



Autoencoder and Variational Autoencoder

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K-Means Clustering

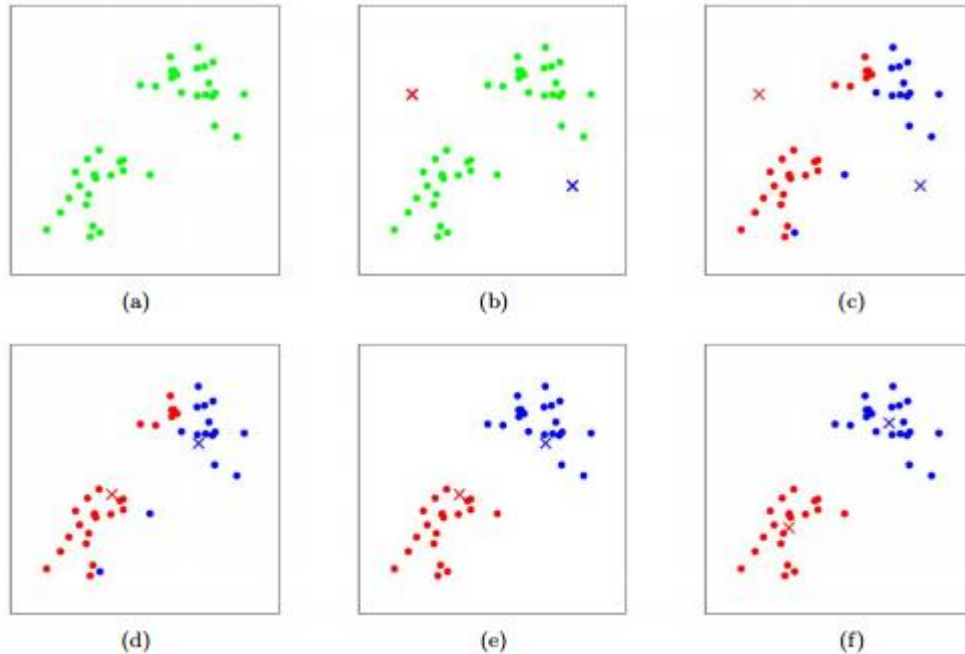
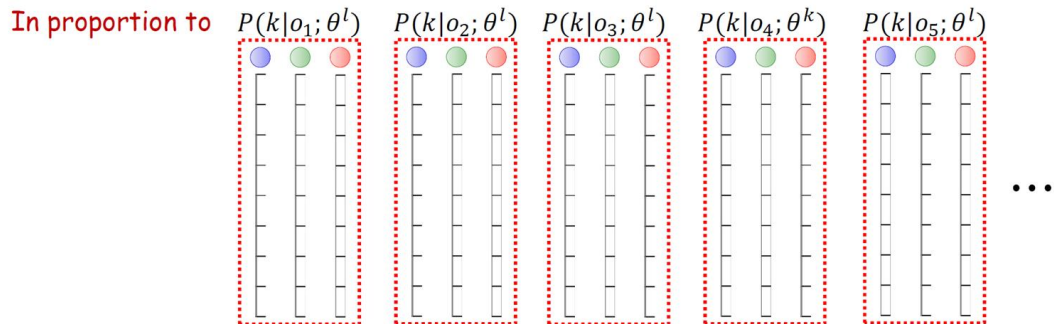


Figure 1: K-means algorithm. Training examples are shown as dots, and cluster centroids are shown as crosses. (a) Original dataset. (b) Random initial cluster centroids. (c-f) Illustration of running two iterations of k-means. In each iteration, we assign each training example to the closest cluster centroid (shown by "painting" the training examples the same color as the cluster centroid to which is assigned); then we move each cluster centroid to the mean of the points assigned to it. Images courtesy of Michael Jordan.

