{Bscr}(1,2) = y(1, \text{Sext}(2)) \]
\[ \text{Bscr}(1,2:N) = -\infty \]

for \( t = 2:T \)

\[ \text{BP}(t,1) = \text{BP}(t-1,1); \]
\[ \text{Bscr}(t,1) = \text{Bscr}(t-1,1) \cdot y(t, \text{Sext}(1)) \]

for \( i = 2:N \)

if (\( i > 2 \) && \( \text{Sext}(i) \neq \text{Sext}(i-2) \))

\[ \text{BP}(t,i) = \text{argmax}_i(\text{Bscr}(t-1,i), \text{Bscr}(t-1,i-1), \text{Bscr}(t-1,i-2)) \]

else

\[ \text{BP}(t,i) = \text{argmax}_i(\text{Bscr}(t-1,i), \text{Bscr}(t-1,i-1)) \]

\[ \text{Bscr}(t,i) = \text{Bscr}(t-1,\text{BP}(t,i)) \cdot y(t, \text{Sext}(i)) \]

# Backtrace

\[ \text{AlignedSymbol}(T) = \text{Bscr}(T,N) > \text{Bscr}(T,N-1) \ ? \ N, N-1; \]

for \( t = T \text{ downto } 1 \)

\[ \text{AlignedSymbol}(t-1) = \text{BP}(t,\text{AlignedSymbol}(t)) \]

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation
Modified Forward Algorithm

- Initialization:

\[- \alpha(0,0) = y_0^b, \alpha(0,1) = y_0^{S(1)}, \alpha(0,r) = 0 \quad r > 1\]

\(S(k)\) refers to the extended sequence with blanks included
Modified Forward Algorithm

- Iteration \( t = 1:N: \)
  
  \[
  \alpha(t, r) = \alpha(t - 1, r) + \alpha(t - 1, r - 1)
  \]

  - If \( S(r) \neq S(r - 2) \)
    
    \[
    \alpha(t, r) += \alpha(t - 1, r - 2)
    \]

  \[
  \alpha(t, r) *= y_t^{S(r)}
  \]

\[
\alpha(t, r) = Y_t^{S(r)} \sum_{q: q \in \text{pred}(S_r)} \alpha(t - 1, q)
\]
FORWARD ALGORITHM (with blanks)

\[ \text{Sext} = \text{extendedsequencewithblanks}(S) \]

\( N = \text{length(Sext)} \)  # Length of extended sequence

# The forward recursion
# First, at \( t = 1 \)
\( \alpha(1,1) = y(1,\text{Sext}(1)) \)  # This is the blank
\( \alpha(1,2) = y(1,\text{Sext}(2)) \)
\( \alpha(1,3:N) = 0 \)
for \( t = 2:T \)
    \( \alpha(t,1) = \alpha(t-1,1) \cdot y(t,\text{Sext}(1)) \)
    for \( i = 2:N \)
        \( \alpha(t,i) = \alpha(t-1,i) + \alpha(t-1,i-1) \)
        if \( (i > 2 \land \text{Sext}(i) \neq \text{Sext}(i-2)) \)
            \( \alpha(t,i) += \alpha(t-1,i-2) \)
        \( \alpha(t,i) *= y(t,\text{Sext}(i)) \)

Without explicitly composing the output table

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation
Modified Backward Algorithm

- Initialization:

\[ \hat{\beta}(T - 1, 2K - 1) = y_{T-1}^b; \hat{\beta}(T - 1, 2K - 2) = y_{T-1}^{S(2K-1)} \]

\[ \hat{\beta}(T - 1, r) = 0 \quad r < 2K - 2 \]

* S(k) refers to the extended sequence with blanks included
• Iteration:
  \[ \hat{\beta}(t, r) = \hat{\beta}(t + 1, r) + \hat{\beta}(t + 1, r + 1) \]
  • If \( S(r) \neq S(r + 2) \)
  \[ \hat{\beta}(t, r) += \hat{\beta}(t + 1, r + 2) \]
  \[ \hat{\beta}(t, r) *= y^S_t(r) \]

  \[ \beta(t, r) = \hat{\beta}(t, r) / y^S_t(r) \]
[Sext] = extendedsequencewithblanks(S)
N = length(Sext)  # Length of extended sequence

