Neural Networks

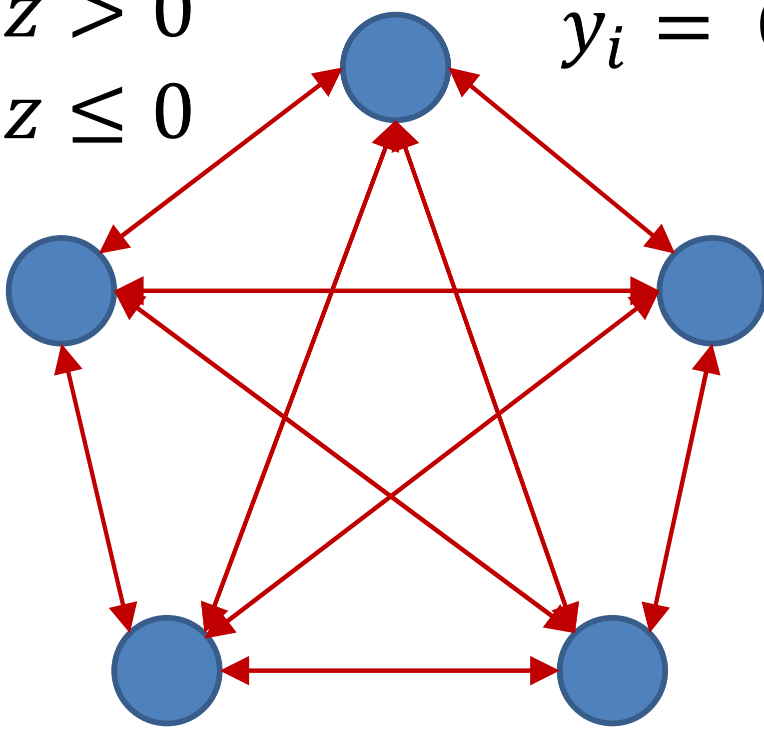
Hopfield Nets and Boltzmann Machines

Fall 2022

Recap: Hopfield network

$$\Theta(z) = \begin{cases} +1 \; if \; z > 0 \\ -1 \; if \; z \leq 0 \end{cases}$$

$$y_i = \Theta\left(\sum_{j \neq i} w_{ji} y_j + b_i\right)$$



- ***Symmetric loopy network***
- Each neuron is a perceptron with +1/-1 output

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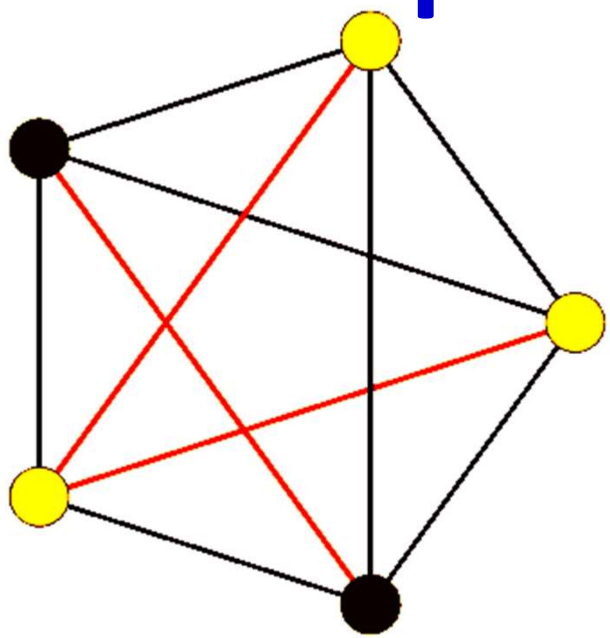

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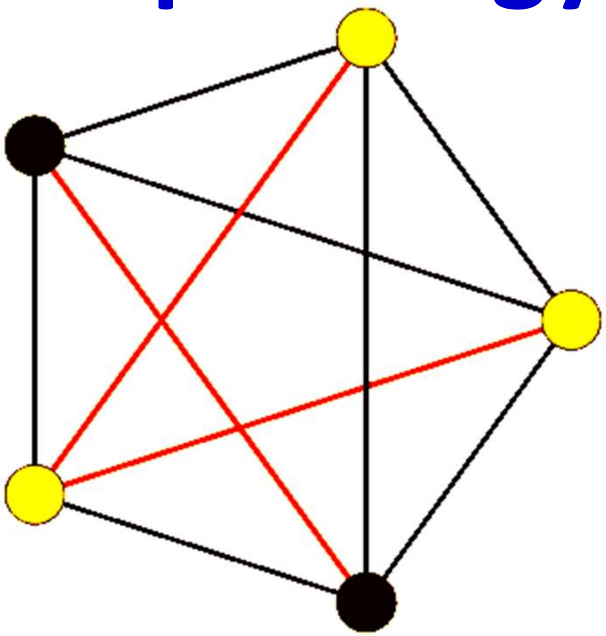
- At each time each neuron receives a "field" $\sum_{j \neq i} w_{ji} y_j + b_i$
- If the sign of the field matches its own sign, it does not respond
- If the sign of the field opposes its own sign, it "flips" to match the sign of the field

Recap: Energy of a Hopfield Network



$$y_i = \Theta\left(\sum_{j \neq i} w_{ji} y_j\right)$$

$$\Theta(z) = \begin{cases} +1 \; if \; z > 0 \\ -1 \; if \; z \leq 0 \end{cases}$$

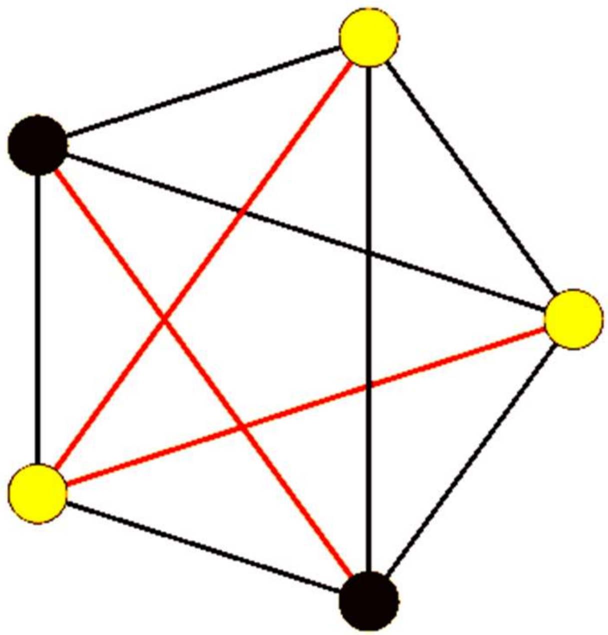
Not assuming node bias

$$E = -\sum_{i,j<i} w_{ij} y_i y_j$$

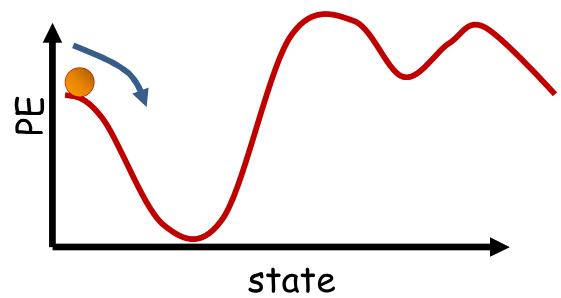
- The system will evolve until the energy hits a local minimum
- In vector form, including a bias term (not typically used in Hopfield nets)

$$E = -\frac{1}{2}\mathbf{y}^T \mathbf{W} \mathbf{y} - \mathbf{b}^T \mathbf{y}$$

Recap: Evolution

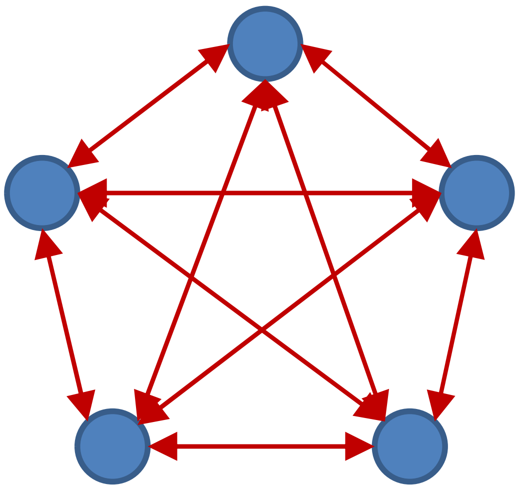


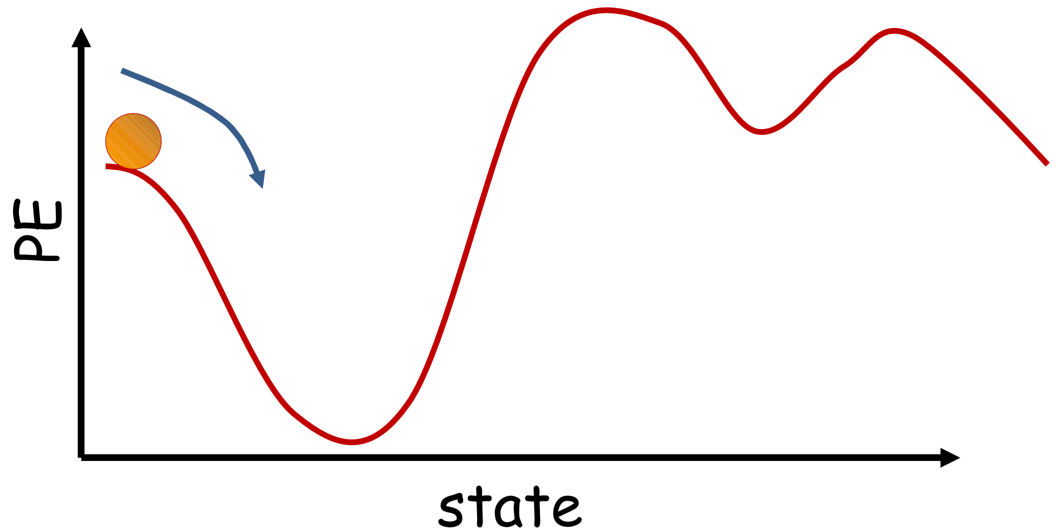
$$E = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y}$$



- The network will evolve until it arrives at a local minimum in the energy contour

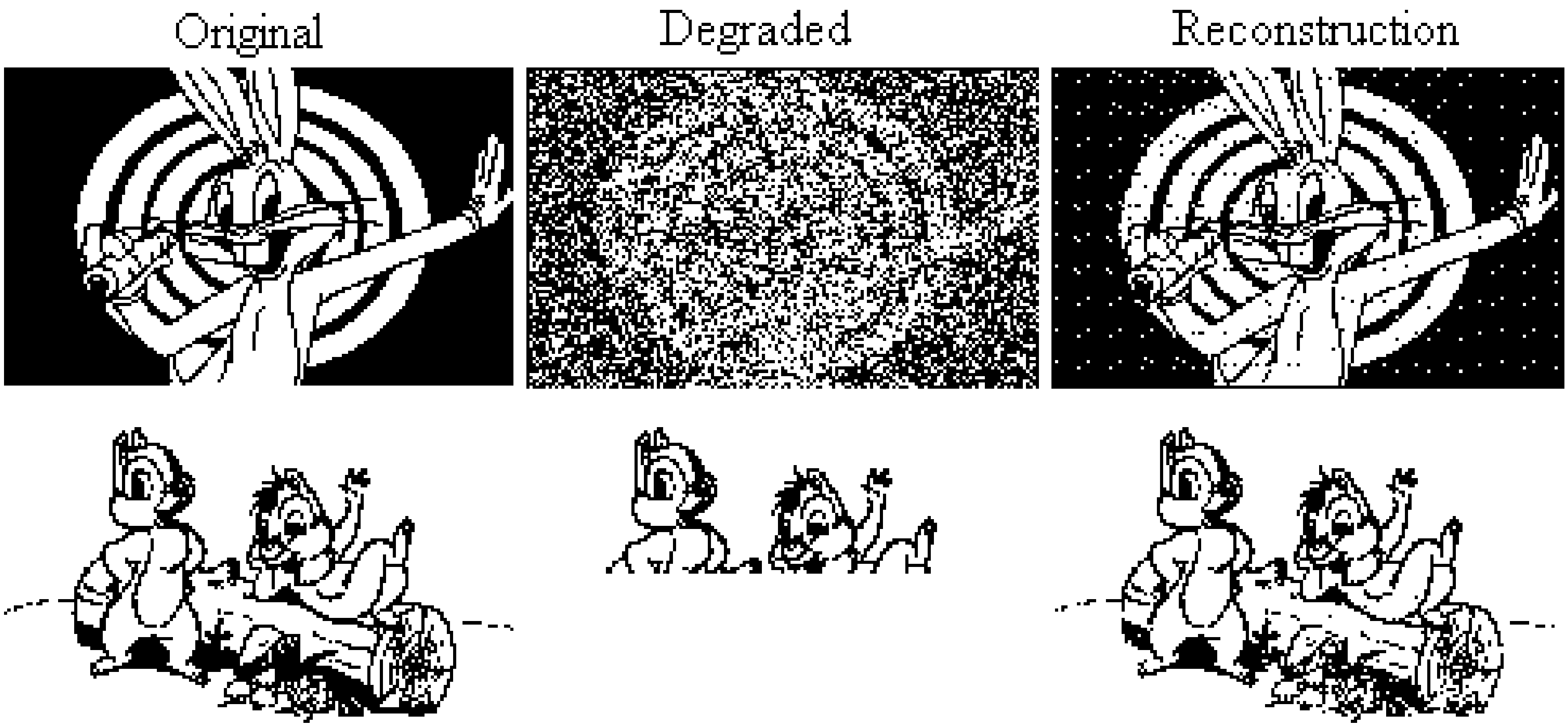
Recap: Content-addressable memory





- Each of the minima is a "stored" pattern
  - If the network is initialized close to a stored pattern, it will inevitably evolve to the pattern
- **This is a *content addressable memory***
  - Recall memory content from partial or corrupt values
- Also called ***associative memory***

Examples: Content addressable memory



Hopfield network reconstructing degraded images from noisy (top) or partial (bottom) cues.

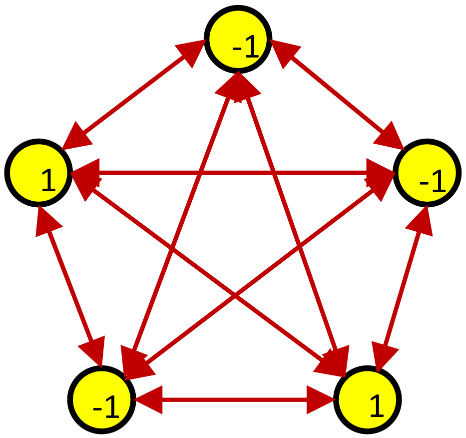
- http://staff.itee.uq.edu.au/janetw/cmc/chapters/Hopfield/

“Training” the network

- How do we make the network store *a specific* pattern or set of patterns?
  - Hebbian learning
  - Geometric approach
  - Optimization

- Secondary question
  - How many patterns can we store?