Expectation Maximization

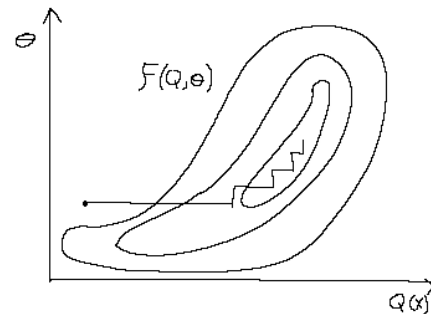
EM for GMMs



- Initialize μ_k^0 and Σ_k^0 for all k
- Iterate (over l):
 - Compute $P(k|o; \theta^l)$ for all o
 - Compute the proportions by which o is assigned to all Gaussians
 - Update:
 - $\mu_k^{l+1} = \frac{1}{\sum_o P(k|o; \theta^l)} \sum_o P(k|o; \theta^l) o$
 - $\Sigma_k^{l+1} = \frac{1}{\sum_o P(k|o; \theta^l)} \sum_o P(k|o; \theta^l) (o - \mu_k^{l+1})(o - \mu_k^{l+1})^T$

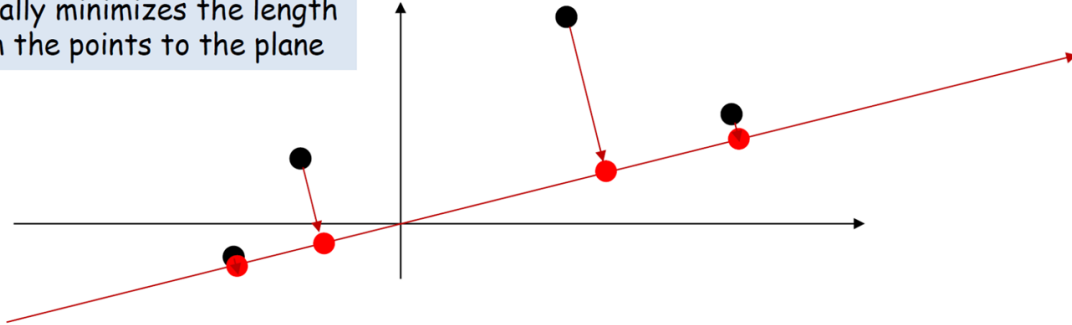
E: complete the data
M: update estimates

Coordinate ascent

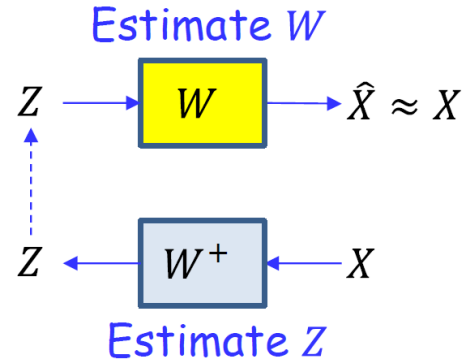


Linear Autoencoder = Iterative PCA

This individually minimizes the length of lines from the points to the plane



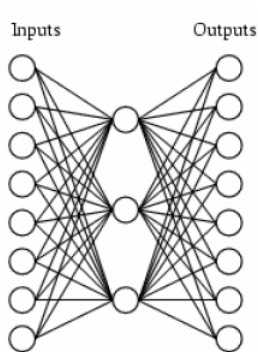
- Initialize a subspace (the basis w)
- Iterate until convergence:
 - Find the best position vectors Z on the W subspace for each training instance
 - Find the location on W that is *closest* to each instance, i.e. the perpendicular projection
 - Let W rotate and stretch/shrink, keeping the arrangement of Z locations fixed
 - Minimize the total square length of the lines attaching the projection on the plane to the instance