# The backward recursion
# First, at t = T
betahat(T,N) = y(T,Sext(N))
betahat(T,N-1) = y(T,Sext(N-1))
betahat(T,1:N-2) = 0
for t = T-1 downto 1
    betahat(t,N) = betahat(t+1,N)*y(t,Sext(N))
    for i = N-1 downto 1
        betahat(t,i) = betahat(t+1,i) + betahat(t+1,i+1)
        if (i<=N-2 && Sext(i) != Sext(i+2))
            betahat(t,i) += betahat(t+1,i+2)
        betahat(t,i) *= y(t,Sext(i))

# Compute beta from betahat
for t = T downto 1
    for i = N downto 1
        beta(t,i) = betahat(t,i)/y(t,Sext(i))

Without explicitly composing the output table

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation
The rest of the computation

• Posteros and derivatives are computed exactly as before

• But using the extended graphs with blanks
COMPUTING POSTERIORS

\[ \text{Sext, skipconnect} = \text{extendedsequencewithblanks}(S) \]
\[ N = \text{length}(\text{Sext}) \]  # Length of extended sequence

#Assuming the forward are completed first
\[ \text{alpha} = \text{forward}(y, \text{Sext}) \]  # forward probabilities computed
\[ \text{beta} = \text{backward}(y, \text{Sext}) \]  # backward probabilities computed

#Now compute the posteriors
for t = 1:T
    sumgamma(t) = 0
    for i = 1:N
        gamma(t,i) = alpha(t,i) * beta(t,i)
        sumgamma(t) += gamma(t,i)
    end
    for i=1:N
        gamma(t,i) = gamma(t,i) / sumgamma(t)
end

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation
[Sext, skipconnect] = extendedsequencewithblanks(S)
N = length(Sext)  # Length of extended sequence

# Assuming the forward are completed first
alpha = forward(y, Sext)  # forward probabilities computed
beta = backward(y, Sext)  # backward probabilities computed

# Compute posteriors from alpha and beta
gamma = computeposteriors(alpha, beta)

# Compute derivatives
for t = 1:T
    dy(t,1:L) = 0  # Initialize all derivatives at time t to 0
    for i = 1:N
        dy(t,Sext(i)) -= gamma(t,i) / y(t,Sext(i))

Using 1..N and 1..T indexing, instead of 0..N-1, 0..T-1, for convenience of notation.
Overall training procedure for Seq2Seq with blanks

/B/   /IY/   /F/   /IY/

• Problem: Given input and output sequences without alignment, train models
Overall training procedure

• **Step 1**: Setup the network
  – Typically many-layered LSTM

• **Step 2**: Initialize all parameters of the network
  – Include a “blank” symbol in vocabulary
Overall Training: Forward pass

• Foreach training instance
  • **Step 3:** Forward pass. Pass the training instance through the network and obtain all symbol probabilities at each time, including blanks.
Overall training: Backward pass

- Foreach training instance
  - **Step 3:** Forward pass. Pass the training instance through the network and obtain all symbol probabilities at each time
  - **Step 4:** Construct the graph representing the specific symbol sequence in the instance. Use appropriate connections if blanks are included
Foreach training instance:

– **Step 5**: Perform the forward-backward algorithm to compute \( \alpha(t, r) \) and \( \beta(t, r) \) at each time, for each row of nodes in the graph using the modified forward-backward equations. Compute a posteriori probabilities \( \gamma(t, r) \) from them.