Recap: Hebbian Learning to Store a Specific Pattern



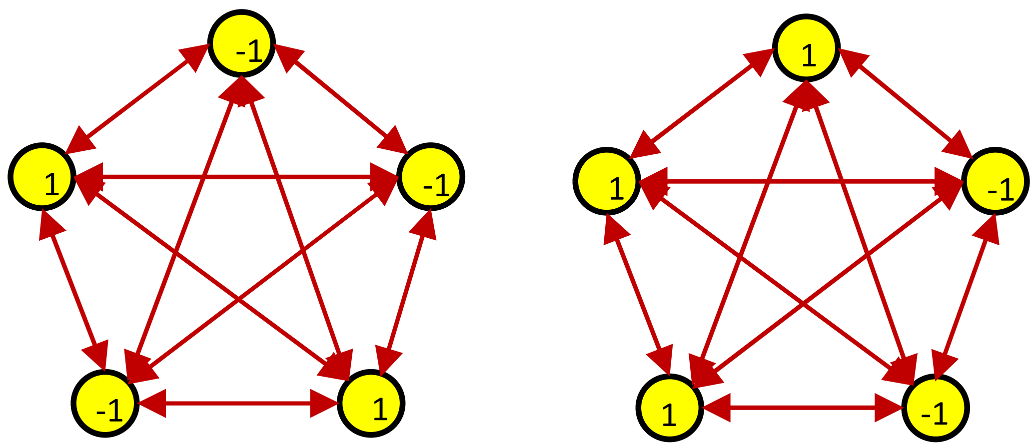
HEBBIAN LEARNING:

$$w_{ji} = y_j y_i$$

$$\mathbf{W} = \mathbf{y}_p \mathbf{y}_p^T - \mathrm{I}$$

- For a single stored pattern, Hebbian learning results in a network for which the target pattern is a global minimum

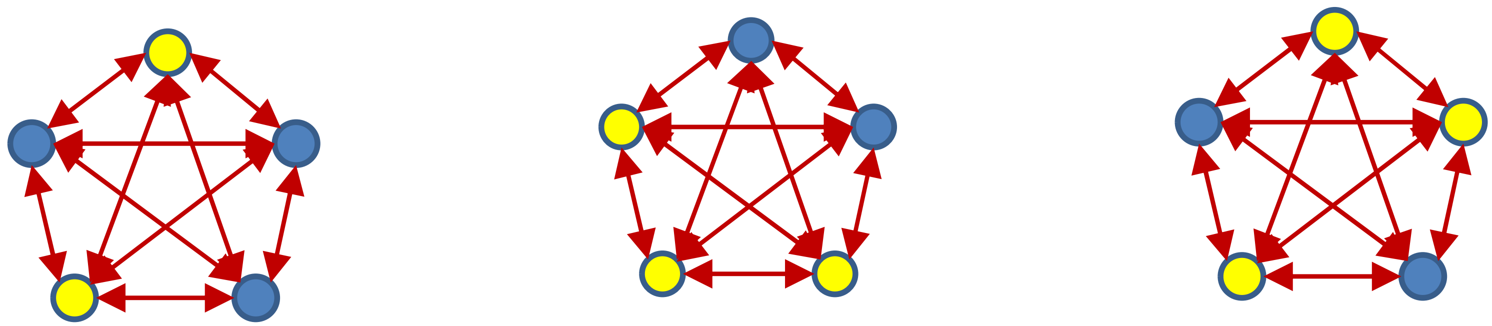
Storing multiple patterns



$$w_{ji} \propto \sum_{p \in \{y_p\}} y_i^p y_j^p$$

- $\{y_p\}$ is the set of patterns to store
- Superscript p represents the specific pattern

How many patterns can we store?



- Hopfield: For a network of N neurons can store up to $0.14N$ random patterns
- In reality, seems possible to store K > 0.14N patterns
  - i.e. obtain a weight matrix W such that K > 0.14N patterns are stationary
  - But behavior with more than even 1 pattern is unpredictable

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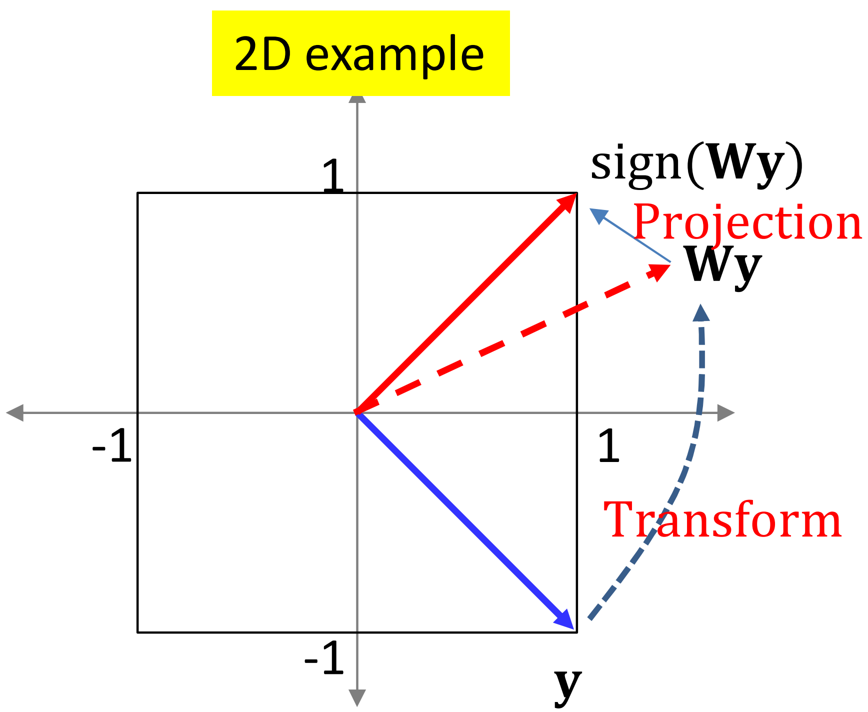
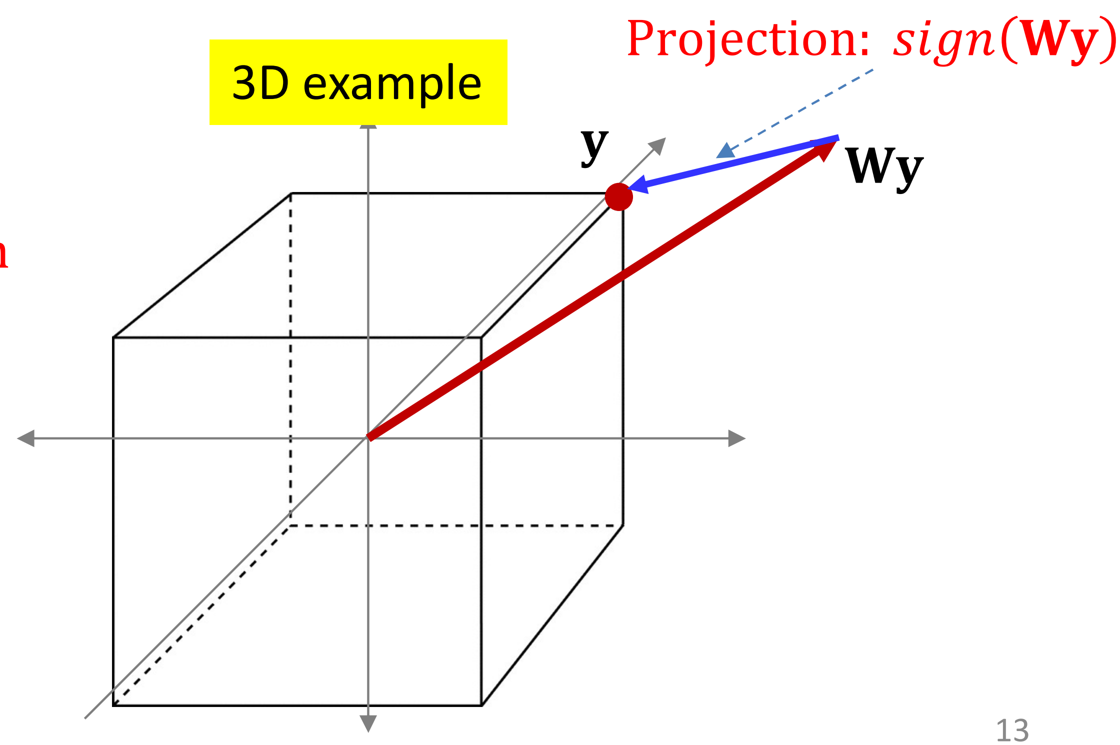
Evolution of the network

- Note: for real vectors $sign(\mathbf{y})$ is a projection
  - Projects $\mathbf{y}$ onto the nearest corner of the hypercube
  - It "quantizes" the space into orthants

- Response to field: $\mathbf{y} \leftarrow sign(\mathbf{W}\mathbf{y})$
  - Each step rotates the vector $\mathbf{y}$ and then projects it onto the nearest corner





Storing patterns

- A pattern $\mathbf{y}_P$ is stored if:
  - $sign(\mathbf{W}\mathbf{y}_p) = \mathbf{y}_p$ for all target patterns
- Training: Design $\mathbf{W}$ such that this holds
- Simple solution: $\mathbf{y}_p$ is an Eigenvector of $\mathbf{W}$
  - And the corresponding Eigenvalue is positive

$$\mathbf{W}\mathbf{y}_p = \lambda \mathbf{y}_p$$

  - More generally orthant($\mathbf{W}\mathbf{y}_p$) = orthant($\mathbf{y}_p$)
- How many such $\mathbf{y}_p$ can we have?

Storing more than one pattern

- Requirement: Given $\mathbf{y}_1, \mathbf{y}_2, \ldots, \mathbf{y}_P$
  - Design $\mathbf{W}$ such that
    - $sign(\mathbf{W}\mathbf{y}_p) = \mathbf{y}_p$ for all target patterns
    - There are no other *binary* vectors for which this holds

- What is the largest number of patterns that can be stored?

Storing K orthogonal patterns

- Simple solution: Design $\mathbf{W}$ such that $\mathbf{y}_1$, $\mathbf{y}_2, \ldots, \mathbf{y}_K$ are the Eigen vectors of $\mathbf{W}$
  - Let $\mathbf{Y} = [\mathbf{y}_1\ \mathbf{y}_2 \ldots \mathbf{y}_K]$

$$\mathbf{W} = \mathbf{Y}\Lambda\mathbf{Y}^T$$

  - $\lambda_1, \ldots, \lambda_K$ are positive
  - For $\lambda_1 = \lambda_2 = \lambda_K = 1$ this is exactly the Hebbian rule
- The patterns are provably stationary

Storing N orthogonal patterns

- The N orthogonal patterns $\mathbf{y}_1, \mathbf{y}_2, \ldots, \mathbf{y}_N$ *span the space*
- Any pattern $\mathbf{y}$ can be written as

$$\mathbf{y} = a_1\mathbf{y}_1 + a_2\mathbf{y}_2 + \cdots + a_N\mathbf{y}_N$$

$$\mathbf{W}\mathbf{y} = a_1\mathbf{W}\mathbf{y}_1 + a_2\mathbf{W}\mathbf{y}_2 + \cdots + a_N\mathbf{W}\mathbf{y}_N$$

$$= a_1\mathbf{y}_1 + a_2\mathbf{y}_2 + \cdots + a_N\mathbf{y}_N = \mathbf{y}$$

- *All patterns are stationary*
  - Remembers everything
  - ***Completely useless network***

Hebbian rule and general (non-orthogonal) vectors

$$w_{ji} = \sum_{p \in \{p\}} y_i^p y_j^p$$

- What happens when the patterns are *not* orthogonal
- What happens when the patterns are presented *more* than once
  - Different patterns presented different numbers of times
  - Equivalent to having unequal Eigen values..
- Can we predict the evolution of any vector $\mathbf{y}$
  - Hint: For real valued vectors, use Lanczos iterations
    - Can write $\mathbf{Y}_P = \mathbf{U}_P \Lambda \mathbf{V}_p^T, \rightarrow \mathbf{W} = \mathbf{U}_P \Lambda^2 \mathbf{U}_p^T$
  - Tougher for binary vectors (NP)

The bottom line

- With a network of N units (i.e. N-bit patterns)
- The maximum number of stationary patterns is actually *exponential* in N
  - McElice and Posner, 84'
  - E.g. when we had the Hebbian net with N orthogonal base patterns, *all* patterns are stationary

- For a *specific* set of K patterns, we can *always* build a network for which all K patterns are stable provided $K \leq N$
  - Mostafa and St. Jacques 85'
    - For large N, the upper bound on K is actually N/4logN
      - McElice et. Al. 87'
  - **But this may come with many "parasitic" memories**

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How do we find this network?

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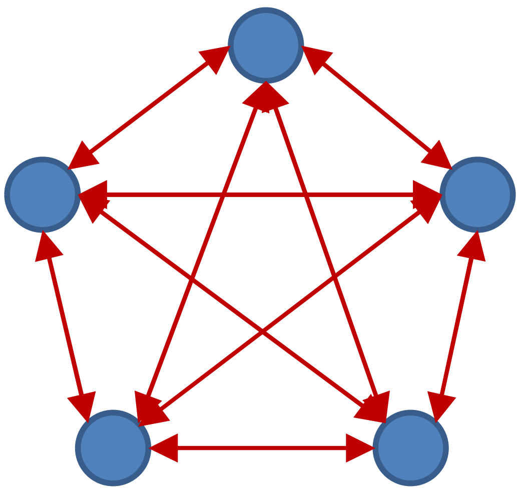
Can we do something about this?

A different tack

- How do we make the network store *a specific* pattern or set of patterns?
  - Hebbian learning
  - Geometric approach
  - Optimization

- Secondary question
  - How many patterns can we store?

Consider the energy function

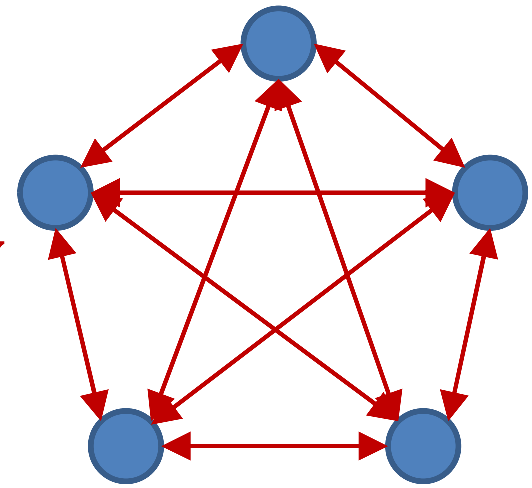


$$E = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y} - \mathbf{b}^T\mathbf{y}$$

- This must be *maximally* low for target patterns
- Must be *maximally* high for *all other patterns*
  - So that they are unstable and evolve into one of the target patterns

Alternate Approach to Estimating the Network

$$E(\mathbf{y}) = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y} - \mathbf{b}^T\mathbf{y}$$



- Estimate $\mathbf{W}$ (and $\mathbf{b}$) such that
  - E is minimized for $\mathbf{y}_1, \mathbf{y}_2, \ldots, \mathbf{y}_P$
  - E is maximized for all other $\mathbf{y}$
- Caveat: Unrealistic to expect to store more than N patterns, but can we make those N patterns *memorable*

Optimizing W (and b)

$$E(\mathbf{y}) = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y} \qquad \widehat{\mathbf{W}} = \underset{\mathbf{W}}{\operatorname{argmin}} \sum_{\mathbf{y}\in\mathbf{Y}_P} E(\mathbf{y})$$

The bias can be captured by
another fixed-value component

- Minimize total energy of target patterns
  - Problem with this?