Examples of Autoencoders

Binary Autoencoder

Network

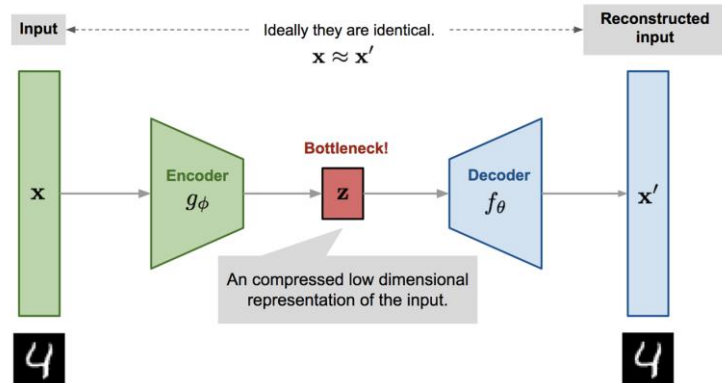


Data/Target

One-hot encodings of 0 to 7

Can we get the network to learn a binary latent vector?

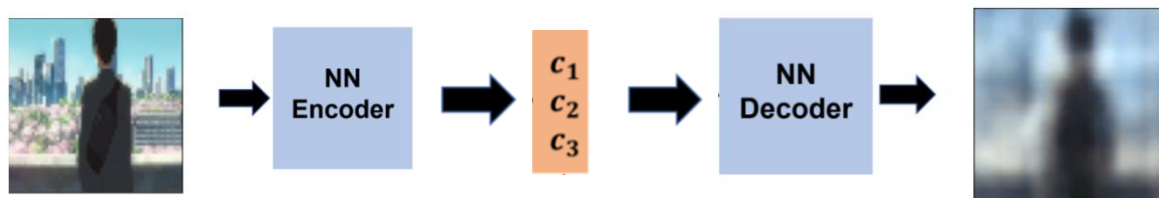
MNIST Autoencoder



MNIST dataset

How do we improve the quality of reconstructions?