– **Step 6**: Compute derivative of divergence \( \nabla_{Y_t} DIV \) for each \( Y_t \)
Overall training: Backward pass

• Foreach instance
  
  – **Step 6:** Compute derivative of divergence $\nabla_{Y_t} \text{DIV}$ for each $Y_t$

$$\nabla_{Y_t} \text{DIV} = \begin{bmatrix} \frac{d\text{DIV}}{dy_t^0} & \frac{d\text{DIV}}{dy_t^1} & \cdots & \frac{d\text{DIV}}{dy_t^{L-1}} \end{bmatrix}$$

$$\frac{d\text{DIV}}{dy_t^l} = - \sum_{r : S(r)=l} \gamma(t, r) \frac{y_t^{S(r)}}{y_t}$$

• **Step 7:** Backpropagate $\frac{d\text{DIV}}{dy_t^l}$ and aggregate derivatives over minibatch and update parameters
CTC: Connectionist Temporal Classification

- The overall framework we saw is referred to as CTC

- Applies to models that output order-aligned, but time-asynchronous outputs
Returning to an old problem:

**Decoding**

<table>
<thead>
<tr>
<th>/AH/</th>
<th>$y_0^{AH}$</th>
<th>$y_1^{AH}$</th>
<th>$y_2^{AH}$</th>
<th>$y_3^{AH}$</th>
<th>$y_4^{AH}$</th>
<th>$y_5^{AH}$</th>
<th>$y_6^{AH}$</th>
<th>$y_7^{AH}$</th>
<th>$y_8^{AH}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>/B/</td>
<td>$y_0^{B}$</td>
<td>$y_1^{B}$</td>
<td>$y_2^{B}$</td>
<td>$y_3^{B}$</td>
<td>$y_4^{B}$</td>
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<td>$y_8^{B}$</td>
</tr>
<tr>
<td>/D/</td>
<td>$y_0^{D}$</td>
<td>$y_1^{D}$</td>
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<td>$y_7^{D}$</td>
<td>$y_8^{D}$</td>
</tr>
<tr>
<td>/EH/</td>
<td>$y_0^{EH}$</td>
<td>$y_1^{EH}$</td>
<td>$y_2^{EH}$</td>
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<td>$y_8^{EH}$</td>
</tr>
<tr>
<td>/IY/</td>
<td>$y_0^{IY}$</td>
<td>$y_1^{IY}$</td>
<td>$y_2^{IY}$</td>
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</tr>
</tbody>
</table>

- The greedy decode computes its output by finding the most likely symbol at each time and merging repetitions in the sequence.

- This is in fact a *suboptimal* decode that actually finds the most likely *time-synchronous* output sequence.
  - Which is not necessarily the most likely *order-synchronous* sequence.
Greedy decodes are suboptimal

• Consider the following candidate decodes
  – R R – E E D (RED, 0.7)
  – R R — — E D (RED, 0.68)
  – R R E E E D (RED, 0.69)
  – T T E E E D (TED, 0.71)
  – T T — — E E D (TED, 0.3)
  – T T — — — E D (TED, 0.29)

• A greedy decode picks the most likely output: TED
• A decode that considers the sum of all alignments of the same final output will select RED
• Which is more reasonable?
Greedy decodes are suboptimal

- Consider the following candidate decodes
  - \( R R \rightarrow E E D \) (RED, 0.7)
  - \( R R \rightarrow \rightarrow E D \) (RED, 0.68)
  - \( R R E E E D \) (RED, 0.69)
  - \( T T E E E D \) (TED, 0.71)
  - \( T T \rightarrow E E D \) (TED, 0.3)
  - \( T T \rightarrow \rightarrow E D \) (TED, 0.29)

- A greedy decode picks the most likely output: TED
- A decode that considers the sum of all alignments of the same final output will select RED
- Which is more reasonable?
- And yet, remarkably, greedy decoding can be surprisingly effective, when using decoding with blanks
What a CTC system outputs

- Ref: Graves
- Symbol outputs peak at the ends of the sounds
  - Typical output: - - R - - - E - - - D
  - Model output naturally eliminates alignment ambiguities
- But this is still suboptimal..