Optimizing W

$$E(\mathbf{y}) = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y}$$

$$\widehat{\mathbf{W}} = \underset{\mathbf{W}}{\operatorname{argmin}} \sum_{\mathbf{y}\in\mathbf{Y}_P} E(\mathbf{y}) - \sum_{\mathbf{y}\notin\mathbf{Y}_P} E(\mathbf{y})$$

- Minimize total energy of target patterns
- Maximize the total energy of all *non-target* patterns

Optimizing W

$$E(\mathbf{y}) = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y} \qquad \widehat{\mathbf{W}} = \underset{\mathbf{W}}{\operatorname{argmin}} \sum_{\mathbf{y}\in\mathbf{Y}_P} E(\mathbf{y}) - \sum_{\mathbf{y}\notin\mathbf{Y}_P} E(\mathbf{y})$$

- Simple gradient descent:

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T\right)$$

Optimizing W

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T\right)$$

- Can "emphasize" the importance of a pattern by repeating
  - More repetitions → greater emphasis

Optimizing W

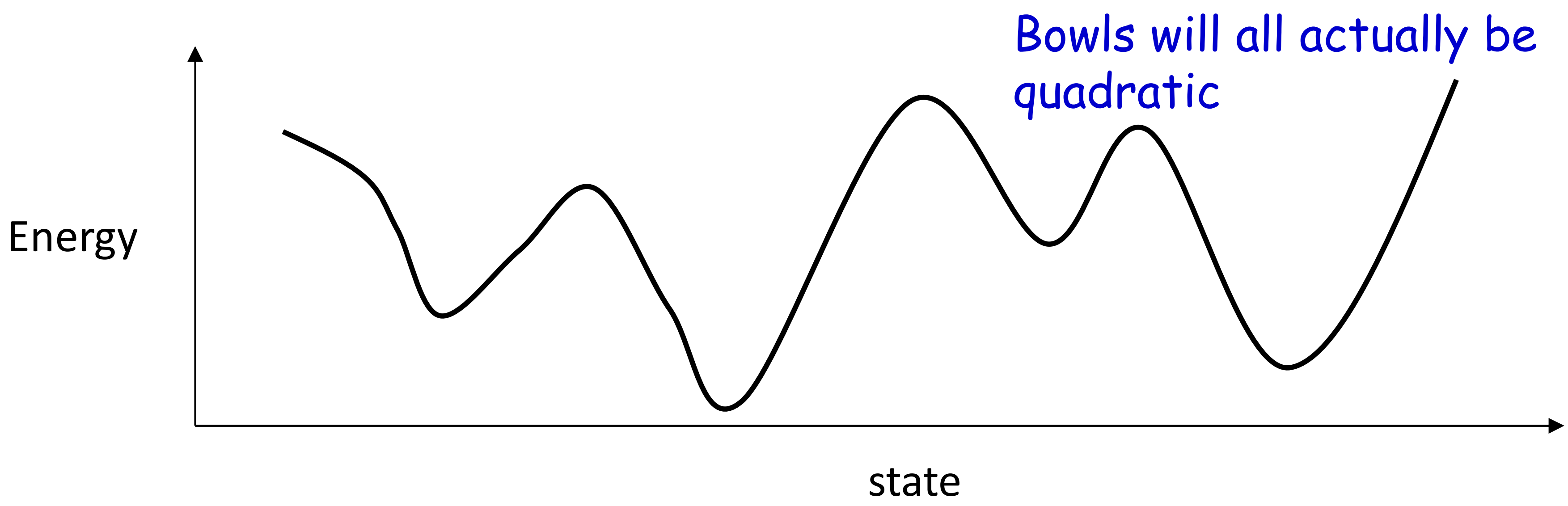
$$\mathbf{W} = \mathbf{W} + \eta \left(\sum_{\mathbf{y} \in \mathbf{Y}_P} \mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y} \notin \mathbf{Y}_P} \mathbf{y}\mathbf{y}^T \right)$$

- Can "emphasize" the importance of a pattern by repeating
  - More repetitions → greater emphasis
- How many of these?
  - Do we need to include *all* of them?
  - Are all equally important?

The training again..

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T\right)$$

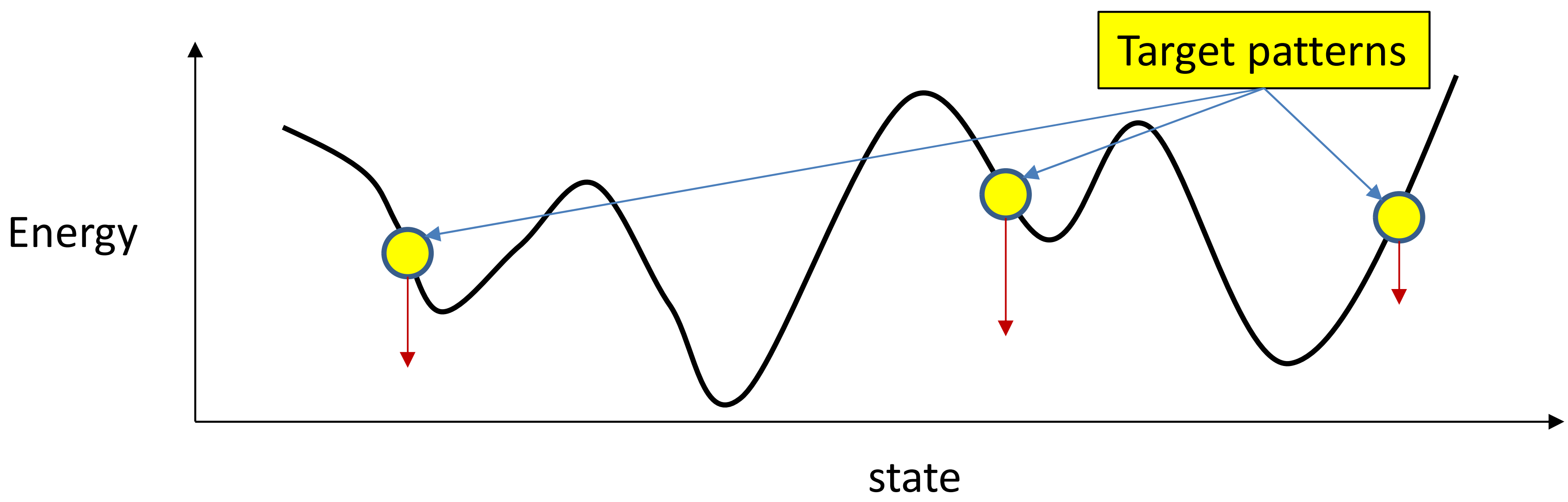
- Note the energy contour of a Hopfield network for any weight $\mathbf{W}$



The training again

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P}\mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P}\mathbf{y}\mathbf{y}^T\right)$$

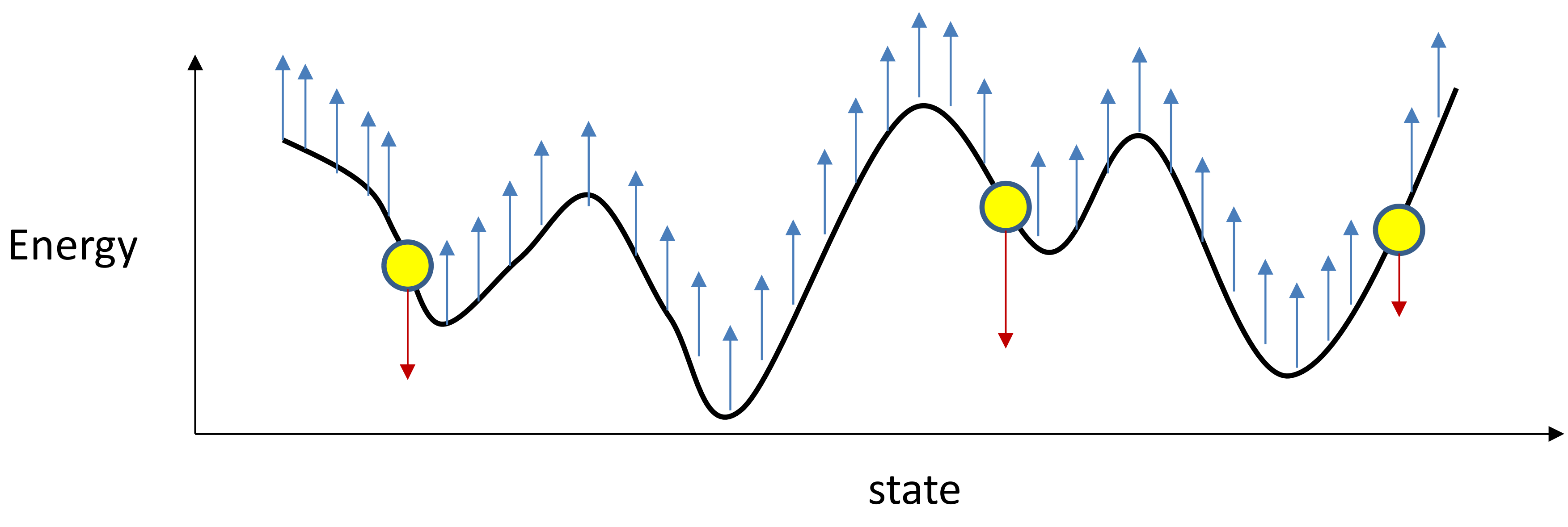
- The first term tries to *minimize* the energy at target patterns
  - Make them local minima
  - Emphasize more "important" memories by repeating them more frequently



The negative class

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T\right)$$

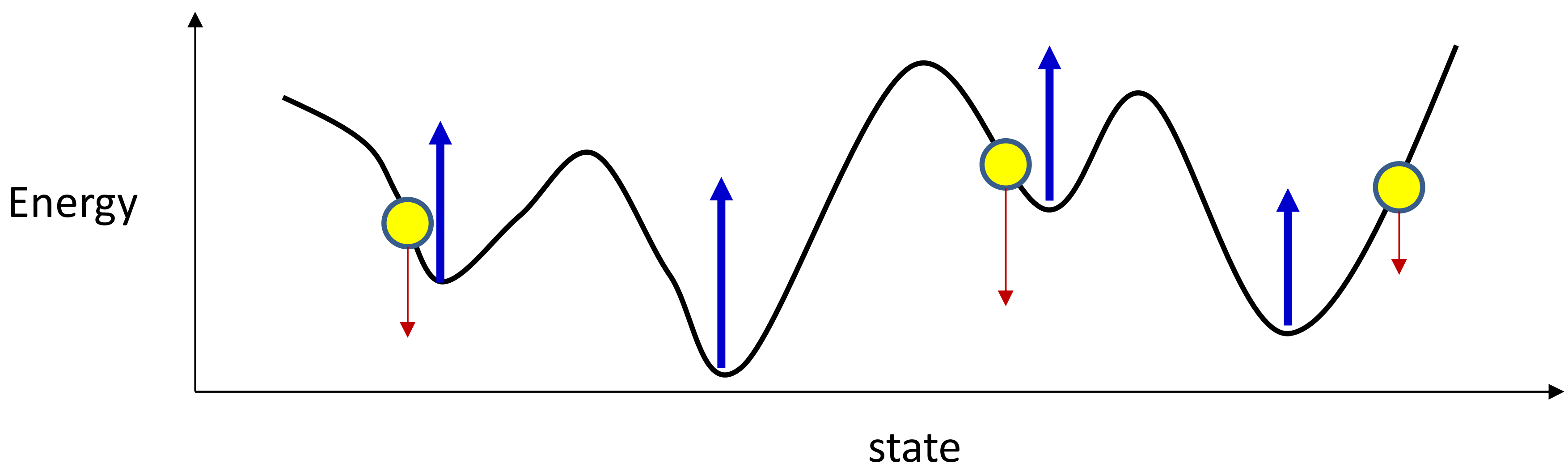
- The second term tries to “raise” all non-target patterns
  - Do we need to raise *everything*?



Option 1: Focus on the valleys

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P \& \mathbf{y}=valley} \mathbf{y}\mathbf{y}^T\right)$$

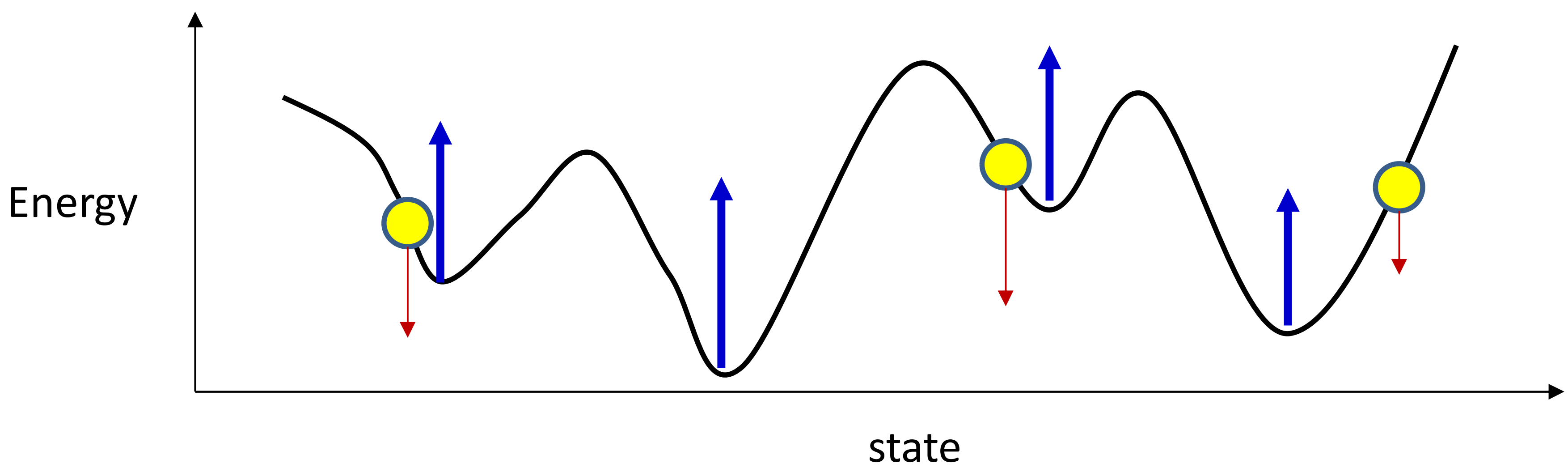
- Focus on raising the valleys
  - If you raise *every* valley, eventually they'll all move up above the target patterns, and many will even vanish



Identifying the valleys..

$$\mathbf{W} = \mathbf{W} + \eta \left(\sum_{\mathbf{y} \in \mathbf{Y}_P} \mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y} \notin \mathbf{Y}_P \& \mathbf{y} = valley} \mathbf{y}\mathbf{y}^T \right)$$

- Problem: How do you identify the valleys for the current $\mathbf{W}$?