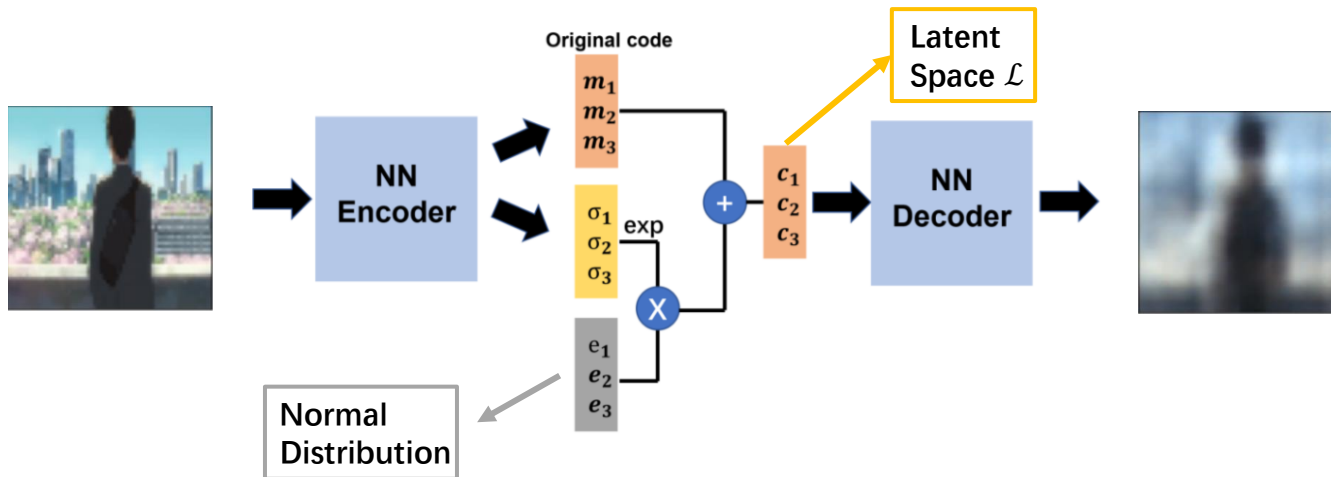
AE

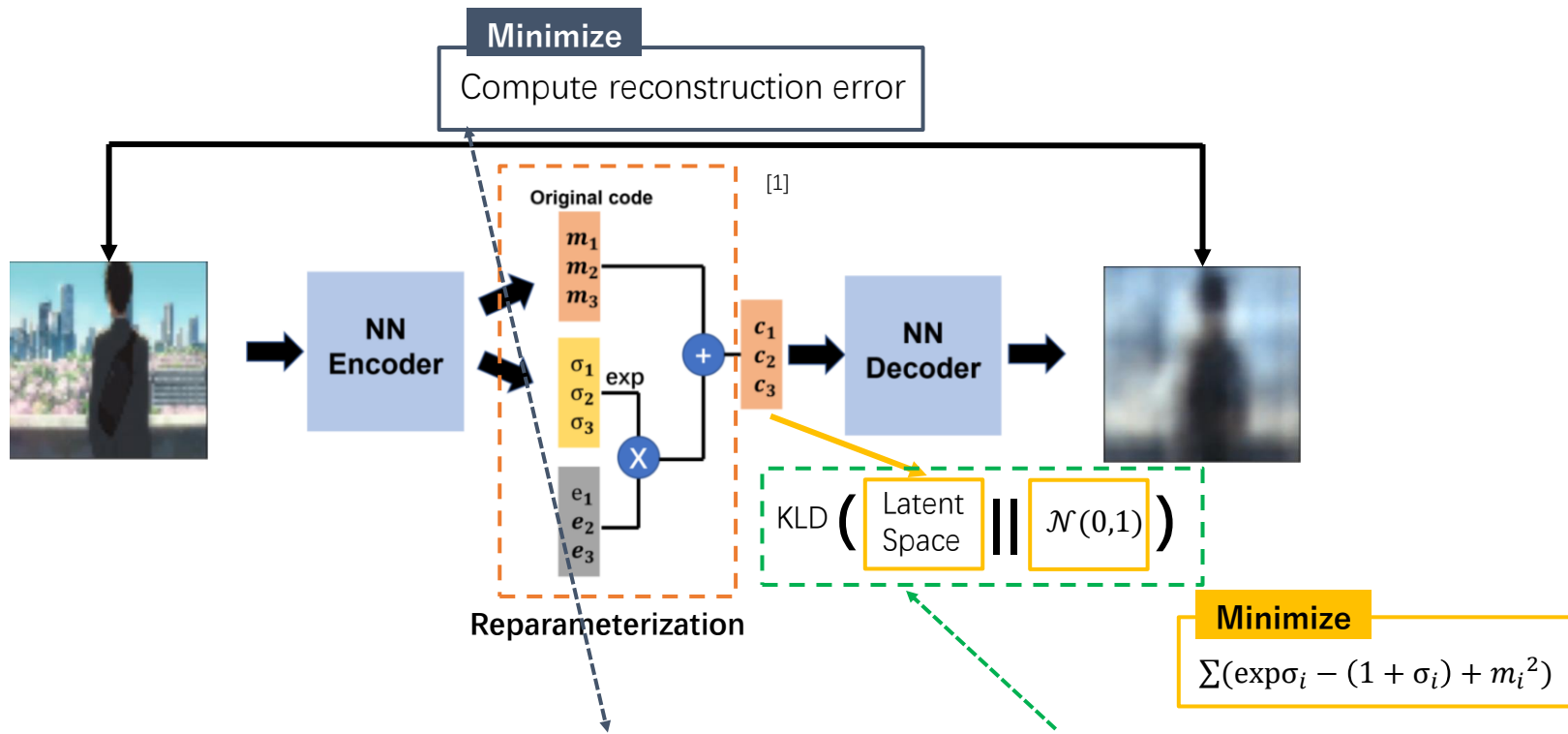


Can hardly learn a continuous latent space if we directly learn the code (c_i) here.