Figure 1. Framewise and CTC networks classifying a speech signal. The shaded lines are the output activations, corresponding to the probabilities of observing phonemes at particular times. The CTC network predicts only the sequence of phonemes (typically as a series of spikes, separated by ‘blanks’, or null predictions), while the framewise network attempts to align them with the manual segmentation (vertical lines). The framewise network receives an error for misaligning the segment boundaries, even if it predicts the correct phoneme (e.g. ‘dh’). When one phoneme always occurs beside another (e.g. the closure ‘dcl’ with the stop ‘d’), CTC tends to predict them together in a double spike. The choice of labelling can be read directly from the CTC outputs (follow the spikes), whereas the predictions of the framewise network must be post-processed before use.
Actual objective of decoding

• Want to find most likely order-aligned symbol sequence
  – RED
  – What greedy decode finds: most likely time synchronous symbol sequence
    • – /R/ /R/ – – /EH//EH//D/
    • Which must be compressed

• Find the order-aligned symbol sequence \( S = S_0, \ldots, S_{K-1} \), given an input \( X = X_0, \ldots, X_{T-1} \), that is most likely
  \[
  = \arg\max_S P(S_0, \ldots, S_{K-1} | X)
  \]
Recall: The forward probability $\alpha(t, r)$

The probability of the entire symbol sequence is the alpha at the bottom right node

$$\alpha_{S_0\ldots S_{K-1}}(T - 1, K - 1) = P(S_0\ldots S_{K-1}|X)$$

- The probability of the entire symbol sequence is the alpha at the bottom right node
Actual decoding objective

• Find the most likely (asynchronous) symbol sequence

\[ \hat{S} = \arg\max_S \alpha_S(S_{K-1}, T - 1) \]
Poll 5

• @1107, @1108

The actual objective of decoding is to identify the compressed/unaligned sequence that has the highest probability given the input

• True
• False

This is the same as finding the compressed sequence with the highest forward probability (alpha) for aligning the final symbol in the sequence to the final input

• True
• False
The actual objective of decoding is to identify the compressed/unaligned sequence that has the highest probability given the input

- True
- False

This is the same as finding the compressed sequence with the highest forward probability (alpha) for aligning the final symbol in the sequence to the final input

- True
- False
Actual decoding objective

• Find the most likely (asynchronous) symbol sequence

\[ \hat{S} = \arg \max_S \alpha_S(S_{K-1}, T - 1) \]

• Unfortunately, explicit computation of this will require evaluate of an exponential number of symbol sequences

• Solution: Organize all possible symbol sequences as a (semi)tree
Hypothesis semi-tree

- The semi tree of hypotheses (assuming only 3 symbols in the vocabulary)
- Every symbol connects to every symbol other than itself
  - It also connects to a blank, which connects to every symbol including itself
- The simple structure repeats recursively
- Each node represents a unique (partial) symbol sequence!
The semi tree of hypotheses (assuming only 3 symbols in the vocabulary)

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Highlighted boxes represent possible symbols for first frame
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The decoding graph for the tree

- Graph with more than 2 symbols will be similar but much more cluttered and complicated
The decoding graph for the tree

- The figure to the left is the tree, drawn in a vertical line
- The graph is just the tree unrolled over time
  - For a vocabulary of $V$ symbols, every node connects out to $V$ other nodes at the next time
- Every node in the graph represents a unique symbol sequence
The decoding graph for the tree

- The forward score $\alpha(r, T)$ at the final time represents the full forward score for a unique symbol sequence (including sequences terminating in blanks)
- Select the symbol sequence with the largest alpha at the final time
Recall: Forward Algorithm

- $y_0^b$
- $y_0^B$
- $y_1^b$
- $y_1^B$
- $y_1^{IY}$
- $y_1^F$
- $y_1^F$
- $y_2^b$
- $y_2^B$
- $y_2^{IY}$
- $y_2^F$
- $y_3^b$
- $y_3^B$
- $y_3^{IY}$
- $y_3^F$
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- $y_7^b$
- $y_7^B$
- $y_7^{IY}$
- $y_7^{IY}$
- $y_8^b$
- $y_8^B$
- $y_8^{IY}$
- $y_8^{IY}$

- $t$

$P(S_0, ..., S_{K-1}|X) = \alpha(T - 1,2K) + \alpha(T - 1,2K + 1)$
The decoding graph for the tree