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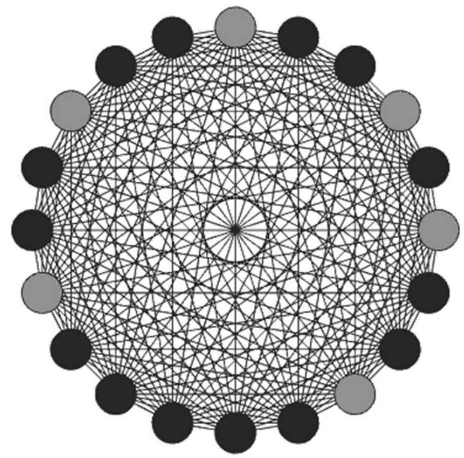
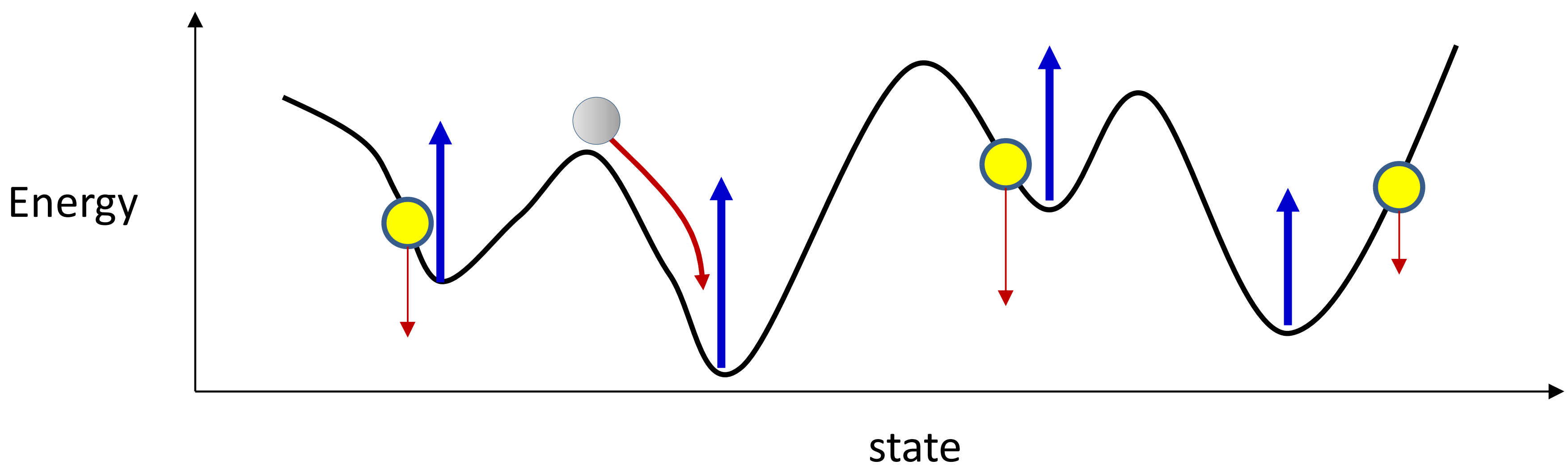


- Initialize the network randomly and let it evolve
  - It will settle in a valley



Training the Hopfield network

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P \& \mathbf{y}=valley} \mathbf{y}\mathbf{y}^T\right)$$

- Initialize $\mathbf{W}$
- Compute the total outer product of all target patterns
  - More important patterns presented more frequently
- Randomly initialize the network several times and let it evolve
  - And settle at a valley
- Compute the total outer product of valley patterns
- Update weights

Training the Hopfield network: SGD version

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P \& \mathbf{y}=valley} \mathbf{y}\mathbf{y}^T\right)$$

- Initialize $\mathbf{W}$
- Do until convergence, satisfaction, or death from boredom:
  - Sample a target pattern $\mathbf{y}_p$
    - Sampling frequency of pattern must reflect importance of pattern
  - Randomly initialize the network and let it evolve
    - And settle at a valley $\mathbf{y}_v$
  - Update weights
    - $\mathbf{W} = \mathbf{W} + \eta\left(\mathbf{y}_p\mathbf{y}_p^T - \mathbf{y}_v\mathbf{y}_v^T\right)$

Training the Hopfield network

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P \& \mathbf{y}=valley} \mathbf{y}\mathbf{y}^T\right)$$

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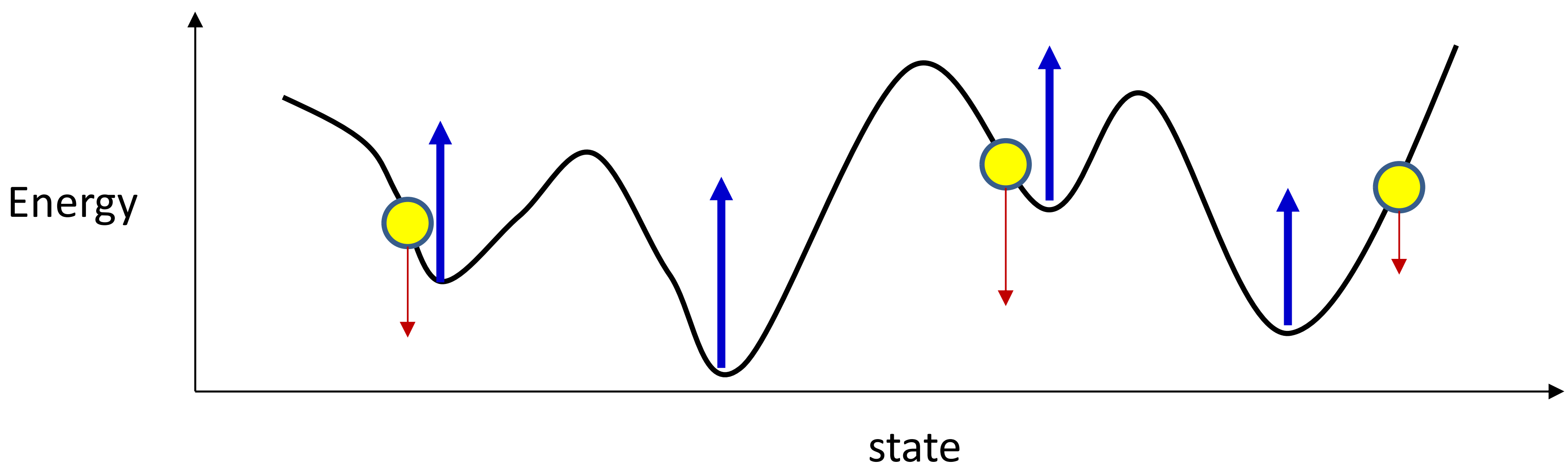
  - Update weights
    - $\mathbf{W} = \mathbf{W} + \eta\left(\mathbf{y}_p\mathbf{y}_p^T - \mathbf{y}_v\mathbf{y}_v^T\right)$

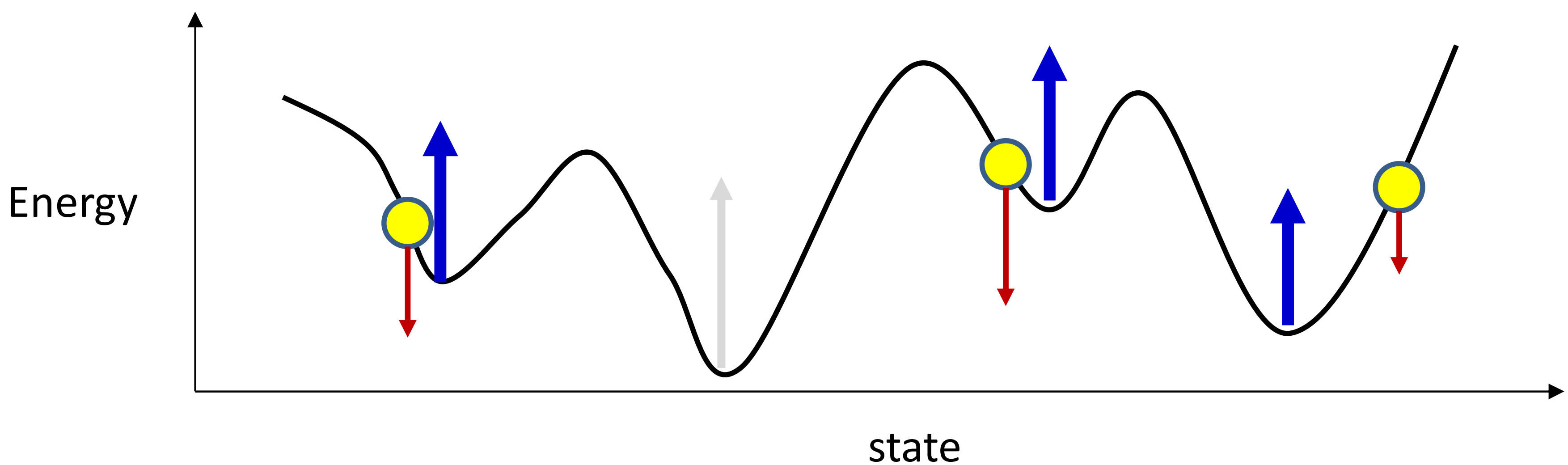
Which valleys?

- Should we *randomly* sample valleys?
  - Are all valleys equally important?

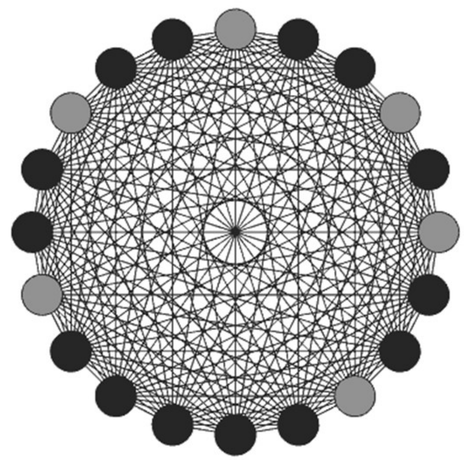


Which valleys?

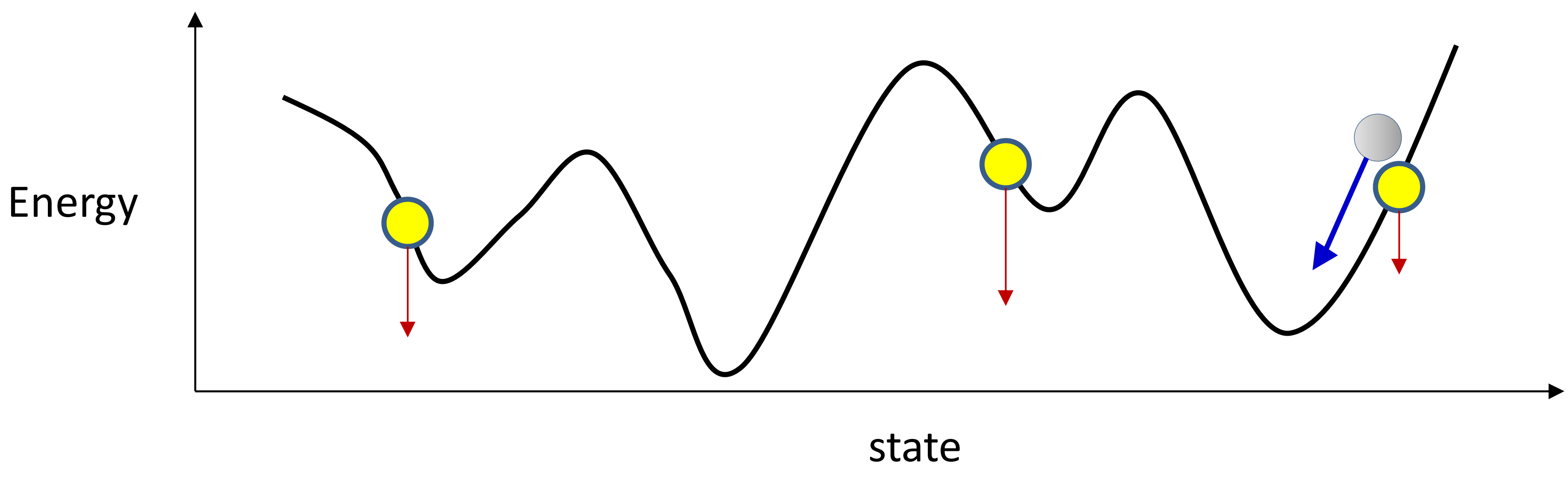
- Should we *randomly* sample valleys?
  - Are all valleys equally important?
- Major requirement: memories must be stable
  - They *must* be broad valleys
- Spurious valleys in the neighborhood of memories are more important to eliminate



Identifying the valleys..



- Initialize the network at valid memories and let it evolve
  - It will settle in a valley. If this is not the target pattern, raise it



Training the Hopfield network

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P \& \mathbf{y}=valley} \mathbf{y}\mathbf{y}^T\right)$$

- Initialize $\mathbf{W}$
- Compute the total outer product of all target patterns
  - More important patterns presented more frequently
- Initialize the network with each target pattern and let it evolve
  - And settle at a valley
- Compute the total outer product of valley patterns
- Update weights

Training the Hopfield network: SGD version

$$\mathbf{W} = \mathbf{W} + \eta \sum_{\mathbf{y} \in \mathbf{Y}_P} (\mathbf{y}\mathbf{y}^T - \mathbf{y}_\mathbf{v}\mathbf{y}_v^T)$$

- Initialize $\mathbf{W}$
- Do until convergence, satisfaction, or death from boredom:
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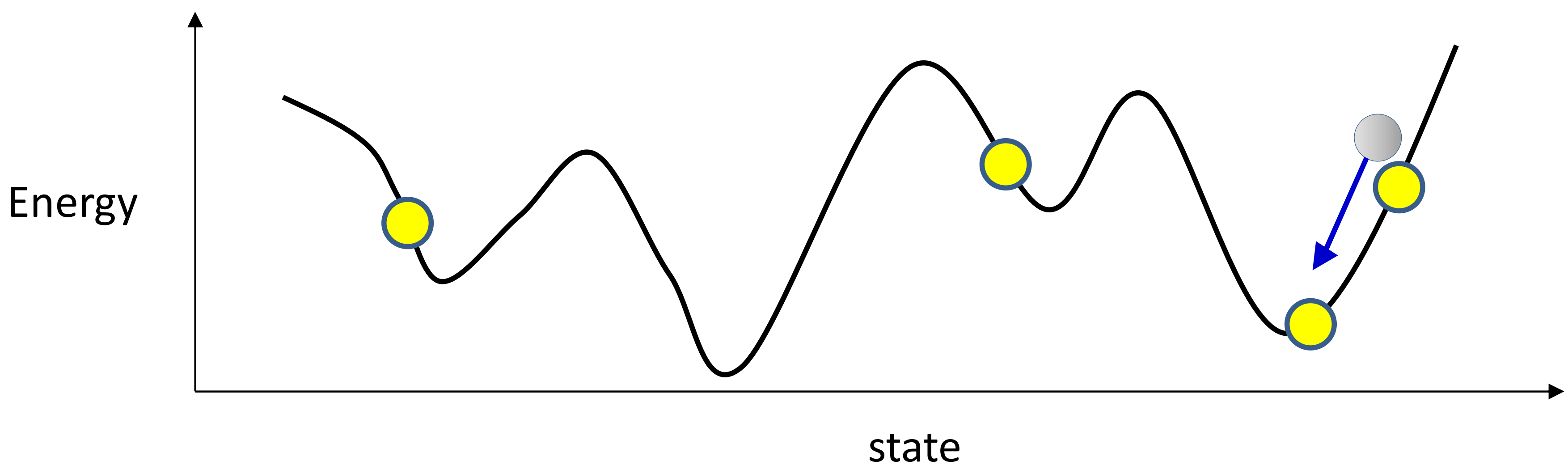
    - Sampling frequency of pattern must reflect importance of pattern
  - Initialize the network at $\mathbf{y}_p$ and let it evolve
    - And settle at a valley $\mathbf{y}_v$
  - Update weights
    - $\mathbf{W} = \mathbf{W} + \eta(\mathbf{y}_p\mathbf{y}_p^T - \mathbf{y}_v\mathbf{y}_v^T)$