But how about we introduce the distribution idea to the latent space, like making the space follow one distribution, so that it can be continuous?

VAE



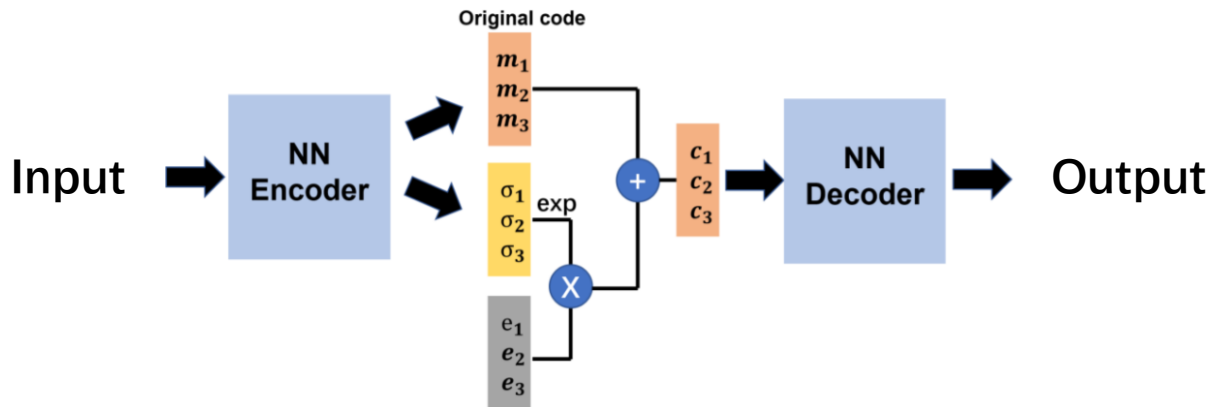


Loss Function: ^[2] $\mathcal{L}(\theta, \phi; x, z, \beta) = \mathbb{E}_{q_\phi(z|x)}[\log p_\theta(x|z)] - \mathbb{D}(q_\phi(z|x) || p(z))$

Reference:

[1] Hung-yi Lee's lecture <https://www.youtube.com/watch?v=0CKeqXI5IY0&t=1650s>

[2] Higgins, Irina, et al. "beta-vae: Learning basic visual concepts with a constrained variational framework." (2016).



Hope to learn the probability distribution of output

Gaussian Mixture Model

$$P(x) = \sum_m P(m) * P(x|m)$$

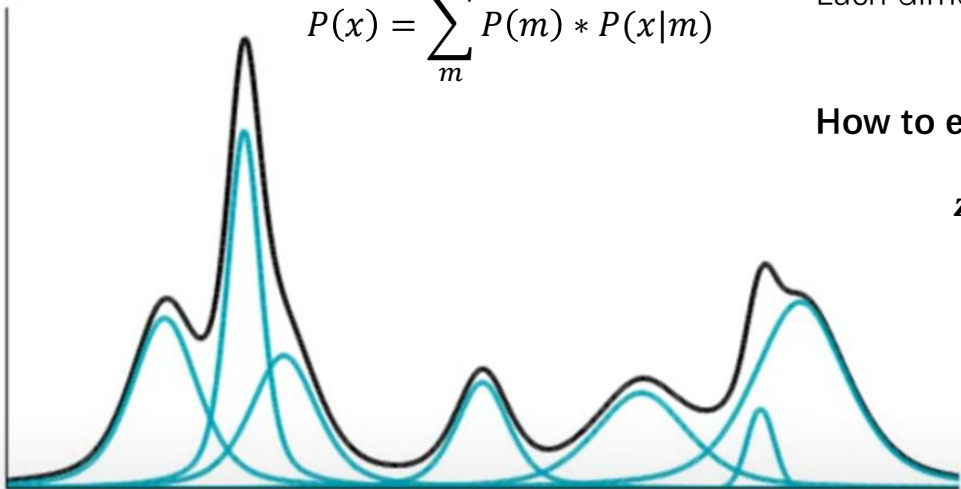
$z \sim N(0, I)$ z is a vector from normal distribution
 Each dimension of Z represents an attribute
 $x|z \sim N(\mu(z), \sigma(z))$