- The forward score $\alpha(r, T)$ at the final time represents the full forward score for a unique symbol sequence (including sequences terminating in blanks).
- Select the symbol sequence with the largest alpha.
  - Sequences may two alphas, one for the sequence itself, one for the sequence followed by a blank.
  - Add the alphas before selecting the most likely.
CTC decoding

- This is the “theoretically correct” CTC decoder
- In practice, the graph gets exponentially large very quickly
- To prevent this pruning strategies are employed to keep the graph (and computation) manageable
  - This may cause suboptimal decodes, however
  - The fact that CTC scores peak at symbol terminations minimizes the damage due to pruning
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• In practice, the graph gets exponentially large very quickly
• To prevent this pruning strategies are employed to keep the graph (and computation) manageable
  – This may cause suboptimal decodes, however
  – The fact that CTC scores peak at symbol terminations minimizes the damage due to pruning
Beamsearch Pseudocode Notes

• Retaining separate lists of paths and pathscores for paths terminating in blanks, and those terminating in valid symbols
  – Since blanks are special
  – Do not explicitly represent blanks in the partial decode strings

• Pseudocode takes liberties (particularly w.r.t null strings)
  – I.e. you must be careful if you convert this to code

• Key
  – PathScore: array of scores for paths ending with symbols
  – BlankPathScore: array of scores for paths ending with blanks
  – SymbolSet: A list of symbols not including the blank
Global PathScore = [], BlankPathScore = []

# First time instant: Initialize paths with each of the symbols, # including blank, using score at time t=1
NewPathsWithTerminalBlank, NewPathsWithTerminalSymbol, NewBlankPathScore, NewPathScore = InitializePaths(SymbolSet, y[:,0])

# Subsequent time steps
for t = 1:T
    # Prune the collection down to the BeamWidth
    PathsWithTerminalBlank, PathsWithTerminalSymbol, BlankPathScore, PathScore = Prune(NewPathsWithTerminalBlank, NewPathsWithTerminalSymbol, NewBlankPathScore, NewPathScore, BeamWidth)

    # First extend paths by a blank
    NewPathsWithTerminalBlank, NewBlankPathScore = ExtendWithBlank(PathsWithTerminalBlank, PathsWithTerminalSymbol, y[:,t])

    # Next extend paths by a symbol
    NewPathsWithTerminalSymbol, NewPathScore = ExtendWithSymbol(PathsWithTerminalBlank, PathsWithTerminalSymbol, SymbolSet, y[:,t])
end

# Merge identical paths differing only by the final blank
MergedPaths, FinalPathScore = MergeIdenticalPaths(NewPathsWithTerminalBlank, NewBlankPathScore, NewPathsWithTerminalSymbol, NewPathScore)

# Pick best path
BestPath = argmax(FinalPathScore)  # Find the path with the best score
BEAM SEARCH

Global PathScore = [], BlankPathScore = []

# First time instant: Initialize paths with each of the symbols, # including blank, using score at time t=1
NewPathsWithTerminalBlank, NewPathsWithTerminalSymbol, NewBlankPathScore, NewPathScore = InitializePaths(SymbolSet, y[:,0])

# Subsequent time steps
for t = 1:T
    # Prune the collection down to the BeamWidth
    PathsWithTerminalBlank, PathsWithTerminalSymbol, PathScore, BlankPathScore = Prune(NewPathsWithTerminalBlank, NewPathsWithTerminalSymbol, NewBlankPathScore, NewPathScore, BeamWidth)
    # First extend paths by a blank
    NewPathsWithTerminalBlank, NewBlankPathScore = ExtendWithBlank(PathsWithTerminalBlank, PathsWithTerminalSymbol, y[:,t])
    # Next extend paths by a symbol
    NewPathsWithTerminalSymbol, NewPathScore = ExtendWithSymbol(PathsWithTerminalBlank, PathsWithTerminalSymbol, SymbolSet, y[:,t])
end
# Merge identical paths differing only by the final blank
MergedPaths, FinalPathScore = MergeIdenticalPaths(NewPathsWithTerminalBlank, NewBlankPathScore, NewPathsWithTerminalSymbol, NewPathScore)
# Pick best path
BestPath = argmax(FinalPathScore)
BEAM SEARCH