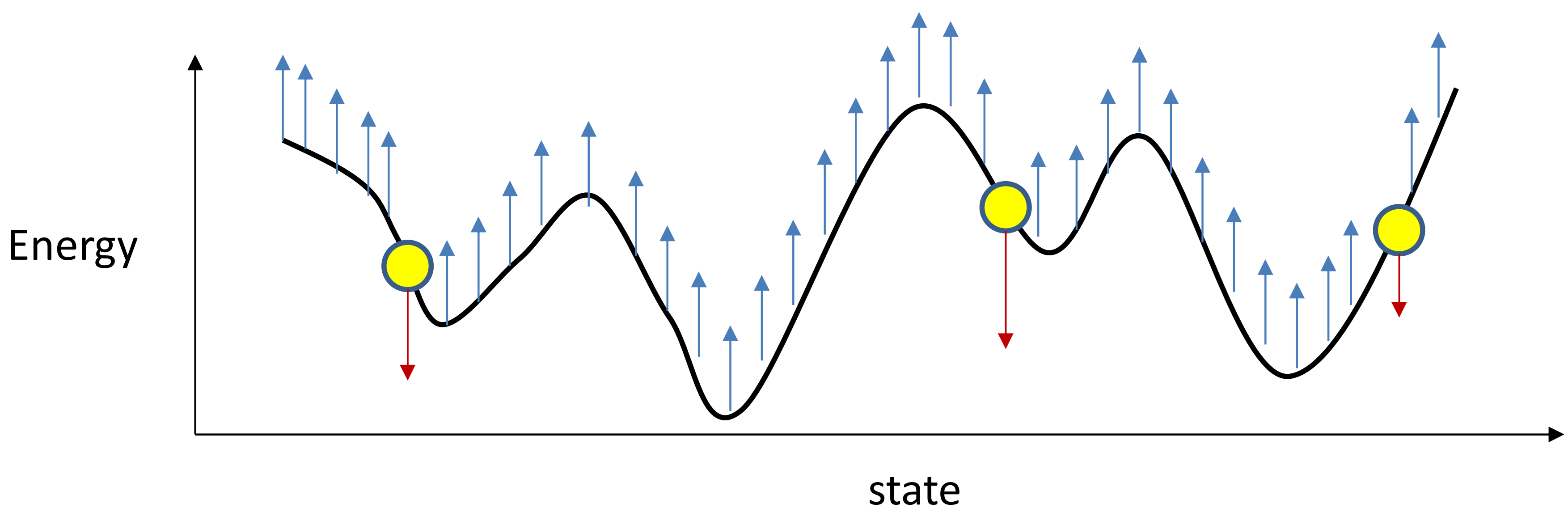
A possible problem

- What if there's another target pattern downvalley
  - Raising it will destroy a better-represented or stored pattern!



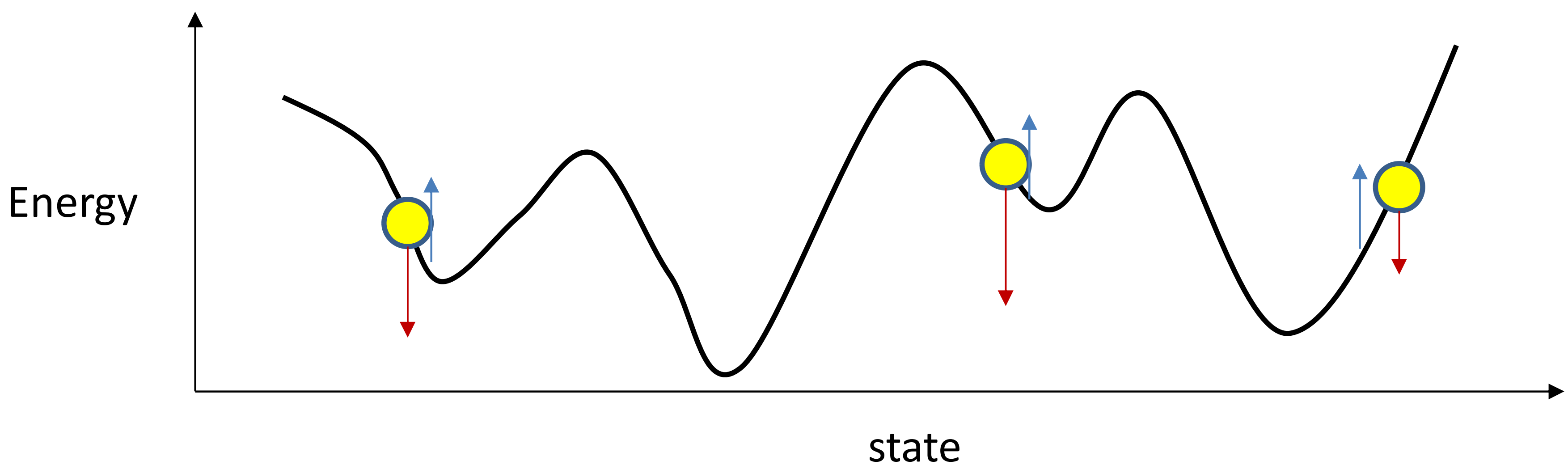
A related issue

- Really no need to raise the entire surface, or even every valley



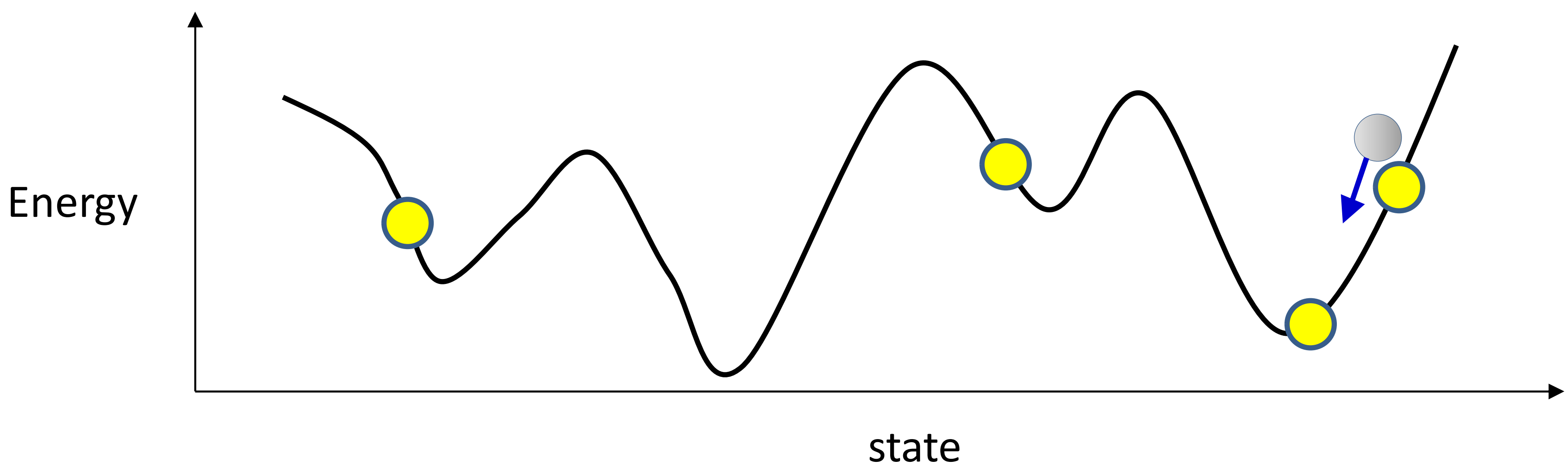
A related issue

- Really no need to raise the entire surface, or even every valley
- Raise the *neighborhood* of each target memory
  - Sufficient to make the memory a valley
  - The broader the neighborhood considered, the broader the valley



Raising the neighborhood

- Starting from a target pattern, let the network evolve only a few steps
  – Try to raise the resultant location
- Will raise the neighborhood of targets
- Will avoid problem of down-valley targets



Training the Hopfield network: SGD version

$$\mathbf{W} = \mathbf{W} + \eta\eta \sum_{\mathbf{y}\in\mathbf{Y}_P} \left(\mathbf{y}\mathbf{y}^T - \mathbf{y}_{\boldsymbol{d}}\mathbf{y}_{\boldsymbol{d}}^T\right)$$

- Initialize $\mathbf{W}$
- Do until convergence, satisfaction, or death from boredom:
  - Sample a target pattern $\mathbf{y}_p$
    - Sampling frequency of pattern must reflect importance of pattern
  - Initialize the network at $\mathbf{y}_p$ and let it evolve ***a few steps (2-4)***
    - And arrive at a down-valley position $\mathbf{y}_d$
  - Update weights
    - $\mathbf{W} = \mathbf{W} + \eta\left(\mathbf{y}_p\mathbf{y}_p^T - \mathbf{y}_d\mathbf{y}_d^T\right)$

Story so far

- Hopfield nets with N neurons can store up to $0.14N$ random patterns through Hebbian learning
  - Issue: Hebbian learning assumes all patterns to be stored are equally important

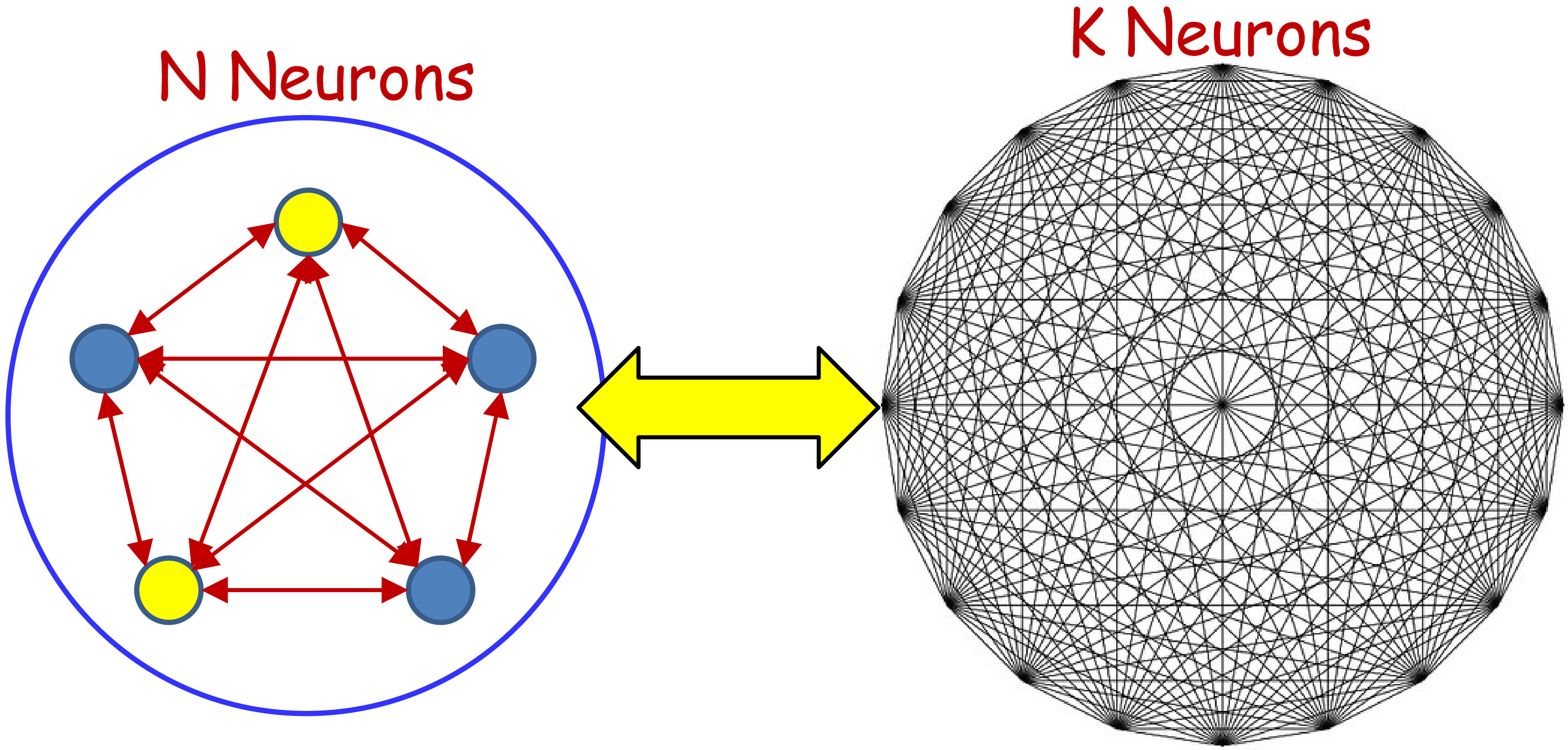
- In theory the number of *intentionally* stored patterns (stationary *and* stable) can be as large as N
  - But comes with many parasitic memories

- Networks that store $O(N)$ memories can be trained through optimization
  - By minimizing the energy of the target patterns, while increasing the energy of the neighboring patterns

Storing more than N patterns

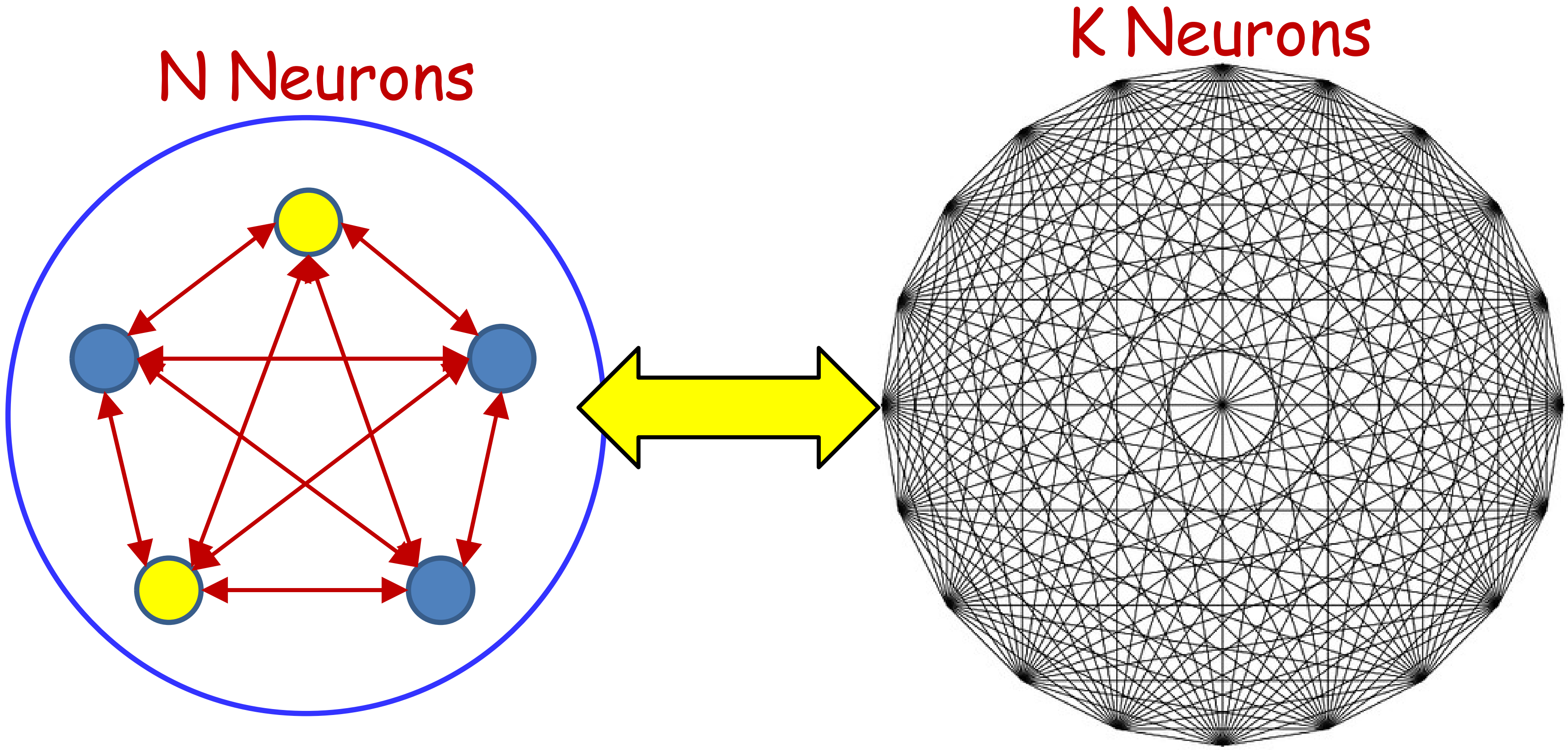
- The memory capacity of an N-bit network is at most N
  - Stable patterns (not necessarily even stationary)
    - Abu Mustafa and St. Jacques, 1985
    - Although "information capacity" is $\mathcal{O}(N^3)$
- How do we increase the capacity of the network
  - How to store more than N patterns