How to estimate $\mu(z), \sigma(z)$?



$$P(x) = \int_z P(z) * P(x|z) dz$$

$P(x)$

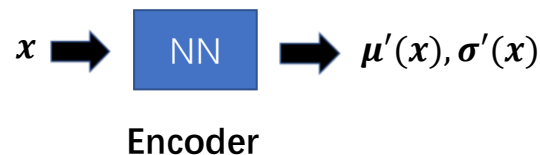
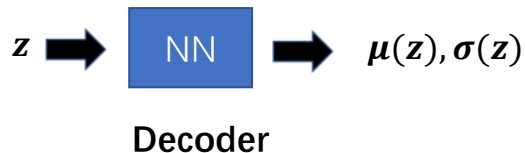


$$P(x) = \int_z P(z) * P(x|z) dz$$

Tune the NN parameters to max likelihood of the observed x: $L = \sum_x \log P(x)$

Another distribution $q(z|x)$:

$$z|x \sim N(\mu'(x), \sigma'(x))$$



$$\log P(x) = \int_z q(z|x) \log P(x) dz \quad \text{s.t.} \quad \int_z q(z|x) dz = 1 \quad \text{and } q \text{ can be any distribution}$$

$$= \int_z q(z|x) \log \frac{P(z, x)}{P(z|x)} dz = \int_z q(z|x) \log \left(\frac{P(z, x)}{q(z|x)} * \frac{q(z|x)}{P(z|x)} \right) dz$$

$$= \int_z q(z|x) \log \frac{P(z, x)}{q(z|x)} dz + \int_z q(z|x) \log \frac{q(z|x)}{P(z|x)} dz$$

$$\geq \int_z q(z|x) \log \frac{P(z, x)}{q(z|x)} dz \quad \text{Evidence Lower Bound (ELBO) } L_b$$

$$* KLD(p||q) = \sum p * \log \frac{p}{q}$$

$$KLD(q(z|x)||P(z|x)) \geq 0$$

$$\log P(x) = L_b + KLD(q(z|x)||P(z|x))$$

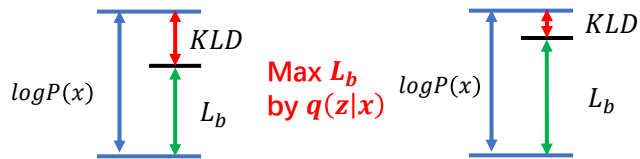
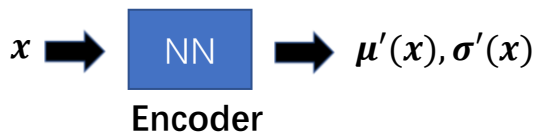
$\sim N(0,1)$

$$L_b = \int_z q(z|x) \log \frac{P(z, x)}{q(z|x)} dz = \int_z q(z|x) \log \frac{P(x|z) * P(z)}{q(z|x)} dz$$

$$= \int_z q(z|x) \log \frac{P(z)}{q(z|x)} dz + \int_z q(z|x) \log P(x|z) dz$$

$$= -KLD(q(z|x)||P(z)) + \int_z q(z|x) \log P(x|z) dz$$

$$z|x \sim N(\mu'(x), \sigma'(x))$$



Find $q(z|x)$ and $P(x|z)$ to $\max L_b$

1. Minimize $KLD(q(z|x)||P(z))$:

Minimize

$$\sum(\exp \sigma_i - (1 + \sigma_i) + m_i^2)$$

2. Maximize $\int_z q(z|x) \log P(x|z) dz$
 $= E_{q(z|x)}[\log P(x|z)]$

Minimize

Compute reconstruction error