Global PathScore = [], BlankPathScore = []

# First time instant: Initialize paths with each of the symbols, # including blank, using score at time t=1
NewPathsWithTerminalBlank, NewPathsWithTerminalSymbol, NewBlankPathScore, NewPathScore = InitializePaths(SymbolSet, y[:,0])

# Subsequent time steps
for t = 1:T
    # Prune the collection down to the BeamWidth
    PathsWithTerminalBlank, PathsWithTerminalSymbol, BlankPathScore, PathScore = Prune(NewPathsWithTerminalBlank, NewPathsWithTerminalSymbol, NewBlankPathScore, NewPathScore, BeamWidth)
    # First extend paths by a blank
    NewPathsWithTerminalBlank, NewBlankPathScore = ExtendWithBlank(PathsWithTerminalBlank, PathsWithTerminalSymbol, y[:,t])
    # Next extend paths by a symbol
    NewPathsWithTerminalSymbol, NewPathScore = ExtendWithSymbol(PathsWithTerminalBlank, PathsWithTerminalSymbol, SymbolSet, y[:,t])
end

# Merge identical paths differing only by the final blank
MergedPaths, FinalPathScore = MergeIdenticalPaths(NewPathsWithTerminalBlank, NewBlankPathScore, NewPathsWithTerminalSymbol, NewPathScore)

# Pick best path
BestPath = argmax(FinalPathScore)
**BEAM SEARCH**

Global PathScore = [], BlankPathScore = []

# First time instant: Initialize paths with each of the symbols,
# including blank, using score at time t=1
NewPathsWithTerminalBlank, NewPathsWithTerminalSymbol, NewBlankPathScore, NewPathScore = InitializePaths(SymbolSet, y[:,0])

# Subsequent time steps
for t = 1:T
  # Prune the collection down to the BeamWidth
  PathsWithTerminalBlank, PathsWithTerminalSymbol, BlankPathScore, PathScore = Prune(NewPathsWithTerminalBlank, NewPathsWithTerminalSymbol, NewBlankPathScore, NewPathScore, BeamWidth)

# First extend paths by a blank
NewPathsWithTerminalBlank, NewBlankPathScore = ExtendWithBlank(PathsWithTerminalBlank, PathsWithTerminalSymbol, y[:,t])

# Next extend paths by a symbol
NewPathsWithTerminalSymbol, NewPathScore = ExtendWithSymbol(PathsWithTerminalBlank, PathsWithTerminalSymbol, SymbolSet, y[:,t])

# Merge identical paths differing only by the final blank
MergedPaths, FinalPathScore = MergeIdenticalPaths(NewPathsWithTerminalBlank, NewBlankPathScore, NewPathsWithTerminalSymbol, NewPathScore)

# Pick best path
BestPath = argmax(FinalPathScore)
BEAM SEARCH

Global PathScore = [], BlankPathScore = []

# First time instant: Initialize paths with each of the symbols, # including blank, using score at time t=1
NewPathsWithTerminalBlank, NewPathsWithTerminalSymbol, NewBlankPathScore, NewPathScore = InitializePaths(SymbolSet, y[:,0])

# Subsequent time steps
for t = 1:T
    # Prune the collection down to the BeamWidth
    PathsWithTerminalBlank, PathsWithTerminalSymbol, BlankPathScore, PathScore = Prune(NewPathsWithTerminalBlank, NewPathsWithTerminalSymbol, NewBlankPathScore, NewPathScore, BeamWidth)
    # First extend paths by a blank
    NewPathsWithTerminalBlank, NewBlankPathScore = ExtendWithBlank(PathsWithTerminalBlank, PathsWithTerminalSymbol, y[:,t])
    # Next extend paths by a symbol
    NewPathsWithTerminalSymbol, NewPathScore = ExtendWithSymbol(PathsWithTerminalBlank, PathsWithTerminalSymbol, SymbolSet, y[:,t])

# Merge identical paths differing only by the final blank
MergedPaths, FinalPathScore = MergeIdenticalPaths(NewPathsWithTerminalBlank, NewBlankPathScore, NewPathsWithTerminalSymbol, NewPathScore)