Expanding the network



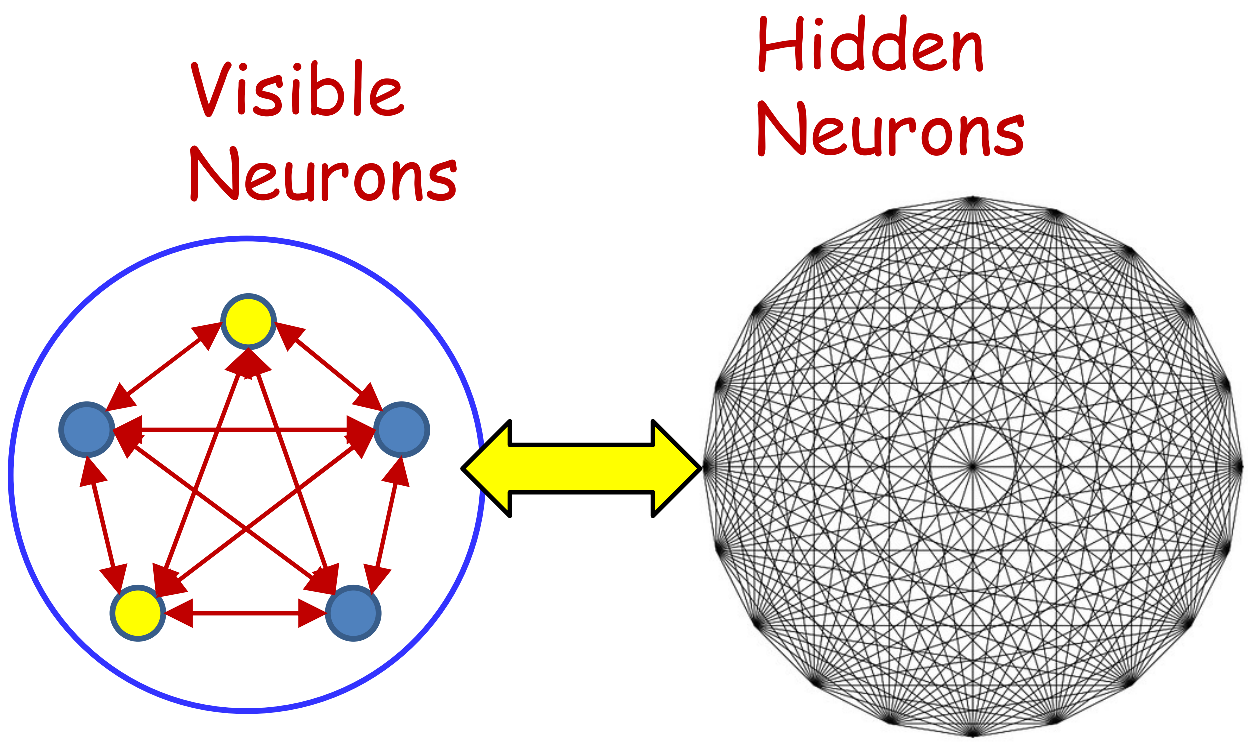
- Add a large number of neurons whose actual values you don’t care about!

Expanded Network



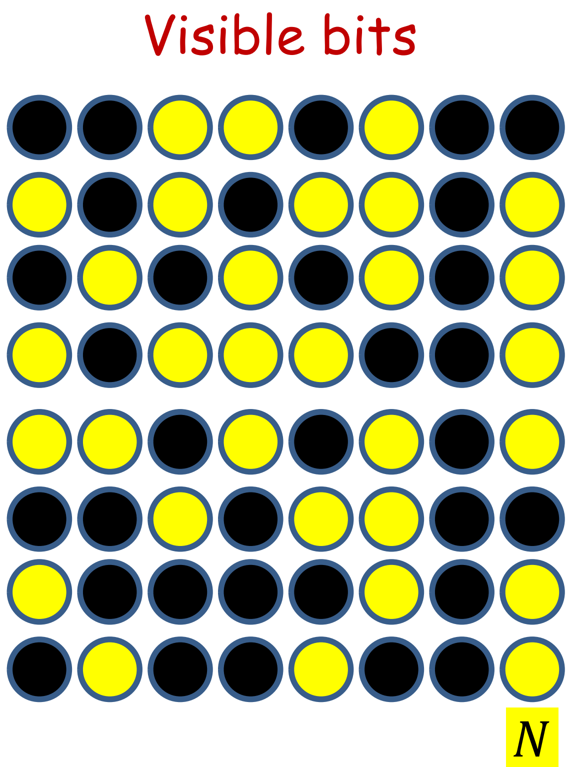
- New capacity: $\sim(N + K)$ patterns
  - Although we only care about the pattern of the first N neurons
  - We're interested in *N-bit* patterns

Terminology



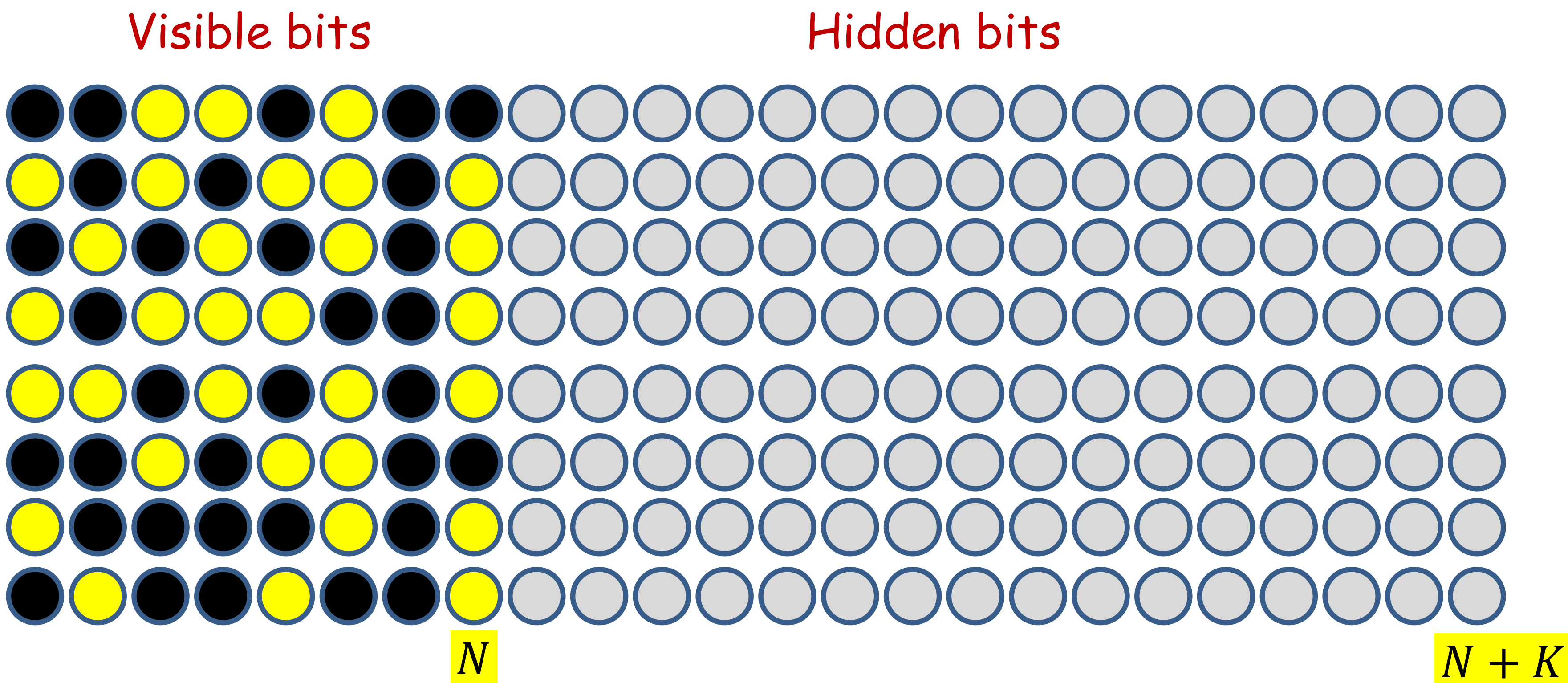
- Terminology:
  - The neurons that store the actual patterns of interest: *Visible neurons*
  - The neurons that only serve to increase the capacity but whose actual values are not important: *Hidden neurons*
  - These can be set to anything in order to store a visible pattern

Increasing the capacity: bits view



- The maximum number of patterns the net can store is bounded by the width *N* of the patterns..

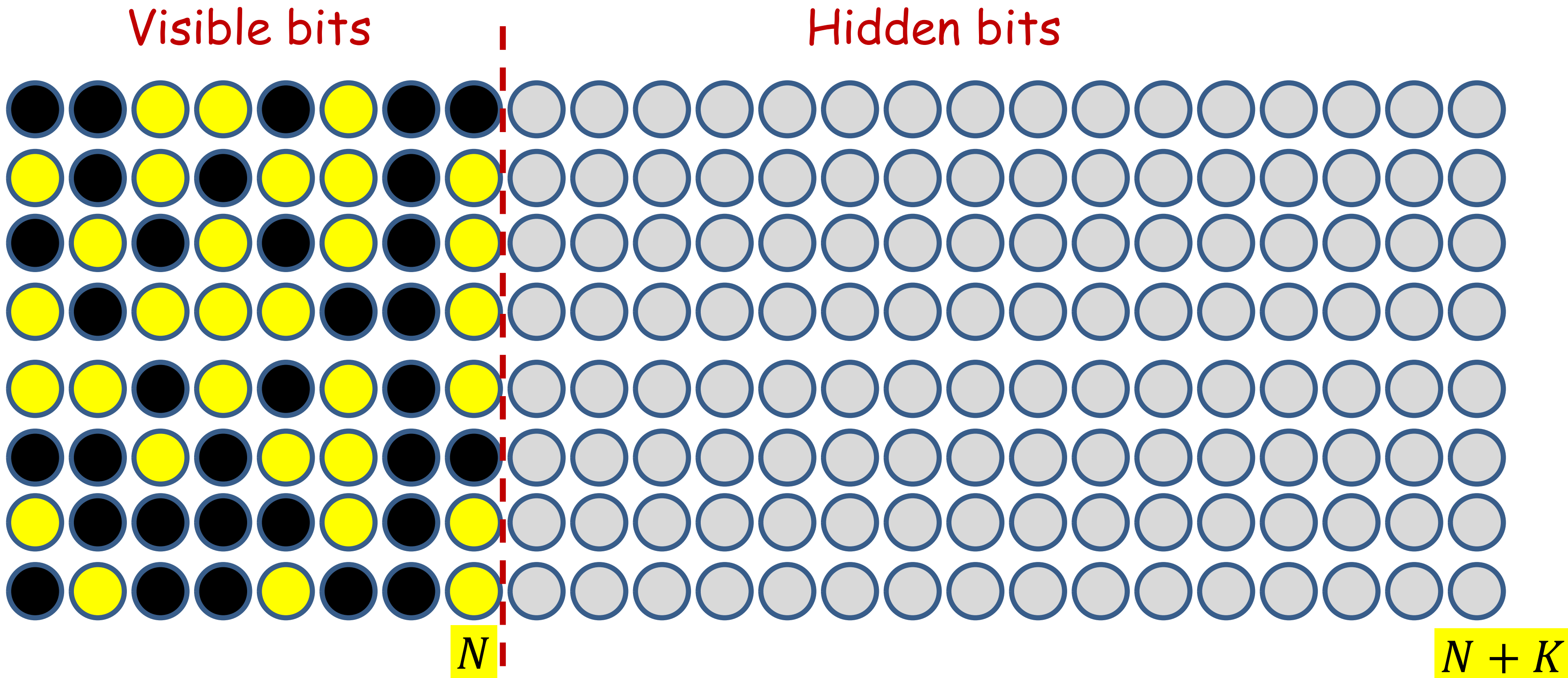
Increasing the capacity: bits view



- The maximum number of patterns the net can store is bounded by the width *N* of the patterns..

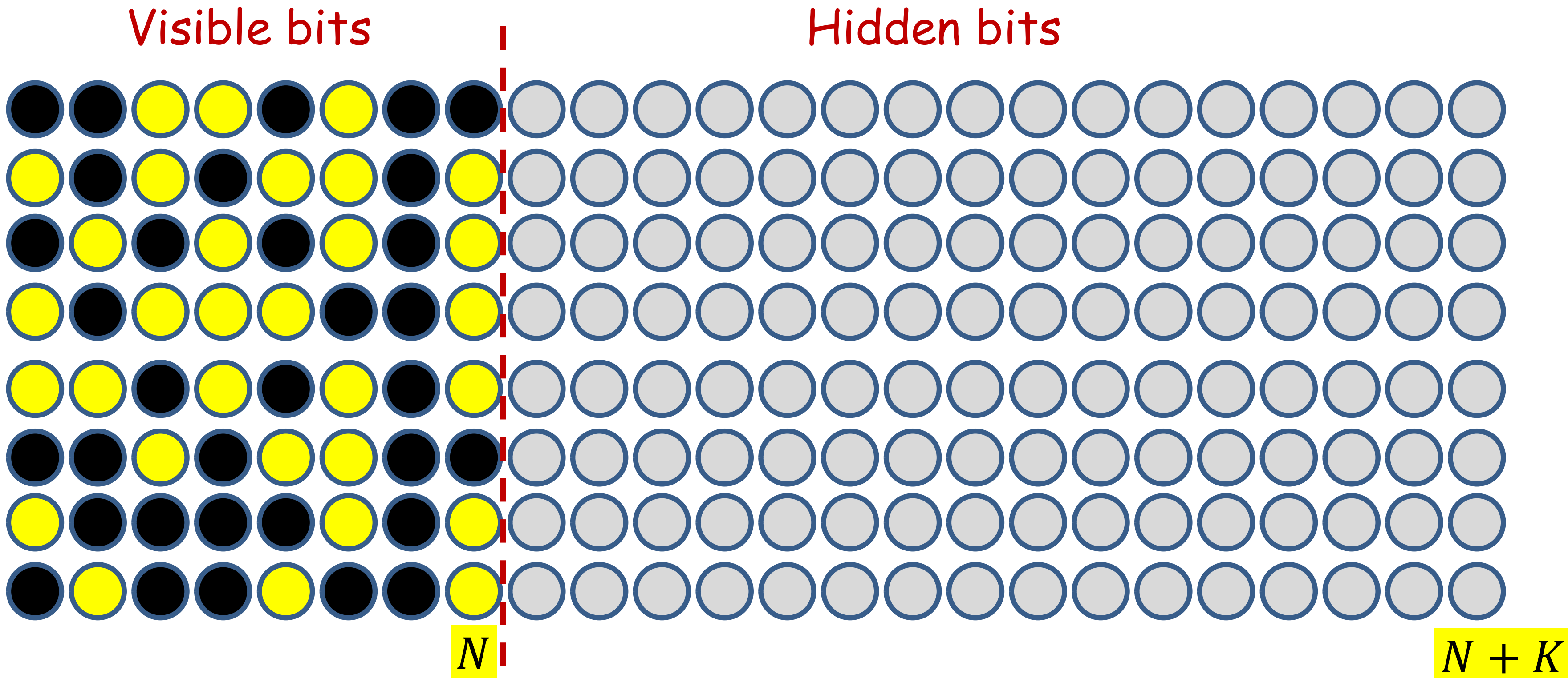
- So, let's *pad* the patterns with *K* "don't care" bits
  - The new width of the patterns is N+K
  - Now we can store N+K patterns!

Issues: Storage



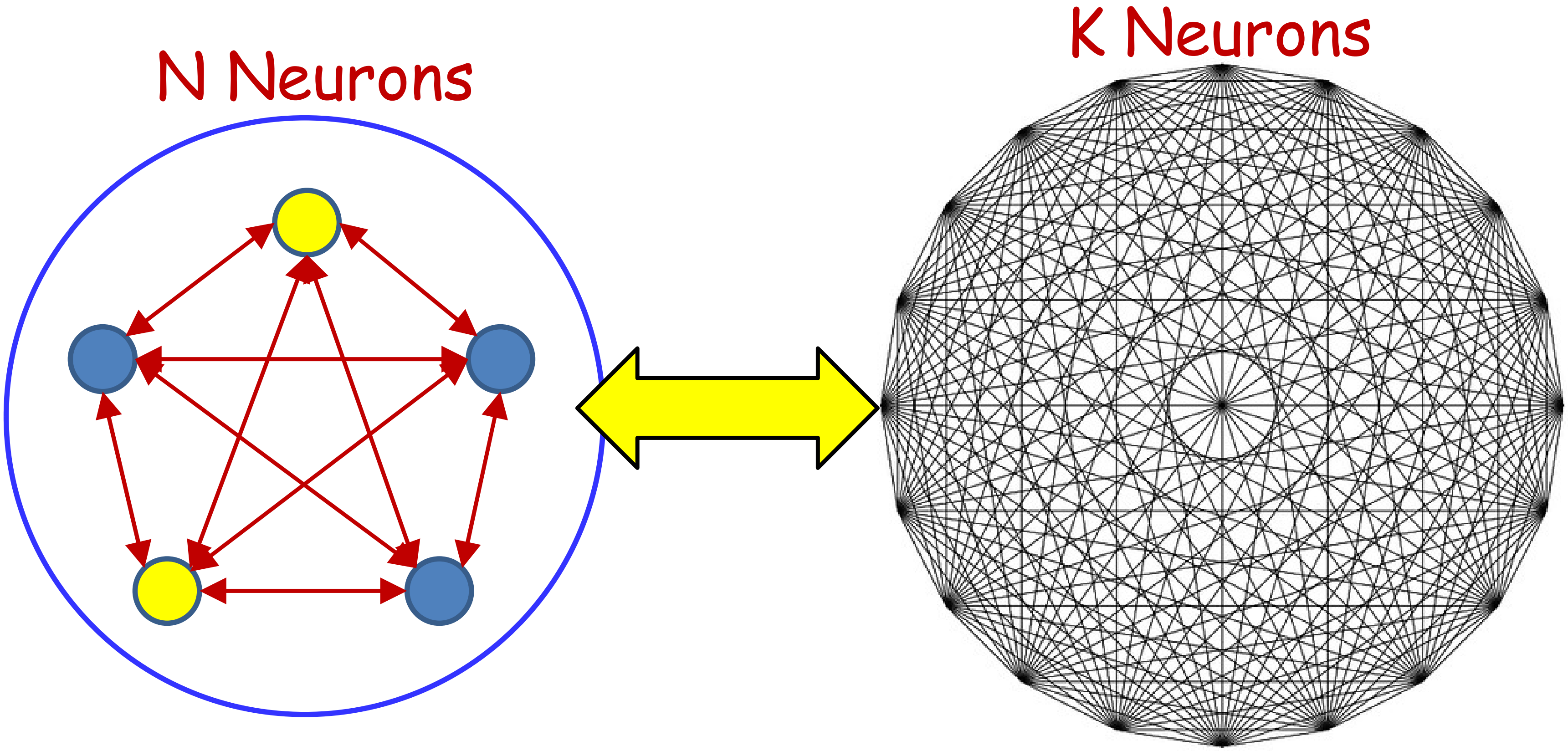
- What patterns do we fill in the don't care bits?
  - Simple option: Randomly
    - Flip a coin for each bit
  - We could even compose *multiple* extended patterns for a base pattern to increase the probability that it will be recalled properly
    - Recalling any of the extended patterns from a base pattern will recall the base pattern
- How do we store the patterns?
  - Standard optimization method should work

Issues: Recall



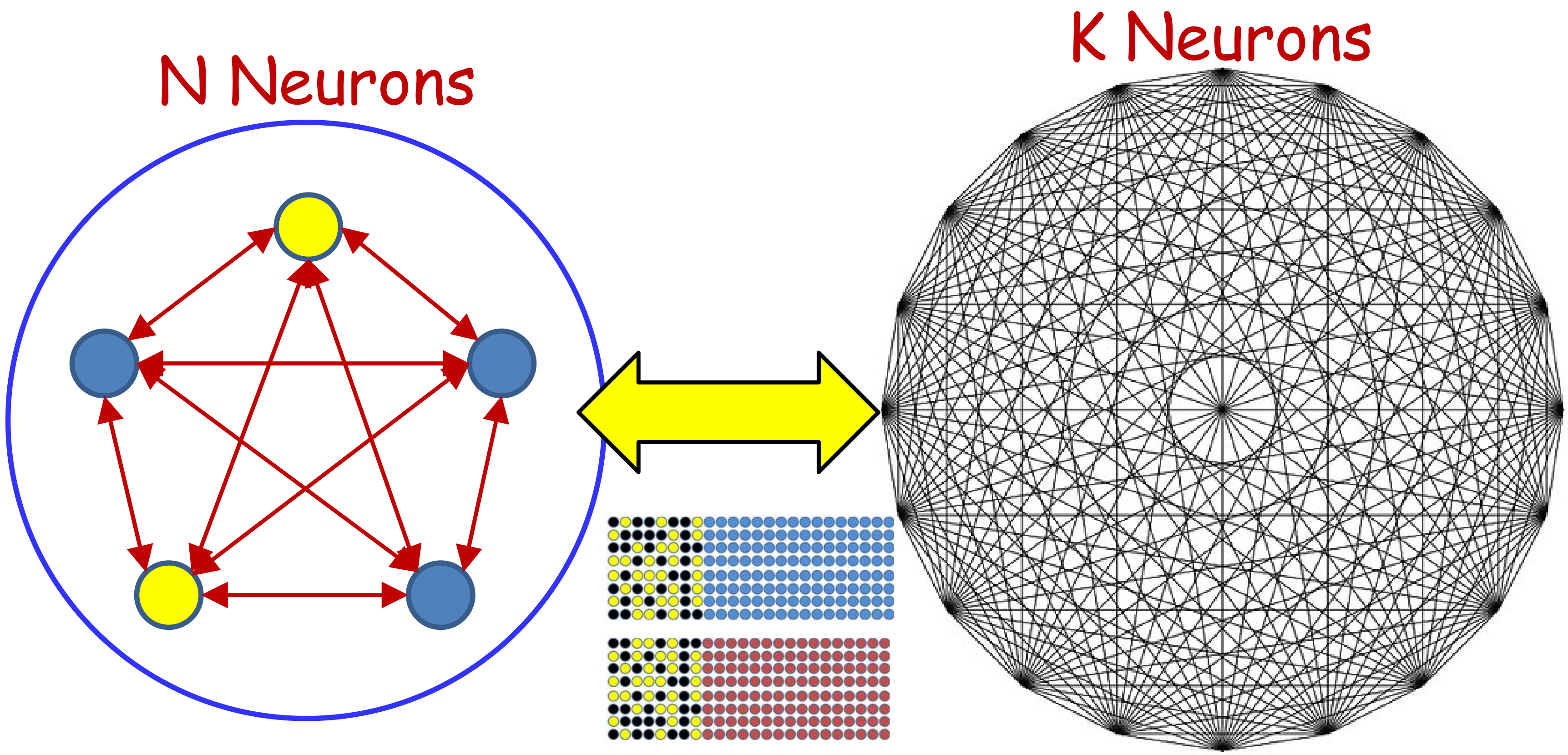
- How do we retrieve a memory?
- Can do so using usual "evolution" mechanism
- But this is not taking advantage of a key feature of the extended patterns:
  - Making errors in the don't care bits doesn't matter

Robustness of recall



- The value taken by the K hidden neurons during recall doesn't really matter
  - Even if it doesn't match what we actually tried to store
- Can we take advantage of this somehow?

Robustness of recall



- Also, we can have multiple extended patterns with the same pattern over visible bits
  - Can we exploit this somehow?

Taking advantage of don't care bits

- Simple random setting of don't care bits, and using the usual training and recall strategies for Hopfield nets should work

- However, it doesn't sufficiently exploit the redundancy of the don't care bits
  - Possible to set the don't care bits such that the overall pattern (and hence the "visible" bits portion of the pattern) is more memorable
  - Also, may have multiple don't-care patterns for a target pattern
    - Multiple valleys, in which the visible bits remain the same, but don't care bits vary

- To exploit it properly, it helps to view the Hopfield net differently: as a probabilistic machine

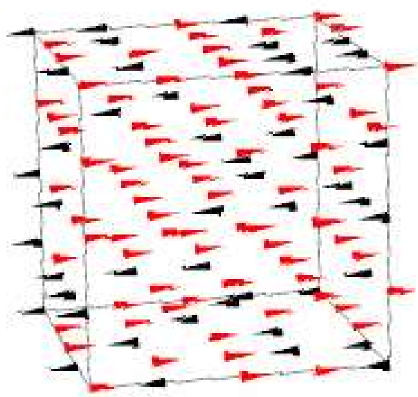
A probabilistic interpretation of Hopfield Nets

- For *binary* y the energy of a pattern is the analog of the negative log likelihood of a *Boltzmann distribution*
  - **Minimizing energy maximizes log likelihood**

$$E(\mathbf{y}) = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y} \qquad P(\mathbf{y}) = Cexp(-E(\mathbf{y}))$$

The Boltzmann Distribution

$$E(\mathbf{y}) = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y} - \mathbf{b}^T\mathbf{y} \qquad P(\mathbf{y}) = C exp\left(\frac{-E(\mathbf{y})}{kT}\right)$$



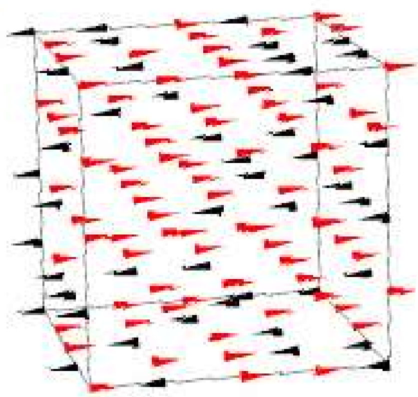
$$C = \frac{1}{\sum_{\mathbf{y}} exp\left(\frac{-E(\mathbf{y})}{kT}\right)}$$

- k is the Boltzmann constant
- T is the temperature of the system
- The energy terms are the negative loglikelihood of a Boltzmann distribution at $T = 1$ to within an additive constant
  - Derivation of this probability is in fact quite trivial..

Continuing the Boltzmann analogy

$$E(\mathbf{y}) = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y} - \mathbf{b}^T\mathbf{y}$$

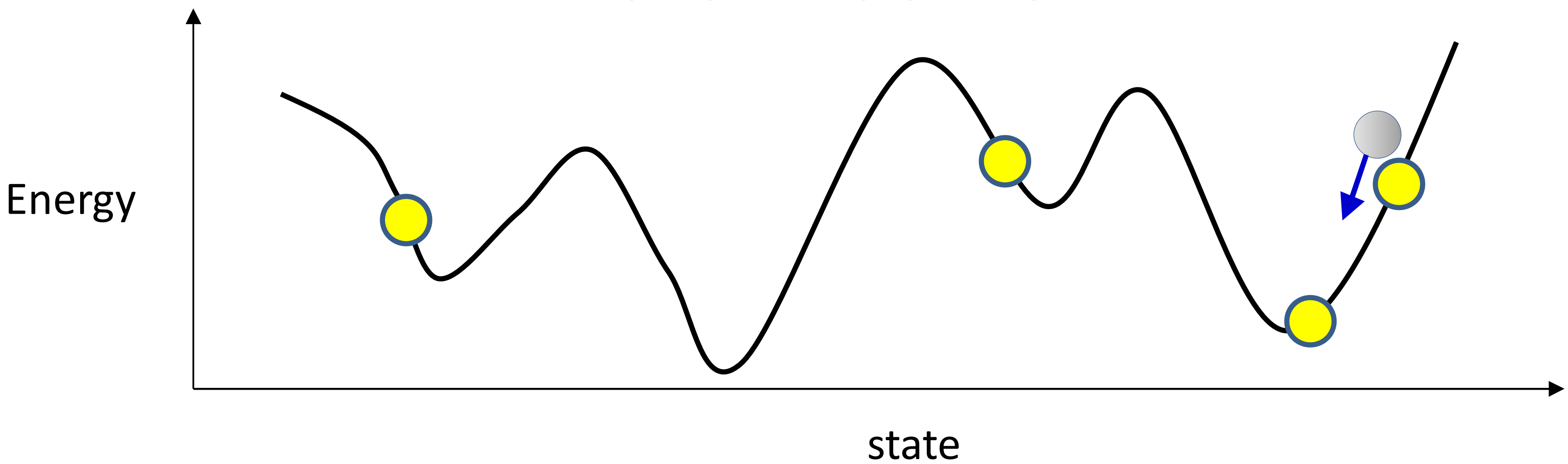
$$P(\mathbf{y}) = Cexp\left(\frac{-E(\mathbf{y})}{kT}\right)$$



$$C = \frac{1}{\sum_{\mathbf{y}} exp\left(\frac{-E(\mathbf{y})}{kT}\right)}$$

- The system *probabilistically* selects states with lower energy
  - With infinitesimally slow cooling, at $T = 0$, it arrives at the global minimal state

Spin glasses and the Boltzmann distribution



- Selecting a next state is analogous to drawing a sample from the Boltzmann distribution at $T = 1$, in a universe where $k = 1$
  – Energy landscape of a spin-glass model: Exploration and characterization, Zhou and Wang, Phys. Review E 79, 2009

Hopfield nets: Optimizing W

$$E(\mathbf{y}) = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y} \qquad \widehat{\mathbf{W}} = \underset{\mathbf{W}}{\operatorname{argmin}} \sum_{\mathbf{y}\in\mathbf{Y}_P} E(\mathbf{y}) - \sum_{\mathbf{y}\notin\mathbf{Y}_P} E(\mathbf{y})$$

- Simple gradient descent:

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \alpha_{\mathbf{y}}\mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P} \beta(E(\mathbf{y}))\mathbf{y}\mathbf{y}^T\right)$$

More importance to more frequently presented memories

More importance to more attractive spurious memories

Hopfield nets: Optimizing W

$$E(\mathbf{y}) = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y} \qquad \widehat{\mathbf{W}} = \underset{\mathbf{W}}{\operatorname{argmin}} \sum_{\mathbf{y}\in\mathbf{Y}_P} E(\mathbf{y}) - \sum_{\mathbf{y}\notin\mathbf{Y}_P} E(\mathbf{y})$$

- Simple gradient descent:

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \alpha_{\mathbf{y}}\mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P} \beta(E(\mathbf{y}))\mathbf{y}\mathbf{y}^T\right)$$

More importance to more frequently presented memories

More importance to more attractive spurious memories

THIS LOOKS LIKE AN EXPECTATION!