# Pick best path
BestPath = argmax(FinalPathScore)
function InitializePaths(SymbolSet, y)

InitialBlankPathScore = [], InitialPathScore = []
# First push the blank into a path-ending-with-blank stack. No symbol has been invoked yet
path = null
InitialBlankPathScore[path] = y[blank]  # Score of blank at t=1
InitialPathsWithFinalBlank = {path}

# Push rest of the symbols into a path-ending-with-symbol stack
InitialPathsWithFinalSymbol = {}
for c in SymbolSet  # This is the entire symbol set, without the blank
    path = c
    InitialPathScore[path] = y[c]  # Score of symbol c at t=1
    InitialPathsWithFinalSymbol += path  # Set addition
end

return InitialPathsWithFinalBlank, InitialPathsWithFinalSymbol, InitialBlankPathScore, InitialPathScore
**BEAM SEARCH: Extending with blanks**

Global PathScore, BlankPathScore

```python
function ExtendWithBlank(PathsWithTerminalBlank, PathsWithTerminalSymbol, y)
    UpdatedPathsWithTerminalBlank = {}
    UpdatedBlankPathScore = []
    # First work on paths with terminal blanks
    #(This represents transitions along horizontal trellis edges for blanks)
    for path in PathsWithTerminalBlank:
        # Repeating a blank doesn’t change the symbol sequence
        UpdatedPathsWithTerminalBlank += path  # Set addition
        UpdatedBlankPathScore[path] = BlankPathScore[path] * y[blank]
    end

    # Then extend paths with terminal symbols by blanks
    for path in PathsWithTerminalSymbol:
        # If there is already an equivalent string in UpdatesPathsWithTerminalBlank
        # simply add the score. If not create a new entry
        if path in UpdatedPathsWithTerminalBlank
            UpdatedBlankPathScore[path] += PathScore[path] * y[blank]
        else
            UpdatedPathsWithTerminalBlank += path  # Set addition
            UpdatedBlankPathScore[path] = PathScore[path] * y[blank]
        end
    end

    return UpdatedPathsWithTerminalBlank, UpdatedBlankPathScore
```
BEAM SEARCH: Extending with symbols

Global PathScore, BlankPathScore

function ExtendWithSymbol(PathsWithTerminalBlank, PathsWithTerminalSymbol, SymbolSet, y)
    UpdatedPathsWithTerminalSymbol = {}
    UpdatedPathScore = []

    # First extend the paths terminating in blanks. This will always create a new sequence
    for path in PathsWithTerminalBlank:
        for c in SymbolSet:  # SymbolSet does not include blanks
            newpath = path + c  # Concatenation
            UpdatedPathsWithTerminalSymbol += newpath  # Set addition
            UpdatedPathScore[newpath] = BlankPathScore[path] * y(c)
    end
    end

    # Next work on paths with terminal symbols
    for path in PathsWithTerminalSymbol:
        # Extend the path with every symbol other than blank
        for c in SymbolSet:  # SymbolSet does not include blanks
            newpath = (c == path[end]) ? path : path + c  # Horizontal transitions don’t extend the sequence
            if newpath in UpdatedPathsWithTerminalSymbol:  # Already in list, merge paths
                UpdatedPathScore[newpath] += PathScore[path] * y[c]
            else  # Create new path
                UpdatedPathsWithTerminalSymbol += newpath  # Set addition
                UpdatedPathScore[newpath] = PathScore[path] * y[c]
            end
        end
    end

    return UpdatedPathsWithTerminalSymbol, UpdatedPathScore
BEAM SEARCH: Pruning low-scoring entries

Global PathScore, BlankPathScore

function Prune(PathsWithTerminalBlank, PathsWithTerminalSymbol, BlankPathScore, PathScore, BeamWidth)
    PrunedBlankPathScore = []
    PrunedPathScore = []
    # First gather all the relevant scores
    i = 1
    for p in PathsWithTerminalBlank
        scorelist[i] = BlankPathScore[p]
        i++
    end
    for p in PathsWithTerminalSymbol
        scorelist[i] = PathScore[p]
        i++
    end
    # Sort and find cutoff score that retains exactly BeamWidth paths
    sort(scorelist)  # In decreasing order
    cutoff = BeamWidth < length(scorelist) ? scorelist[BeamWidth] : scorelist[end]