Hopfield nets: Optimizing W

$$E(\mathbf{y}) = -\frac{1}{2}\mathbf{y}^T\mathbf{W}\mathbf{y} \qquad \widehat{\mathbf{W}} = \underset{\mathbf{W}}{\operatorname{argmin}} \sum_{\mathbf{y}\in\mathbf{Y}_P} E(\mathbf{y}) - \sum_{\mathbf{y}\notin\mathbf{Y}_P} E(\mathbf{y})$$

- Update rule

$$\mathbf{W} = \mathbf{W} + \eta\left(\sum_{\mathbf{y}\in\mathbf{Y}_P} \alpha_{\mathbf{y}}\mathbf{y}\mathbf{y}^T - \sum_{\mathbf{y}\notin\mathbf{Y}_P} \beta(E(\mathbf{y}))\mathbf{y}\mathbf{y}^T\right)$$

$$\mathbf{W} = \mathbf{W} + \eta\left(E_{\mathbf{y}\sim\mathbf{Y}_P}\mathbf{y}\mathbf{y}^T - E_{\mathbf{y}\sim Y}\mathbf{y}\mathbf{y}^T\right)$$

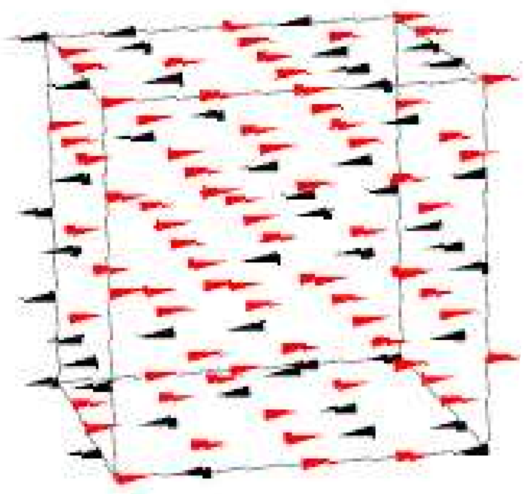
Natural distribution for variables: The Boltzmann Distribution

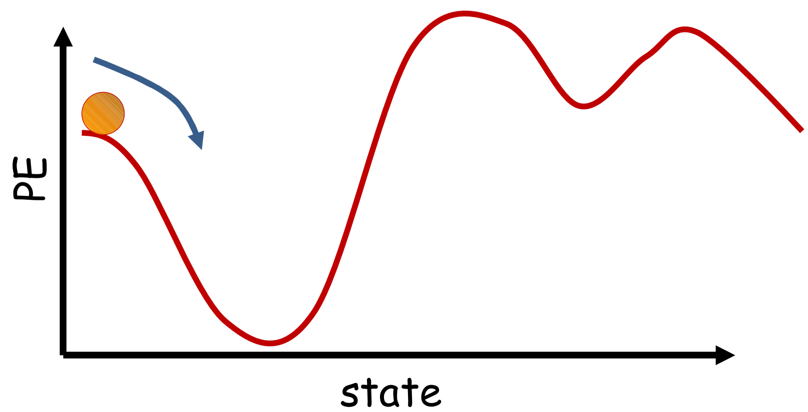
From Analogy to Model

- The behavior of the Hopfield net is analogous to annealed dynamics of a spin glass characterized by a Boltzmann distribution

- So, let's explicitly model the Hopfield net as a distribution..

Revisiting Thermodynamic Phenomena





- Is the system actually in a specific state at any time?
- No – the state is actually continuously changing
  - Based on the temperature of the system
    - At higher temperatures, state changes more rapidly
- What is actually being characterized is the *probability* of the state
  - And the *expected* value of the state

The Helmholtz Free Energy of a System

- A thermodynamic system at temperature T can exist in one of many states
  - Potentially infinite states
  - At any time, the probability of finding the system in state s at temperature T is $P_T(s)$
- At each state s it has a potential energy E_s
- The *internal energy* of the system, representing its capacity to do work, is the average:

$$U_T = \sum_s P_T(s)\, E_s$$

The Helmholtz Free Energy of a System

- The capacity to do work is counteracted by the internal disorder of the system, i.e. its entropy

$$H_T = -\sum_s P_T(s) \log P_T(s)$$

- The *Helmholtz* free energy of the system combines the two terms

$$F_T = U_T + kTH_T$$

$$= \sum_s P_T(s)\, E_s - kT \sum_s P_T(s) \log P_T(s)$$

The Helmholtz Free Energy of a System

$$F_T = \sum_s P_T(s)\, E_s - kT \sum_s P_T(s) \log P_T(s)$$

- A system held at a specific temperature *anneals* by varying the rate at which it visits the various states, to reduce the free energy in the system, until a minimum free-energy state is achieved

- The probability distribution of the states at steady state is known as the *Boltzmann distribution*

The Helmholtz Free Energy of a System

$$F_T = \sum_s P_T(s)\, E_s - kT \sum_s P_T(s) \log P_T(s)$$

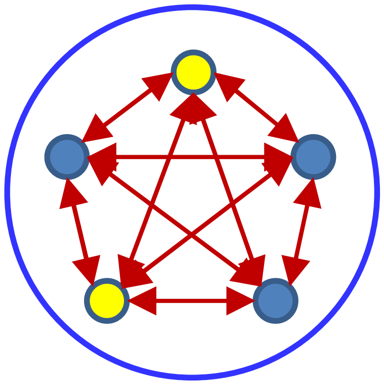
- Minimizing this w.r.t $P_T(s)$, we get

$$P_T(s) = \frac{1}{Z} exp\left(\frac{-E_s}{kT}\right)$$

  – Also known as the *Gibbs* distribution
  – Z is a normalizing constant
  – Note the dependence on T
  – A T = 0, the system will always remain at the lowest-energy configuration with prob = 1.

The Energy of the Network

Visible Neurons

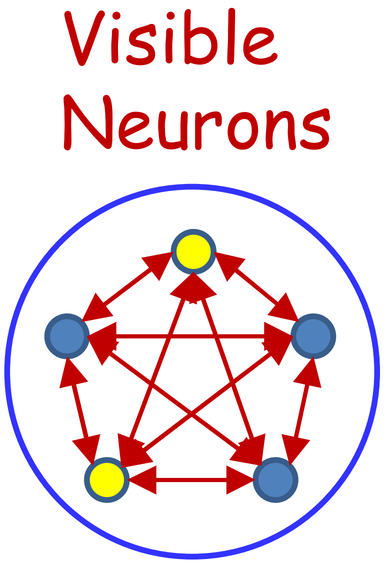


$$E(S) = -\sum_{i<j} w_{ij} s_i s_j - b_i s_i$$

$$\boxed{P(S) = \frac{exp(-E(S))}{\sum_{S'} exp(-E(S'))}}$$

- We can define the energy of the system as before
- Since neurons are stochastic, there is disorder or entropy (with T = 1)
- The *equilibribum* probability distribution over states is the Boltzmann distribution at T=1
  - This is the probability of different states that the network will wander over *at equilibrium*

The Hopfield net is a distribution



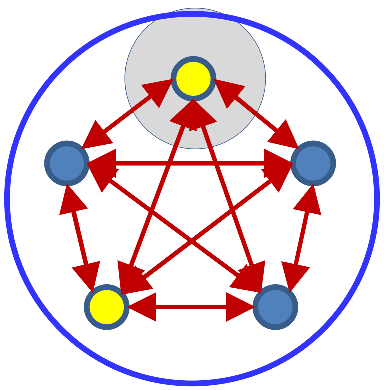
$$E(S) = -\sum_{i<j} w_{ij} s_i s_j - b_i s_i$$

$$\boxed{P(S) = \frac{exp(-E(S))}{\sum_{S'} exp(-E(S'))}}$$

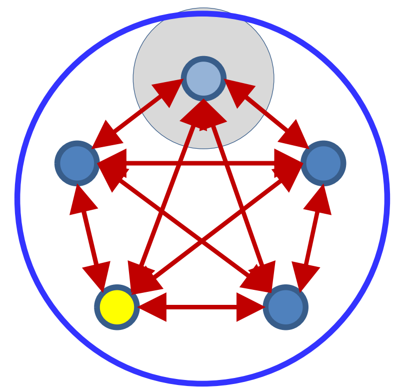
- The stochastic Hopfield network models a ***probability distribution*** over states
  - Where a state is a binary string
  - Specifically, it models a *Boltzmann distribution*
  - **The parameters of the model are the weights of the network**
- The probability that (at equilibrium) the network will be in any state is $P(S)$
  - It is a *generative* model: generates states according to $P(S)$

The field at a single node

- Let S and S' be otherwise identical states that only differ in the i-th bit
  - S has i-th bit = $+1$ and S' has i-th bit = -1



$$P(S) = P(s_i = 1 | s_{j \neq i}) P(s_{j \neq i})$$
$$P(S') = P(s_i = -1 | s_{j \neq i}) P(s_{j \neq i})$$

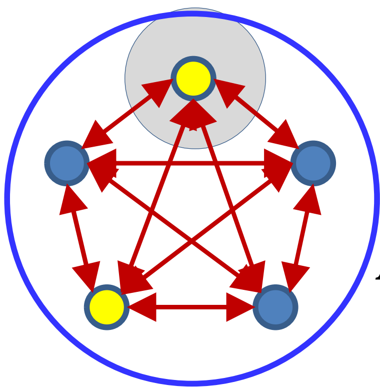


$$logP(S) - logP(S') = logP(s_i = 1 | s_{j \neq i}) - logP(s_i = -1 | s_{j \neq i})$$

$$logP(S) - logP(S') = log\frac{P(s_i = 1 | s_{j \neq i})}{1 - P(s_i = 1 | s_{j \neq i})}$$

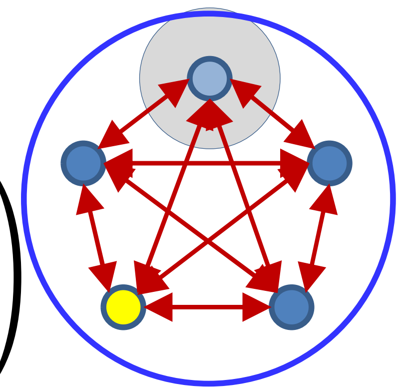
The field at a single node

- Let S and S' be the states with the ith bit in the $+1$ and -1 states



$$\log P(S) = -E(S) + C$$

$$E(S) = -\frac{1}{2}\left(E_{not\ i} + \sum_{j \neq i} w_j s_j + b_i\right)$$



$$E(S') = -\frac{1}{2}\left(E_{not\ i} - \sum_{j \neq i} w_j s_j - b_i\right)$$

- $logP(S) - logP(S') = E(S') - E(S) = \sum_{j \neq i} w_j s_j + b_i$

The field at a single node

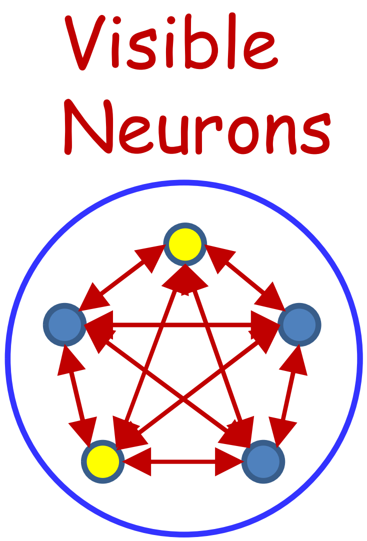
$$log\left(\frac{P\left(s_i = 1 \middle| s_{j\neq i}\right)}{1 - P\left(s_i = 1 \middle| s_{j\neq i}\right)}\right) = \sum_{j\neq i} w_j s_j + b_i$$

- Giving us

$$P\left(s_i = 1 \middle| s_{j\neq i}\right) = \frac{1}{1 + e^{-\left(\sum_{j\neq i} w_j s_j + b_i\right)}}$$

- The probability of any node taking value 1 given other node values is a logistic

Redefining the network

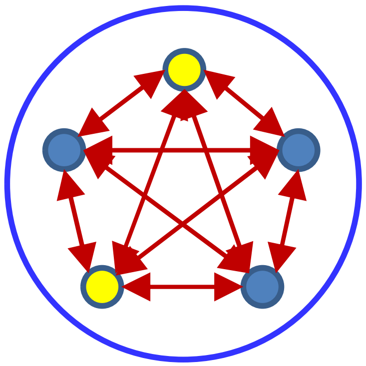


$$z_i = \sum_j w_{ji} s_j + b_i$$

$$\boxed{P(s_i = 1 | s_{j \neq i}) = \frac{1}{1 + e^{-z_i}}}$$

- First try: Redefine a regular Hopfield net as a stochastic system
- Each neuron is *now a stochastic unit* with a binary state s_i, which can take value 0 or 1 with a probability that depends on the local field
  - Note the slight change from Hopfield nets
  - Not actually necessary; only a matter of convenience

The Hopfield net is a distribution

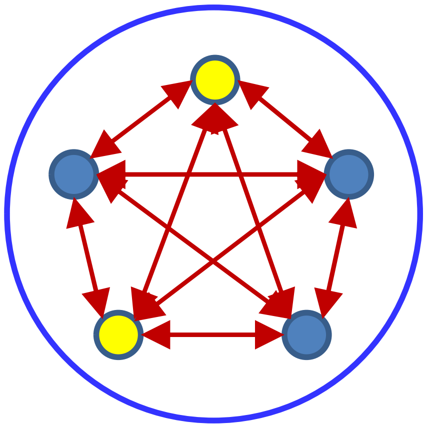


$$z_i = \sum_j w_{ji} s_j + b_i$$

$$\boxed{P(s_i = 1 | s_{j \neq i}) = \frac{1}{1 + e^{-z_i}}}$$

- The Hopfield net is a probability distribution over binary sequences
  - The Boltzmann distribution
- The *conditional* distribution of individual bits in the sequence is a logistic

Running the network



$$z_i = \sum_j w_{ji} s_j + b_i$$

$$\boxed{P(s_i = 1 | s_{j \neq i}) = \frac{1}{1 + e^{-z_i}}}$$

- Initialize the neurons
- Cycle through the neurons and randomly set the neuron to 1 or -1 according to the probability given above
  - Gibbs sampling: Fix N-1 variables and sample the remaining variable
  - As opposed to energy-based update (mean field approximation): run the test $z_i > 0$?
- After many many iterations (until "convergence"), *sample* the individual neurons

Exploiting the probabilistic view

- Next..