    PrunedPathsWithTerminalBlank = {}
    for p in PathsWithTerminalBlank
        if BlankPathScore[p] >= cutoff
            PrunedPathsWithTerminalBlank += p  # Set addition
            PrunedBlankPathScore[p] = BlankPathScore[p]
        end
    end

    PrunedPathsWithTerminalSymbol = {}
    for p in PathsWithTerminalSymbol
        if PathScore[p] >= cutoff
            PrunedPathsWithTerminalSymbol += p  # Set addition
            PrunedPathScore[p] = PathScore[p]
        end
    end

    return PrunedPathsWithTerminalBlank, PrunedPathsWithTerminalSymbol, PrunedBlankPathScore, PrunedPathScore
BEAM SEARCH: Merging final paths

# Note: not using global variable here

function MergeIdenticalPaths(PathsWithTerminalBlank, BlankPathScore, PathsWithTerminalSymbol, PathScore)

# All paths with terminal symbols will remain
MergedPaths = PathsWithTerminalSymbol
FinalPathScore = PathScore

# Paths with terminal blanks will contribute scores to existing identical paths from # PathsWithTerminalSymbol if present, or be included in the final set, otherwise
for p in PathsWithTerminalBlank
    if p in MergedPaths
        FinalPathScore[p] += BlankPathScore[p]
    else
        MergedPaths += p  # Set addition
        FinalPathScore[p] = BlankPathScore[p]
end

return MergedPaths, FinalPathScore
Story so far: CTC models

• Sequence-to-sequence networks which irregularly produce output symbols can be trained by
  – Iteratively aligning the target output to the input and time-synchronous training
  – Optimizing the expected error over all possible alignments: CTC training

• Distinct repetition of symbols can be disambiguated from repetitions representing the extended output of a single symbol by the introduction of blanks

• Decoding the models can be performed by
  – Best-path decoding, i.e. Viterbi decoding
  – Optimal CTC decoding based on the application of the forward algorithm to a tree-structured representation of all possible output strings
CTC caveats

• The “blank” structure (with concurrent modifications to the forward-backward equations) is only one way to deal with the problem of repeating symbols

• Possible variants:
  – Symbols partitioned into two or more sequential subunits
    • No blanks are required, since subunits must be visited in order
  – Symbol-specific blanks
    • Doubles the “vocabulary”
  – CTC can use bidirectional recurrent nets
    • And frequently does
  – Other variants possible..
Most common CTC applications

• Speech recognition
  – Speech in, phoneme sequence out
  – Speech in, character sequence (spelling out)

• Handwriting recognition
Speech recognition using Recurrent Nets

- Recurrent neural networks (with LSTMs) can be used to perform speech recognition
  - Input: Sequences of audio feature vectors
  - Output: Phonetic label of each vector
Speech recognition using Recurrent Nets

- Alternative: Directly output phoneme, character or word sequence
Next up: Attention models
CNN-LSTM-DNN for speech recognition

Ensembles of RNN/LSTM, DNN, & Conv Nets (CNN):

Fig. 1. CLDNN Architecture
Translating Videos to Natural Language Using Deep Recurrent Neural Networks

Subhashini Venugopalan, Huijun Xu, Jeff Donahue, Marcus Rohrbach, Raymond Mooney, Kate Saenko
“man in black shirt is playing guitar.”

“construction worker in orange safety vest is working on road.”

“two young girls are playing with lego toy.”

“boy is doing backflip on wakeboard.”

“a young boy is holding a baseball bat.”

“a cat is sitting on a couch with a remote control.”

“a woman holding a teddy bear in front of a mirror.”

“a horse is standing in the middle of a road.”
Not explained

• Can be combined with CNNs
  – Lower-layer CNNs to extract features for RNN

• Can be used in tracking
  – Incremental prediction